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# RLC-DSP404 Repeater, Link and Remote Base Controller

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Link Communications, Inc. 1035 Cerise Rd Billings, MT 59101-7378 (406) 245-5002 Voice (406) 245-4889 Fax

http://www.link-comm.com

#### Introduction:

The RLC-DSP404 is a powerful tool for controlling radio systems. It features include:

<u>Four radio ports (with planned expansion options to provide a total of 8 or 12 radio ports)</u>, each of

- \_\_ which can be interfaced to a repeater, link or remote base <u>radio</u>.
  - -Commands can be entered from any receiver, the reverse autopatch, or a computer.
  - -Separate DTMF decoders for each receiver input and the autopatch.
- -Voice synthesizer with 680+ word library speaks ID and alarm messages and provides feedback while

while configuring the controller.

- -Nearly all command codes, timer values, and messages are programmable.
- -Each message can contain combinations of Morse code characters, synthesized speech words, sound

effects, DVR tracks, etc.

- -Hundreds of macros allow for the creation or custom commands.
- -Real time clock/calendar chip allows the controller to speak the time or date and to execute macros at
  - <u>at</u> scheduled times.
- -Autopatch with 501 programmable autodial numbers, cover tone, semi-private mode and a variety of

voice response options (kerchunk to dial, etc).

- -Reverse autopatch with over-the-air ringing, directed callout, or full control of the system.
- -Support for frequency control of a variety of HF and VHF/UHF radios for remote bases.

Built-in DVR can store messages in memory (temporarily) or permanently on a (user supplied)
USB

flash drive or SD flash (check compatibility list for supported cards).

- -Extensive security system prevents unauthorized changes.
- 8 (16 with expansion board) analog voltage inputs
- 8 (16 with expansion board) logic inputs
- 8 (16 with expansion board) open collector output drivers.
- -I/O alarms can send alarm messages or trigger other actions when conditions change.
- -Beaconing system can repeat alarm messages over the air or call phone numbers until an alarm is

acknowledged.

Chapter 1 of this manual contains the information you will need to interface it with your radios. The

RLC-DSP404 default settings will allow you to get on the air quickly; setting your ID message may be

all you need to do. Almost every feature can be customized if you wish; Chapters 2 though 20

organized by feature so you can quickly find the information you need. There are several appendices-

with

information you will probably refer to often. Near the beginning of this manual you will find a "Table Of"

\_Contents" organized by topic and a "Command List By Number" that lists all of the setup-commands in

numeric order, along with the pages on which more information can be found.

Nearly every feature of the controller can be configured using a radio with a DTMF pad (a 16-key pad,

with 'A', 'B', 'C' and 'D', is helpful for some commands) or with a computer or serial terminal. Using a

computer can save you a lot of time in the long run, as you can save a file with all of the commands used

to set up the DSP4 and make future changes by modifying that file, then uploading the settings to the

controller again. For more information about using a computer with the DSP4, see Appendix F.

If you have questions the manual doesn't answer, there are a variety of ways to get help:

Through the Internet:

-FAQs (Frequently Asked Questions): FAQs and their answers can be found at http://www.link-comm.com/faqs.html.

-User's Groups. You can ask questions and exchange information with other users (and us) by

email by joining one of these groups.

-Email Us: You can get support for any of our products by emailing support@link-comm.com.

-Support Web Page: Links to the above support options and more can be found at http://www.link-comm.com/support.html.

By Phone:

(406) 245-5002 (406) 245-4889 fax

By Mail

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Billings, MT 59101-7378

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### Limited Warranty

#### **COVERAGE:**

Link Communications, Inc. warrants that its products will be free from defects in materials and workmanship for a period of one year from the date of shipment. During this time, Link Communications, Inc. will cover parts, labor and return shipping. If failure is caused by instances other

than manufacturing defects, Link Communications, Inc. will repair the product and bill the customer for

parts and labor. Contact Link Communications, Inc. for more information.

What Link Communications, Inc. will not cover:

- 1. Too much voltage to the controller. The RLC-DSP404 operates at +11V to +15V, negative ground.
- 2. Damage to the controller by lightning, accident, or incorrect power hook-up.
- 3. Incorrect unit installation.
- 4. Damage caused by shipment (damage claims are handled by the carrier).
- 6. Repairs by other than Link Communications, Inc.

### THIS WARRANTY HOLDS ONLY TO THE ORIGINAL PURCHASER

### HOW TO GET SERVICE

Please contact Link Communications, Inc. for servicing information and authorization.

### **SOFTWARE**

Link Communications, Inc. holds the copyright on the RLC-DSP404's software and hardware. Changes

to the software, copying of the software, and use of the voice code is prohibited without the written

consent of Link Communications, Inc.

### **SOFTWARE UPDATES**

Link Communications, Inc. will provide FREE Software updates for 6 months from the date of purchase.

<u>SThe cost of further software updates</u> will be determined at the release of the update. <u>Manual inserts Updated manuals</u>

and shipping are additional.

### **Return Policy**

These policies supersede policies appearing on all other Link Communications, Inc. literature and are in

effect for purchases made after March 1, 1989.

- Please keep all packing material and documentation in the event that your equipment has to be serviced or returned.
- $-\underline{\underline{\dot{u}}}$  Before returning any product, you must obtain a Return Authorization (RMA) number. You can

obtain this by calling (406) 245-5002.

- -<u>u</u> No returns, of any type, will be accepted without an RMA number. Please have the following information on hand when calling for an RMA number: customer name, invoice number, serial number, and the nature of the problem. All can be found on your invoice.
- -<u>u</u> All product to be returned must be returned within 30 days from the invoice date, 100% complete, and must include manuals, parts bags, and other accessories provided by the manufacturer.
- -<u>u</u> All defective products will be accepted directly by Link Communications, Inc. for credit, exchange, replacement, or repair at Link Communications, Inc.'s discretion. After 30 days from

invoice date, the manufacturer's warranty applies.

-<u>u</u> All non-defective returns for credit, exchange, or refund are subject to a restocking fee on the schedule listed below. No returns will be accepted beyond the 30 day period. Shipping costs are

not refundable.

11 to 20 days 10% restocking 11 to 20 days 10% restocking 15% restocking 15% restocking

Link Communications, Inc. reserves the right to authorize product returns beyond 30 days from date of invoice. If the product is accepted after 30 days, credit will be issued toward FUTURE PURCHASE ONLY.

If you have any questions JUST ASK.

All of us have tried to make sure that this order has been shipped correctly. If we have made an error -

we want to make it right. If you have a question or problem with this order, just write or call, and our

staff will personally handle your situation.

### User Survey (Optional)

A knowledge of the user base will allow us to better serve you in the future by helping us develop more
specialized software and hardware. Please take a few minutes and fill out this questionnaire.
RLC-DSP404 Serial Number
RLC-DSP404 Purchase Date
Application: (Circle All That Apply)
Ownership:
- 1 - Privately Owned Repeater
- 2 - Club Owned Repeater
- 3 - Group Owned Repeater
- 4 - Commercial Business Repeater
- 5 - Other
Installation:
- 1 - Wide Coverage Repeater with Chain Links
- Port to Port Linking
- 2 - Full Duplex Links
- 3 - Half Duplex Links
- 4 - VHF Repeater: Power Make
- 5 - UHF Repeater: Power Make
- 6 - Link Ports Used as Repeater Ports: Yes No
- 7 - Serial Data Used to Control Repeater: Yes No
- 8 - Other Amateur Repeaters At the Site: Yes No
- 9 - Other Link Communication Inc. Products Used: Yes No
N.C.
Misc:
- 1 - User Base: Technical Rag Chew Personal
/ ΛΙΙΙΟΝΌΙΙΟΝ ΠΕΘΟΙΑΝΉ ΤΗΟ ΝΙΕΤΟΜΙ' V ΔΕΙΝΙΟ

- 2 Autopatch used on the System: Yes No
- 3 Frequency Adjustable Remotes: Yes No
- 4 Linking to Other Repeaters: Yes No
- 5 Linking Closed Access: Yes No
- 6 PL Required on Main Repeater: Yes No Varies
- 7 PL Required on Linking System: Yes No Varies

### Please Return to:

Link Communications, Inc. 1035 Cerise Rd Billings, MT 59101-7378

### Comments:

### Chapter 1: Getting Started

Welcome to the powerful RLC-DSP404 advanced DSP based communications controller. The DSP404

supports up to 12 full-duplex radio ports, 16 inputs, 16 analogs and 16 output channels in a small 1U

(1.750") enclosure.

This section will cover the basic mechanical and port locations, radio port DB-9 connector pinouts and

the DB-25 I/O connector pinouts. Initial port configuration switches will be explained and detailed.

Following the hardware mechanical descriptions a complete discussion on the programming and operation of the included Windows(TM) Remote Control Interface (RCI) software. Once section 1 has

been read, the DSP-404 can be setup and operated. In most cases, the rest of the manual is used for

reference only and not necessary for day to day operations of the system.

**RLC-DSP404 Port Locations** 

### RLC-DSP404 Radio Port

The DB-9 used on the DSP404 will accept any Link Communications controller based cable, but for

extended operations you many need to make a few changes. The DSP404's input and output characteristics are different (in a good way), expanding the flexibility of the types of signals the controller

\_can accept without external changes.

Front View of the DB-9 on the DSP-404

Pin
Default Function
Alternate Function
Default Switch Setting

1

### Ground RS-232 Transmit Data 6 position Switch 1 - Off, Switch 2 - On

2 CTCSS Detect CTCSS/DCS Output 10 position Switch 8 - Off, Switch 9 -On

> 3 PTT Out

....

4 Audio Out

....

5 Audio In

.....

6
Ground
RS-232 Receive Data
6 position Switch 3 - Off, Switch 4 - On

7 COR Detect

.....

8
Ground
+5 Volt Output

### 6 position Switch 5 - Off, Switch 6 - On

9 Ground .....

You will notice that several pins have different functions depending on the switch settings. This enables a

<u>a</u> 9 pin connector to be used in varying applications without requiring a larger connector. In most

### instances

\_you will leave the switch settings in their default position. A complete list of switch settingvariables is

\_provided below. It is a good idea to decide ahead of time what setting positions you need-because you

will need to open the case to access them. When the 12 port expansion card is installed youwill need to

— remove that piece to access the lower boards switch settings.

There are two switches per port. The six position switch is for RS-232 serial and power selection. The

ten position switch configures receiver and transmit setup functions

Switch Default Function

> 1 Off

DB-9 Pin 1 Function: RS-232 Transmit Data Output

2 On DB-9 Pin 1 Function: Ground

> 3 Off

DB-9 Pin 6 Function: RS-232 Receive Data Input

4 On DB-9 Pin 6 Function: Ground

5 Off DB-9 Pin 8 Function: +5V Power Available (For smart cables)

> 6 On DB-9 Pin 8 Function: Ground

Six Position Switch Functions

Switch Default Function

On
COR Input Pull-Up (47.5K ohm) to +3.3V

2 Off COR Pull-Down (47.5K ohm) to Ground

3 On CTCSS Input Pull-Up (47.5K ohm) to +3.3V

4 Off CTCSS Pull-Down (47.5K ohm) to Ground

5 Off Receiver Audio Input De-Emphasis filter, -6dB/octave 6 On Transmit Audio Output Pre-Emphasis filter bypass, +6dB/octave 7 Off Transmit Audio Output Gain Range (x3.33) Higher gain when Off 8 Off DB-9 Pin 2 is a Tone Output from DAC 2 9 On DB-9 Pin 2 is the CTCSS detect input 10 On Receive Input Range Select (ö2.333) Higher gain when Off Ten Position Switch Functions

The DB-25 used on the DSP404 will accept any Link Communications RLC-3 based cable. The I/O

portion of the DSB-404 will now accept without any switch changes, analog inputs from 0 to 15 volts.

Any input voltages above +15V must be externally resistively divided to keep from over voltage on the

analog system. The digital inputs can handle a maximum of 60V inputs. The output lines can handle a

maximum of 100mA sinking current.

\_\_RLC-DSP404 I/O Port

Pinout

When attaching an externally powered temperature sensor, like the National Semiconductor LM335Z, a

switch is provided that powers the sensor. This switch is an 8 position where each switch number

corresponds to an analog input line.

Front View of the DB-25 on the DSP-404

The connector is dived into three distinct areas; Analog, Inputs and Outputs. There are 25 pins and 24

signals with one ground reference. The ground reference is at the same potential as the DSP404's (-)

power terminal.

When attaching an analog input that is greater than +15V an external series resistor is necessary to act as

a voltage divider. The input resistance of the analog input is 120K ohms. A series 100K resistor is part

of the input circuit and a 20K resistor provides the necessary voltage divider to bring 15V maximum

down to +2.5V which is the rail of the 12 bit Analog to Digital Converter (ADC).

 $Vo = Vi (Rg/(Ri+Rg): Vo = 2.5V, Rg = 100K, Ri = 20K and Vi = 15V so...select Ri based on your Vi_to^-$ 

keep from exceeding +2.5V at Vo. So 25Vi, Ri would be 180K (100K already there), so add a series

80K to handle a 25V input.

To test the 80K plug it back into the above formula.

Vo = 25V(20K/180K+20K) ... Vo = 2.5V which works.

If an 80K resistor is not available, choose the next larger value and then refer to Chapter 12 concerning

your calibration and offset options that can be programmed to each analog input to address the analog

input differences.

Pin

**Functions** 

Pin

**Functions** 

**Ground Reference** 

14

Ground on I/O Board #1 : Analog 8 on I/ Board #2

2

Analog 7

15

Analog 6

3

Analog 5

16

Analog 4

Analog 3

17

Analog 2

5

Analog 1

18

Input 8

6 Input 7

19

Input 6

7

Input 5

20

Input 4

8 Input 3

21

Input 2

9

Input 1

22

Output 8

10 Output 7

23 Output 6

11

Output 5

24

Output 4

12

Output 3

25

Output 2

13

Output 1

Switch Function Switch Function

Analog #1 Power 5 Analog #5 Power

2 Analog #2 Power 6 Analog #6 Power

3
Analog #3 Power
7
Analog #7 Power
4
Analog #4 Power
8
Analog #8 Power (No function on I/O Board #1)
DB-25 pinout and Analog Power Switches

RLC-DSP404 Power Input

The RLC-DSP404 utilizes an Anderson Power Pole(TM) power connector as the primary power system.

All other Link controllers utilize a 2.5mm power connector but the style was changed to a latching-

power

connector to address concerns with unplugging that could occur with the 2.5mm connector. There is,

however, a 2.5mm power connector pattern on the PC board. A connector can be purchased to-fill this

\_pattern if desired.

Power Pole Polarities: Red is (+)...

### Connecting a computer to the DSP404

Even if you plan to connect to the DSP404 using an Ethernet network (such as a LAN or Internet connection), you should first connect using a serial port.

### Connecting RCI Using the Serial Port

First you will need to install RCI, the Remote Control Interface software for the DSP404, on a computer

running Windows 2000, XP or Vista. If you don't have a copy or you want to download an updated

copy, you can get it from the web site http://www.link-comm.com/ftp/dsp4/dsp4\_rci/newest/-look for

the file DSP4RCI\_Installer.exe. Connect a serial cable between a COM port on your computer and the

serial port on the front of the DSP404 (next to the USB connector).

Start RCI and click on the "Settings" button. Select a "serial" connection and specify your computer's

COM port. If you have everything set correctly, it should connect, at which time the "Connection Status" window will disappear. You can also try pressing the "Reconnect" button to make it try again.

If you have trouble getting it to connect, try another COM port (if you have one), or continue to the next

step - it may help in determining the problem.

Using the serial port to set the network access password

If you plan on connecting the DSP404 to an Ethernet network, you will need to set a network access

password (it defaults disabled). This can currently be done only through a serial port connection, as

described below. This same process can be helpful for troubleshooting if you are having trouble getting

RCI to connect through the serial port.

Make sure that you have a serial cable connected between your computer and the DSP404 as described

above. Then you will need a serial communications program like HyperTerminal or Putty.

- -HyperTerminal comes with Windows 95 and later, but may not be installed by default. If it is installed, you may be able to find it by clicking on Start > Programs > Accessories > Communications > Hyperterminal.
- -Putty is a communications program that can be downloaded for free from http://www.chiark.greenend.org.uk/~sgtatham/putty/download.html. Look for the file

putty-0.60-installer.exe, or whatever the latest release version is.

Whichever program you choose, set it up for 115200 baud with no handshaking and the COM port used

by your computer. Turn on power to the DSP404. You should see several screens of messages scroll by.

Pressing Enter will provide you with a root:~> prompt. Type "passwd" in lower case to set the password.

passwd

... and enter a password as prompted. This password will be required to access the DSP404 over the

network. It can only be changed through the serial port by repeating the above process if you ever forget

it. When starting RCI, under Connection Settings you can enter this password for network access.

The password IS NOT ECHOED back to you when entering it. This is for your security. If you do not

see the information you typed, that is correct. The password will also need to be verified by retyping it.

Once the DSP404 accepts the password you can now access the unit from the computer via the network.

When accessing the DSP404 from the serial port, not password is required.

If you don't see any serial output, check the above, or look for more hints on the web page http://link-comm.com/wiki/index.php?title=Serial\_Port\_Troubleshooting.

Type "client" from the root:~> prompt to access the "DSP4>" prompt

Setting the DSP404's Network Addresses Automatically

If the DSP404 is plugged into an existing Ethernet network that has a router, it will by default try to

obtain an IP address and other network settings from the router (using the DHCP protocol). You can

view the settings by connecting to the serial port with HyperTerminal or Putty as described above, then

entering the following command (shown in bold):

root:~> ifconfig eth0

eth0 Link encap:Ethernet HWaddr 00:18:8D:00:00:37

inet addr:192.168.25.81 Bcast:192.168.25.255 Mask:255.255.255.0

UP BROADCAST NOTRAILERS RUNNING MULTICAST MTU:1500 Metric:1

RX packets:275 errors:0 dropped:0 overruns:0 frame:0

TX packets:6 errors:0 dropped:0 overruns:0 carrier:0

collisions:0 txqueuelen:1000

The most important piece of information displayed is the IP address, shown above in italics. If the

DSP404 was unable to obtain an IP address automatically, you will see something like the following

instead:

root:~> ifconfig eth0

eth0 Link encap:Ethernet HWaddr 00:00:00:00:24:00

UP BROADCAST NOTRAILERS RUNNING MULTICAST MTU:1500 Metric:1

RX packets:0 errors:0 dropped:0 overruns:0 frame:0

TX packets:5 errors:0 dropped:0 overruns:0 carrier:0

collisions:0 txqueuelen:1000

If your network has a router, it is generally much better to try to let it set the address automatically. If it

does not have a router (such as if you are using a crossover cable or simple hub/switch between your

computer and the DSP404), you will need to set the IP address manually.

Setting the DSP404's Network Addresses Manually

If you are running HyperTerminal or Putty, exit it and start RCI again. Wait until it connects (using the

serial connection, as described above), then go to the TCB Settings menu and select "Network Settings".

Make sure "Enable Network" is selected, and deselect "Use DHCP" (so you can enter the settings manually).

It can be complicated to figure out what network settings to use, but typically you can use one of the

computers that is already on the network as an example. From a Windows computer, click Start > Run >

and type "cmd" then press ENTER. You should get a command prompt. Type "ipconfig" at that prompt, as shown below:

C:\Documents and Settings\steve.strobel>ipconfig

Windows IP Configuration

# Ethernet adapter Local Area Connection:

Connection-specific DNS Suffix :: IP Address. . . . . . : 192.168.0.21 Subnet Mask . . . . : 255.255.255.0 Default Gateway . . . . : 192.168.0.1

If you get more information than shown above, look for the section with the title "Local Area Connection". You can often choose an IP address for the DSP404 that is one greater than the IP address

of your computer, which would be 192.168.0.22 in this case. Just to be sure, try to "ping" that address

from your computer:

C:\Documents and Settings\steve.strobel>ping 192.168.0.22

Pinging 192.168.0.22 with 32 bytes of data:

Reply from 192.168.0.22: bytes=32 time<1ms TTL=128

If you get a reply as shown above, do not use that address; it is already in use by another device. Instead,

you want to find an unused address, which will make ping respond like this:

C:\Documents and Settings\steve.strobel>ping 192.168.0.22

Pinging 192.168.0.22 with 32 bytes of data:

Request timed out.

You can the use RCI to enter that IP address for the DSP404 to use. Use the same subnet mask and

default gateway as your PC. After entering those settings, use RCI's File > Reset Controller option to

make the DSP404 save those settings and restart (so it can use the new network settings).

Testing the network settings

After the DSP404 restarts and loads the new network settings, you can try to "ping" it from your computer using the IP address you set for the DSP404. It should reply, as shown above. If it does, you

can try making RCI connect to it via the network rather than serial connection. To do that go to the

"Communications" menu and select "Communications Settings". Select a connection type of "Telnet",

enter the IP address of the DSP404, and the password you set up previously. Click on "Reconnect" and

it should connect within a few seconds. If it does not, try clicking on the "Reconnect" button again. If

that doesn't work, try "pinging" it again, and check your settings.

# -Windows(TM) Remote Control Interface (RCI)

The RLC-DSP404 comes with a very flexible GUI interface that enables most aspects of the DSP404 to

be setup either using an RS-232 serial port or utilizing an Ethernet port. Only the Ethernet port enables

the Voice Over Internet Protocol (VoIP) features, but either method works well for programming and

operation. Ethernet programming has the added feature which enables up to four computers accessing at

the same time, all with VoIP.

RCI cannot operate at this time without a controller hooked up to or connected to. All variables are

stored on the controller and none on the computer. This feature keeps computer issues from affecting-

the

\_controller's settings if a computer crashes or is not available. If this occurs then download a new

version

of RCI on any computer and connect to the controller and all of your settings are still there.

Windows(TM) Remote Control Interface (RCI)
<del></del>
<del></del>
<del></del>
The operational console
for RCI. If you get to this
screen your computer is- communicating with the
_controller unit, and will indicate a good connection by the Remote Connection-
message. In this case,
Telnet 2 (out of four possible connections). If you were connected using the RS-232RS-
232 serial port, the
connection dialog on the bottom of the screen would identify Serial as the connection
type.

Port Setup from RCI

The easiest way to get to know your DSP404 is with the RCI GUI interface software. For the setup

discussion I will exclusively be using RCI and not the DTMF commands. The DTMF

commands are covered later in the manual and can be referenced if need-be.

Accessing setup is accomplished by clicking your Right mouse button when the pointer is over the Port or Group you wish to configure.

Right Click over the requested Port

# Port Setup Screen

After right clicking the mouse over a port the Port Setup Screen will appear. This screen enables access

to features and variable for the selected port. In an effort to minimize the amount of clicking required.

aport selection box is located to the left of the "Done" button. This enables an easy method of

selecting different ports without the need to exit setup and select a different port.

The initial setup screen enables the user to select a Radio Personality. Personalities contain only stuff-

that

is specific to the make and model of the radio, not how it is used. A ports ID's and Courtesy Beeps are

-are not stored because they are not radio specific.

Some default radio personalities are included for a Repeater, Simplex Link and Duplex Link. To select a personality, select the required personality and press Done. Now all the settings stored in the personality will be recalled.

If a personality does not contain all the exact settings you wish, you can recall a setting and make your own changes.

If you want to use those changed setting on more than one port, you can save them to a User Defined Personality, then select that personality on the other ports.

Because every radio is unique, unique settings are necessary to have the radio setup correctly.

A user slot is handy because it is a good place to start when connecting a radio to the system.

The next setup tab allows the port's displayed Radio Name to be shown on the Port button. The name is limited to 9 characters and shows up on the selected port button.

The Radio Description section is used for a description only and is not displayed. It is currently limited to 100 characters and could be used as a basic log for a port's additions, changes and maintenance.

The next tab is the Radio Type tab that

controls the radio type connected to a port.

Link / Remote Base: This identifies that the

radio attached to the port is not functioning

as a repeater but as either a half-duplex

(simplex) radio or a full-duplex base radio.

Repeater: This identifies that the radio

connected to the port is operating as a

repeater with its COR looped to the PTT on

the same port.

Half Duplex Timer: This timer is only-

active

when a radio is in Half Duplex mode,

and is

\_triggered when the PTT for the port-

goes

\_from active to inactive. Some radios-

#### COR

will bounce when coming out of PTT,-

and

\_will cause an unnecessary courtesy beep or

<u>or</u> other PTT's on connected ports. If your radio has this problem, set the Half Duplex timer to a value-

that

\_will suppress the COR hick-up.

Audio Delay: This timer provides delayed receiver audio from 0 seconds up to 5 seconds per port. The

timer defaults to 0 seconds and is programmable in 1 millisecond steps.

Link Type: This defines if the connected radio is either a Half Duplex (single antenna port with-combined

\_receiver and transmitter inside one package) or Full Duplex (two antenna ports with separate-receiver and

\_separate transmitters in one or two packages).

Radio Channel Control: This setting identifies the function of the connected radio. A Not Controllable

radio is a typical radio without the controllers ability to frequency steer the radio. If steerable radios are

connected, such as the Tait 8115, 9115 series radios, then select the Tait radio in the options box. When

a steerable radio is selected for a port, the right hand 1/3 of the main screen changes to indicate a controllable radio is available. Otherwise this selection keeps that part of the screen unavailable. The

default setting is Not Controllable.

The next tab to examine is the RX Activity

Tab. This tab control the receiver access

conditions for the port.

COR: Carrier Operated Receiver (Relay for

the old timers...) Indicates that activity on

DB-9 pin 7 must go either high or low to

identify an active receiver. The default

condition is active low.

CTCSS: Continuous Tone Coded Squelch

System access is connected to pin 2 of the

DB-9 connector. It receives activity from an

external analog or digital tone decoder, or

other source, as an alternate access method

other than COR.

VOX: Voice Operated Transmitter is a method of accessing the controller with only the presence of

voice. If a connected radio does not have a COR or CTCSS output and you wish to use it (sell it and get

a radio with a COR or CTCSS line...), VOX must be used. In a repeater environment, it is best to use a

radio with a hardware line and not VOX, but otherwise select VOX. When the voice is detected the

controller will indicate an active receiver condition. Because VOX operated on voice, you will need to

select a response time (typically Medium) to delay going from active to inactive between someone's

words. If the average person using your system talks...really...slow... then you will need to set the VOX

response to slow. The response is a voice activated hang timer, therefore when the person stops speaking, the controller will wait a period of time to make sure they are really no longer speaking.

VOX Threshold: This setting it the VOX trigger point where the controller treats incoming audio as

either active or inactive. The lower the number the quieter the input audio to be detected. A setting of

50 works well with most audio sources.

When a line is set to be Low going indicates that the receiver must pull the line to ground for it to be

recognized. Depending on the switch settings, the line can be released to an open (if the pull-up switch-

is

on), be at a voltage and release the line when active (if the pull-down switch is on), or provide avoltage

to the line and a ground when active (if both pull-up and pull-down switches are off).

When a line is set to be High going, it operates opposite from the Low going line. So a receiver provides

a voltage when active. Every receiver is different so between the switch settings and the Low/High

selections, most receivers can be interfaced without issue. The COR and CTCSS lines are connected to

an insulated gate FET which provides an extremely high input impedance to the connected receiver-

when

the switches are both off. The switches provide either a pull-up or pull-down with a load of 47.5K-

ohms

each. Refer to the switch settings at the beginning of this chapter for proper settings for pull-ups

and

\_downs on the COR or CTCSS lines.\_

The next tab controls the Audio Levels for the

receiver, transmitter and tone system.

Transmit Level has 255 discrete adjustment

steps (in 3/8dB/step) and is displayed as a 0 to

255 steps. Future software releases will add a

fine level adjustment to span digitally the 1 step,

steps. Mic and Line level selections are only

available for the Tactical Communication-Bridge (TCB) units. TX Tone Level adjustment sets the level of the transmitted tones and is mixed with all other receivers audio. The tone level is a 0 to 100% adjustment. Receiver Level adjustment adjusts the level of the incoming receiver audio that is presented to the 24 bit CODEC. Enable Automatic Gain Control sets tells the controller to automatically adjust the units receiver level to a point where the controller's CODEC performs the best. This feature is useful when a varietypeople use a system, with different levels of spoken audio. AGC is currently available on the TCBline of units and is planned for the DSP-404. The next tab allows programming of a ports Identification Requirementslike \_the CW Call Sign and the Voice—ID <u>ID</u> used. All ID slots are programmed with the Voice ID entered from this form.

When a user sets up the ID's, currently only two ID's are setup directly with the GUI, the CW and a Voice ID for the selected port.

Access to other ports ID slots is accomplished by pressing the Advanced button. A list of the other ports available ID's will be listed and using the Macro Editor can easily add or modify the ID's.

The next tab enables the recalling and programming of a ports Courtesy Beep information. The user can recall default beeps (that are used on the RLC-Club and RLC-3 controllers), or program a Custom beep sequence when the Custom selection is made.

When a preset beep is requested, custom changes can be made to the recalled beeps by pressing the Advanced button which pulls up the macro editorwith \_the contents of the Courtesy Beep macro.

If a preset beep is not desired, and the userwishes

\_to have a Custom Beep, select Custom. -

Up to

\_three custom tone combinations can be programmed here to provide unique beep sounds.

the Preset option and press the Advanced button.

If you need more than three tone sequences, use

This will allow more than three tones to be programmed into the Courtesy Beep macro.

The last tab under a ports setup is are the Port Specific Timers. There are only six timers that can be set under this screen, and these timer are only the timers that directly affect the ports operation.

The format to change and set timers is either with a point and click up or down selection or to directly enter the time with by clicking on the calculator icon.

Up and down clicking increment in 10mS steps, and are displayed in seconds format.

When using the calculator pad, different timer values are available when entering a time. Msec, Sec and Min are available.

Once the timer amount has been calculated press the Enter Bar to accept and continue.

# System Features

Once a port has been setup access to some system features might be necessary in order for the GUI and unit to perform as desired.

Starting with the File drop-down menu there are three available options.

Save Settings (on TCB or RLC) will take the user changes and store them into non-volatile Flash memory. Until the settings are saved, they can be lost with a controller power-down event.

Reset the TCB (or RLC) will cause a power-on reset command to be issued to the controller. This is the same as pressing the Reset button or removing and reapplying power to the unit

Exit will exit RCI

The Communications drop-down allows communications parameters to be accessed and changed.

There are three options that are available for the communications system. Controlling how the unit communicates with RCI, using serial or Telnet, watching the control signals status and accessing a terminal to make custom changes to the unit are supported.

## Communications Settings:

There are two options to connect to the unit. If using Telnet then an IP address and password is required. If using Serial, then a COM port, Baud Rate (115,200 Baud by default and password is necessary.

Note:

On the RS-232 serial port, there is

no password out of initializations.

One must be entered if desired. On the Network port a password

MUST be entered before the

network port will function.

When RCI first starts, the Communications Status screen will display. This screen shows 15 discrete steps that effect the connection, updating and saving on the controller. If the controller is connected, the Connected line will be highlighted.

The communications settings will keep the system

from connecting and when this occurs, the

communications status screen will display. If your

system is having connection problems, check the

Communications Setup screen of press the-

Settings

\_button.

Make a change then press the Reconnect button.

If all else fails when working with a network, try

the serial port.

If contacting technical support, note the point from the Status screen where the communications failed.

The Terminal Screen enables the user to watch and enter commands

To use the Terminal as a standard terminal ensure the "Verbose" selection is not checked under the view menu.

To watch RCI's communications to from RCI to the controller check the "Verbose" selection. This will

unhide the background communications that is happening. All other features are self explanatory and

can be played with without effecting the controllers operation.

Console drop-down menu accesses settings that affect RCI's console screen. The Console screen is the displayed screen on computers running RCI. The VoIP from the controller must go somewhere for the operator of RCI to access.

This screen requires a radio port to utilize and operate from.

The port can be assigned from the Console drop-down menu-

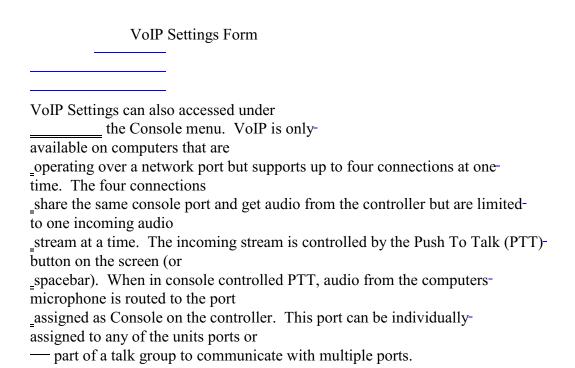
but

\_the port defaults to Port2.

To reassign the console port click the 'On On Port' selection and

assign a port. Only installed ports can be assigned as an RCI

port therefore selection is limited to the non-greyed out ports.



When VoIP is enabled the user must select the method the data is accessed. Two methods are available:

connection over a LAN or Connection through a Firewall. When connecting locally without exiting-

your

LAN, no special configurations are necessary. The VoIP traverses using Port 23000 which will need to

—need to be opened is a firewall is used.

When going through a firewall, RCI can tell you the address it see's by pressing the "Get Public-Address"

\_button. RCI will show you the address that needs to be entered into the firewall address. Youwill still

\_need to open port 23000 for the VoIP data to find the controller, but once connected the systems should

—should talk.

Diagnosing VoIP's Operation: Because of the complex nature of VoIP, a method of easily diagnosing

the operation of the system is necessary. There are several indications that diagnose the

operation of the

digital audio.

The initial method of seeing if a problem exists with the VoIP is with thestreaming

\_message. If the message "Streaming Stopped" is on the screen (bottom-of the

\_VoIP Screen), data is broken between RCI and the unit. None of the-Connection

\_Statistics will fix this problem. This usually occurs when the IP-addresses are

incorrect or a firewall is blocking the VoIP from arriving at RCI. There are no tools built-into RCI that

\_can help in verifying the stream is working. A freeware program is available calledwireShark that is a

\_valuable tool when troubleshooting network connection problems. The software is available at \_\_available at www.wireshark.org/download.html .

Once the stream is working the connection statistics can help determine if your network bandwidth is

good enough for VoIP operation. The controllers RCI socket operates at 128kbps stream (16 bit PCM

\_at-

8KHz) = 128 kbps rate. The broadband nature of the connection is to minimize any audio issues that

\_can-

occur on the VoIP console channel. A lower bandwidth stream is in the development that drops the

bandwidth down to 64kbps G.711 uLaw. Other CODEC's are in the development to drop the bandwidth

even more and will be available in the future.

Once operational, the VoIP audio will follow the clicking on Ports or Groups from RCI. PTT

routes the

computer audio from the microphone to the receiver on the assigned port for VoIP on the controller and

received audio will be routed to the speakers on the computer. The VoIP stream is a full-duplex link

port.

Remember, if you have problems check your network connections.

Up to this point all settings have been RCI based, and not on the controller. The next drop-down is the TCB Settings menu.

The setting of the controllers IP information is accessed from the Network Settings tab. The controller supports both Static IP addresses and DHCP assigned. If you want to use the network check the Enable Network box and select the addressing mode you desire.

(A Talant Password will be assigned bore in order to

(A Telnet Password will be assigned here in order to enable the network. No yet documented...)

If not utilizing the DHCP server you will need to enter the Address, Netmask and Gateway information.

Once completed, press the "Done" button to accept the changes. The controller will need to reboot for

the changes to take place, and all settings will be saved. Once the controller has rebooted the network

will be available.

The next settings tabwindow controls the access level from RCI to the RCI-level security. On this form controller. User andare three columns (Anybody, Users and Administrator) and a Administrator permissions are list of actions that can be assigned for most of the features performed within RCI. An action that RCI can perform. The Administrator permissions can is in the "Anybody" column execute the User permissions does not require a password, but the User permissions can notwhen attempting to perform an action in the "Users" or "Administrator" column, you will be prompted to enter the execute the Administrator respective user or administrator

password. Administrator can
perform the actions in the "Users"
column, but users cannot perform the actions in the "Administrator" column. Actions can be
<u>moved</u>
between columns by selecting them with the mouse and clicking the appropriate arrow button.
permissions
To change the passwords click on
the Change Passwords button.
No passwords are assigned out of initialization, so it is good to assign them here. The RCI assigned
password system ONLY effects the computer these are assigned. The password system was
designed for
dispatch operation where controlled access to the RCI system was necessary. The DSP404 still
maintains
a 1000 user password system as well as the Telnet/SSH password support. In a future release of
software will move these passwords to the controller. The default user password is "user"
and the
default administrator password is "admin"
but it is recommended that you change them
when initially setting up your DSP404. To
change the passwords click on the Change
Passwords button. A form — will appear
where you can enter a new password for
each level. If you forget either password,
you can use command 238 at the terminal to
—reset it.

The next controller based menu is the Macro
Editor. This feature enables the user to
access the macros on the controller and to
create, edit and delete them.

The example to the right has two commands,

032 and 030. Command 032 sends a serial

message out the serial port when executed

and Command 030 sends out a voice ID

message. The contents are stored in macros

320. To add a command simply click the

"Add Line" button and to delete a line in the

macro click the "Delete Line" button. You

\_can cycle to other macros without clicking the

-the Done button.

When finished editing, click the "Done" button to exit.

The next drop-down menu is the Command Editor. This feature allows Command Names to be changed, execution permissions to be assigned and security levels to be assigned. The

command names can be addressed by DTMF Name or Number.

You can cycle to names without clicking the Done button.

When finished editing, click the "Done" button to exit.

# Input and Output Line Control

The DSP404 has support for 16 input lines, 16 output lines and 15 analog 12 bit channels. Access to the telemetry signals is located under the TCB Settings drop-down menu and located under the IO settings tab.

The summary screen shows all lines and the analog lines converted results. Currently the results are text based but a graphical faceplate template is being developed.

Only the output lines can be user functioned (because it is the only output feature) and is changed by double clicking the desired line.

The total system supports 16 of each of the signals, but only 8 of each are installed currently, therefore only 8 of each show.

After double clicking on output

lines 2,3,5 and 7 they change state to Low from High (or open).

Calibrating and assigning unique
settings to the input lines and
analog signals will be
documented at a later date (in

the near future).

Other Misc. Menus and Operations

To manually check for an update for RCI and/or the DSP404 the user simply clicks the Help and the About sub-menu.

The following screen appears which accesses the Link Communications web site where the updates are located.

Once an update available and downloaded, the user can either update immediately (automatically done), or save the update for a later installation time.

When manually updating the

firmware the user clicks the Update

Firmware button which opens My

Documents to load the file.

All RLC and TCB updates end in

the ".elf" designation. This

designation is the Linux and RTMS

file that handles the executable.

Make sure you load the latest

version of firmware as all firmware

versions have the same name. It is

recommended to make a copy of

the downloaded firmware before

transferring it to the controller.

Rename the firmware to a unique

name so you always have a copy

and know what the latest version is.

Clicking "Yes" will download the new update

and ready the system for the new version.

Clicking "No" will cancel updating the new

version.

## Complete Reference Manual

This is the last paragraph in many printed manuals. For many users, this information will be all that is

needed to get the RLC-DSP404 interfaced to radios and programmed using the RCI software. For others

who may wish to find more technical information about advanced capabilities of the controller, the

complete reference manual may be available from the following sources:

A CD-ROM, included with new controllers.

The DSP404 firmware and manuals web page, http://tinyurl.com/a5jnnz or

http://link-comm.com/wiki/index.php?title=RLC-DSP404 Firmware and Manuals

In printed form from Link Communications.

# Chapter 2: Port Connection Commands

This chapter deals with the commands used in connection and control of the radio ports. The areas dealt

with in this chapter are:

-<u>u</u> Radio port connections

Receiver access control

-<u>u</u> COR and PL polarity control

Transmitter PTT control

#### Connected Ports

In this chapter you will often see references to ports being "connected". When two ports are connected.

they hear each other (the COR from each port will activate the PTT on the other, and the audio from

each will be transmitted out the other). All of the radio ports on the controller can work independently,

or they can be connected together in any combination. A typical configuration would be to have

repeater port "connected" to a remote base port. If all of the ports are connected to each other, the

\_whole-

controller works as one unit, with audio received on any of the receivers going out all of the \_transmitters.

## Port Groups

The RLC-DSP4 uses "port groups" (or just "groups") to control which ports are "connected" to each

other. Ports that are in the same group are automatically connected to each other. Multiple groups can

be used to connect different sets of ports together. This is similar in concept to people standing in

various rooms. People in the same room can talk and be heard by others in the same room, but not by

those in different rooms. A port that is not in a group will not be connected to any other ports.

Typically, each port will be a member of only one group at a time. When RCI is used to place a port in a

group, it automatically removes it from any other groups. That is similar to a person walking out of one

room and into another.

Advanced topic: It is possible for a port to be a member of more than one group at a time (command-

017

- \_can be used to set that up). In that case, any signals received by that port will be transmitted tomembers
- of both groups, and it will transmit any signals received by ports in either of the other groups. This is
- similar to a person standing in the doorway between two rooms; he can hear anything spoken ineither
- room and when he speaks, he will be heard by everyone in both rooms. This often causes-confusion.
- Consider the case where the "person in the doorway" (the port that is in more than one-group) has a
- conversation with someone in one of the rooms (groups). The people in the other room canhear the
- \_person in the doorway; but not the responses of the person in the other room; they hear only one

side of

- the conversation. To avoid this, it is often best to either "step into one of the rooms" (join one-group or
- \_the other but not both) or put everyone in the same room (put all of the ports into the same-group).

### Group Sets

It is often useful to change which ports are members of each group, such as to turn a link on or off, or to

set up for a net. This can be done directly each time using command 017, or it can be automated using

"group sets". A group set records which ports are in each group, and allows that set of groups to be

restored at a later time.

To configure a group set, use RCI or command 017 to add some ports to one or more groups.

Those

changes will automatically be made to the currently-selected group set. Then select a different group set

(using command 239 or the selection in the top-left corner of RCI) and configure it differently. To-

return

to the original configuration, just select the original group set.

### Repeater Ports

When a port on the DSP404 is set up to control a repeater rather than a link or remote base, the

receiver

on that port is effectively "connected to" the transmitter on that same port. In other words, anything

received on that port will be transmitted on that port; it "repeats".

To set up a port as a repeater, use RCI to select "repeater" mode in the "Radio Type" tab or use the

shortcut macro "\*16 pp" where "pp" is the port number (example: 02 for port 2). To change a port

configured as a repeater back to a link/remote base port, use "\*15 pp".

Turning a Repeater Off

There is more than one way to turn a repeater off, each of which has advantages and disadvantages. For

this example, we will assume that you have a repeater connected to port 1.

One option is to disable the repeater transmitter. This will keep the transmitter from coming up for any

reason. It will not repeat audio, it will not ID, it will not send any messages that may be caused by the

scheduler (like speaking the time on the hour) or any alarm messages, and if a remote is connected, it-

will

not send the audio from that remote. The receiver will still work normally. You can still use the

receiver

to turn the repeater back on or enter any other commands, and if you have a remote base port-connected

\_to the repeater port, your receiver's audio will still go out the remote. The repeater transmittercan be

\_disabled by entering "155 010".

Another option is to disable the repeater's receiver. In this case, the receiver will not cause any transmitters to key up and no audio that is received by that receiver will be transmitted out the repeater

or

any remotes. The repeater transmitter will continue to work normally. It will still ID (when it needs-

to).

send scheduled and alarm messages, and if a remote is connected, it will still send the audio from-

that

remote. You can disable port 01's receiver by entering "005 010".

You can also choose whether or not to allow commands to be entered when the receiver is disabled with

command 005. Entering " $005\ 0100$ " will make the controller ignore any commands that are entered on

that receiver. This may be useful for keeping someone who is trying to break into your controller from

getting in. It will also keep you from doing anything from that receiver - even turning it back on. If you

set command 005 this way and disable the receiver, you will have to turn the receiver back on from

another receiver on the controller, from the reverse patch, or from the serial port. If you enter "005

0101" instead, the disabled receiver will still not cause any transmitters to key, but you will be able to

enter commands on that receiver. If you enter "005 0110", the repeater will continue to work but it

won't accept any commands, including the command to turn it back on.

The final method for disabling a repeater is to disconnect the repeater port from itself by entering "\*15

pp" as described in the "Repeater Ports" section above. This does not disable either the repeater receiver

(it can still receive commands) or the transmitter (it can still send IDs and scheduled messages), but it

turns off the repeat function so signals received by the repeater receiver will not be transmitted on the

repeater transmitter. This is the best method for most systems.

# 017: Manage Port Membership In Groups

<017> 00 0GG Recall which ports are in group "GG"

<017> A R 0GG PP Change membership of port PP in group GG

<017> A R 0GG PP..QQ Change membership of ports PP..QQ in group GG

#### Parameters:

- -A is one of the following (from port group action enum):
  - -0 add port(s) to group
  - -1 make port(s) monitor group
  - -2 remove port(s) from group
  - -3 toggle port(s) membership in group (if monitoring, leave group)
  - -4 remove port(s) from all groups
- -R is one of the following (from resolve one way enum):
  - -0 if specified port(s) are part of another group, remove them from that group and join the specified one (to avoid one-way conversations)
  - -1 if specified port(s) are part of another group, do not remove them from that group and abort this command (to avoid setting up one-way conversations, won't "fix" existing ones)
  - -2 join the specified group regardless of whether the specified port(s) are part of another group (may cause one-way conversations).

## 210: Recall if Group Contains Port

<210> gggpp Check to see if port 'pp' is in group 'ggg'

#### Parameters:

- 'pp' is the port to search for within the specified group.
- 'ggg' is the port group number to search.

## Examples:

- $-\dot{\mathbf{u}}$  210 105 02 Check to see if group 17 contains port 02.
- $\frac{1}{2}$  210 110 01 Check to see if group 22 contains port 01.

# 239: Manage Group Sets

<239> recall all group sets' descriptions.

<239>0 recall active group set and description

<239> 0 group set set active group set to group 'group set'

<239>1 recall active group set and description

<239> 1 group set set active group set to group 'group set'

# Examples:

- <u>u</u> 239 − recall all group sets' descriptions.
- recall first (active) group set and description.
- -\frac{1}{2} 239 0 1 --- set active group to the first item in the group sets drop-down menu.
  -\frac{1}{2} 239 1 --- recall second group set and description.
- -<u>u</u> 239 1 1 ---- set active group to the second item in the group sets drop-down menu.

## Notes:

<u>ù In firmware versions through at least V4.10, "group set" should be specified as one less than</u>

the intended groupset. For example, to select or recall the settings for groupset 1, use "0" when specifying the group\_set when calling this command. For groupset 5, use "4".

#### 003: Recall Which Transmitters A Receiver Is Connected To

This command allows you to find out which transmitters will send the audio received on the specified

receiver.

<003> pp

**Recall Receiver Connections** 

#### Parameters:

-003 is the default command name. This command finds what transmitters are connected to receiver 'pp'.

-pp is the receiver to recall the connections (to use '0\*' for the current port, see Appendix L)

#### Default:

- Port 1 defaults as a repeater
- Ports 2..12 default to links

## Example:

Receiver 1 is connected to transmitters 2 and 3

<003>01 D or unkey or <Enter>

Response: Voice Response "1 Connect 2 3"

#### 004: Recall Which Receivers Are Connected to a Transmitter

This command allows you to find out which receivers will cause the specified transmitter to key and-

send

\_the received audio.

<004> pp

**Recall Transmitter Connections** 

#### Parameters:

-004 is the default command name. This command finds what receivers are connected to transmitter 'pp'.

-pp is the transmitter to recall the connections to (use '0\*' for the current port, see Appendix L)

#### Default:

- Port 1 defaults as a repeater
- Ports 2..12 default to links

## Example:

Receivers 1 and 2 are connected to transmitter 3

<004> 03 D or unkey or <Enter>

Response: Voice response "3 Connect 1 2"

#### 009: Recall Controller's Entire Audio Crosspoint

This command allows you to check the audio crosspoint conditions on all radio ports on the controller.

This command will check the connected conditions and both show the crosspoint map on the RS-232

serial port, and will speak the conditions out the port that DTMF requested the conditions.

< 009>

#### Parameters:

- 009 is the default command name.

## Voice Response:

The voice response will only speak if a receiver is connected on the selected port. If a receiver is

connected to a port's transmitter, the controller will speak "rr connect tt" where rr and tt are the port

numbers of the receiver and transmitter, respectively.

#### Voice Format:

```
1 Connect <TX1> <TX2> <TX3> <TX4> <TX5> <TX6> <TX7> <TX8> <TX9> <TX10>
<TX11>
<TX12>
2 Connect <TX1> <TX2> <TX3> <TX4> <TX5> <TX6> <TX7> <TX8> <TX9> <TX10>
<TX11>
<TX12>
3 Connect <TX1> <TX2> <TX3> <TX4> <TX5> <TX6> <TX7> <TX8> <TX9> <TX10>
<TX11>
<TX12>
4 Connect <TX1> <TX2> <TX3> <TX4> <TX5> <TX6> <TX7> <TX8> <TX9> <TX10>
<TX11>
<TX12>
5 Connect <TX1> <TX2> <TX3> <TX4> <TX5> <TX6> <TX7> <TX8> <TX9> <TX10>
<TX11>
<TX12>
6 Connect <TX1> <TX2> <TX3> <TX4> <TX5> <TX6> <TX7> <TX8> <TX9> <TX10>
<TX11>
<TX12>
7 Connect <TX1> <TX2> <TX3> <TX4> <TX5> <TX6> <TX7> <TX8> <TX9> <TX10>
<TX11>
<TX12>
```

```
8 Connect <TX1> <TX2> <TX3> <TX4> <TX5> <TX6> <TX7> <TX8> <TX9> <TX10> <TX11> <TX12> 9 Connect <TX1> <TX2> <TX3> <TX4> <TX5> <TX6> <TX7> <TX8> <TX9> <TX10> <TX11> <TX11> <TX12> 10 Connect <TX1> <TX2> <TX3> <TX4> <TX5> <TX6> <TX7> <TX8> <TX9> <TX10> <TX11> <TX11> <TX12> 11 Connect <TX1> <TX2> <TX3> <TX4> <TX5> <TX6> <TX7> <TX8> <TX9> <TX10> <TX11> <TX12> 11 Connect <TX1> <TX2> <TX3> <TX4> <TX5> <TX6> <TX7> <TX8> <TX9> <TX10> <TX11> <TX12> 12 Connect <TX1> <TX2> <TX3> <TX4> <TX5> <TX6> <TX7> <TX8> <TX9> <TX10> <TX11> <TX12> <TX12> <TX12> <TX12> <TX12> <TX12> <TX12> <TX12> <TX13> <TX4> <TX5> <TX6> <TX7> <TX8> <TX9> <TX10> <TX11> <TX12> <TX11> <TX12> <TX13> <TX4> <TX5> <TX6> <TX7> <TX8> <TX9> <TX10> <TX11> <TX12> <TX12> <TX12> <TX12> <TX12> <TX13> <TX4> <TX5> <TX6> <TX7> <TX8> <TX9> <TX10> <TX11> <TX12> <TX12> <TX12> <TX12> <TX12> <TX12> <TX12> <TX12> <TX13> <TX14> <TX12> <TX14> <TX12> <TX14> <TX14> <TX14> <TX14> <TX15> <TX15> <TX15> <TX16> <TX16> <TX16> <TX16> <TX16> <TX17> <TX17> <TX17> <TX17> <TX18> <TX11> <TX11> <TX11> <TX12> <TX11> <TX110> <TX110>
```

## Serial Response:-

#### 005: Set Receiver and DTMF Decoder Conditions

This command lets you specify whether a user must have PL (CTCSS) to key up your repeater or whether it can be keyed with just carrier, among many other options. By selecting a "mode" from the

table below, you can tell the controller what conditions must be met for a receiver to be considered

active, that is to make it key connected transmitters. Each mode is described in detail on the following

page.

This command also lets you specify the conditions the controller requires to be met for DTMF tones to

be processed. Normally they are the same as the conditions for activating the receiver, but you can set

them to be different. You can, for example, allow access to your repeater with just carrier, but require

PL to enter any commands (enter "005 pp13"). Or you can require PL to access the repeater but provide

a PL override command that can be entered with only carrier (enter "005 pp31). The controller will-

mute

\_DTMF digits (if you have that option enabled, see command 007) regardless of the conditions you-

have

\_set to execute commands.

<005> pp Recall settings

<005> pp y Set receiver's access mode

<005> pp y z Set receiver's and DTMF decoder's access modes

#### Parameters:

- 005 is the default command name.
- 'pp' pp' is the port number (01..12)

- $\frac{\mathbf{v}}{\mathbf{v}}$  is the receiver's access mode
- 'z' z' is the DTMF decoder's access mode. If not specified and the receiver's access mode is not

zero, it will automatically be set the same as the receiver's access mode. To set 'z' to zero, all three digits of "pp y z" must be entered.

## Defaults:

- Receiver defaults to mode 1 on all ports.
- The DTMF decoders default to mode 1 on all ports except port 1, where it is "always active". That

should be changed once the COR polarity for port 1 is set up by entering "005 0111".

- If a port is connected to an RLC-ICM, use Mode 1.

#### Mode Definitions:

Mode

Definition

0

No Access

1

**COR Access** 

2

PL Access

3

COR and PL Access

4

COR or PL Access

5

Always Active

## Description of Modes:

Mode 0: The receiver is effectively disabled; even if the carrier and/or PL is received, the

controller will

sub-

ignore that receiver and will not key connected transmitters. If you are going to do this, you

need to have another way to enter commands to re-enable DTMF access (reverse patch, serial

port, another radio port, scheduler...).

Mode 1: The controller will respond to the COR signal, allowing access with carrier. The PL signal is

ignored.

Mode 2: The controller will respond to the PL signal. The COR signal is totally ignored. This mode

may cause very long squelch tails since PL decoders are generally slow to recognize when the

PL tone goes away (see mode 3).

Mode 3: Both COR and PL must be active at the same time for the controller to respond to the receiver.

Repeaters that require PL usually use this mode because it eliminates the long squelch tails

often heard when using mode 2. Typically, when someone keys a repeater with PL, the receiver's COR signal will go active first. The controller will ignore it for the moment. Perhaps 100 milliseconds later (the actual time varies) the PL decoder will recognize the

audible tone and will activate the PL signal going to the controller. At that point the controller

will see that the COR and PL are both active and will key up any connected transmitters (subject to the keyup delay filter and other factors). As long as both the COR and PL signals

are active, the controller will consider that receiver to be active. When that person unkeys, the

receiver's squelch circuit will recognize the loss of carrier very quickly (some squelch circuits

are faster than others - ask about the RLC-MOT) and deactivate the COR signal. The controller will see the change in the COR signal and mute the audio right away, so you get a

short squelch tail. The PL decoder will eventually figure out that the sub-audible tone went

away and deactivate the PL signal, perhaps 200 milliseconds later. The delay in sensing the

loss of PL won't matter because the audio is already muted (unlike mode 2).

Mode 4: Either COR or PL will cause the controller to respond to the receiver. This mode is useful if

you want to allow access to a repeater without PL, but you have to set the squelch relatively

tight to keep noise from keying the repeater. As long as your signal to the repeater is relatively

strong, you can transmit without PL and you will get short squelch tails just like in mode 1. If

you are too far away and can't get a strong enough signal to the repeater to open the squelch,

you can transmit a PL tone. If your signal is strong enough for the PL decoder at the repeater

to work, you will be able to talk on the repeater, even if you can't open the squelch (similar to

mode 2). Note that for this mode to work, the receiver must not mute the audio going to the

controller when the squelch is closed (you must use unsquelched audio). When using this

mode, you should transmit PL to the repeater only when necessary, as whenever you use PL,

you will get long squelch tails.

Mode 5: The controller considers the receiver to be active all of the time, regardless of the COR and PL

signals. This mode is useful for working with HF radios, with or without all-mode squelch. If

the HF radio doesn't have squelch, or if it does but it is set too tight and the signal keeps dropping out, you can select this mode to tell the controller to treat it like it is always active

while you are using it. You may want to change the access mode to mode 0 when you are not

using it, to keep it from timing out.

#### Example:

You want to change the receiver and DTMF mode to COR and PL (mode 3) on port 2. Note that

you don't need to specify the DTMF mode if it is the same as the receiver mode:

Voice Response: "Two CAP CAP" (CAP is for COR and PL)

#### Example:

You want to allow carrier access to a repeater on port 1, but you want to require PL to enter DTMF commands.

<005>01 1 3

Response: Voice Response "One CAP COR"

## 203: Set Vox Response

<203> pp recall vox response for port 'pp'

<203> pp 1 set vox response level 'l'(0..2)

<203> pp 1 ttt set vox response level (0..2) and threshold 'ttt'

#### Parameters:

- pp is the port number to recall or set
- 'l' is the vox response level (0 for slow, 1 for medium, 2 for fast)
- 'ttt' is the vox threshold (0..100)

## Examples:

- <u>→</u> 203 01 0 set vox response for port 01 to Slow
- $-\frac{1}{2}$  203 01 1 set vox response for port 01 to Slow
- $-\frac{1}{2}$  203 01 2 set vox response for port 01 to Slow

## 006: Set or Recall Receiver Priorities (monitor mute)

This command allows audio from a receiver to be automatically muted whenever audio from another receiver is heard. This can be used to mute a weather radio, for example, when someone keys

the repeater. The weather radio will remain muted as long as the repeater receiver is active and for a few

seconds afterward (this time can be changed). This is sometimes known as "monitor mute" because it is

often used when monitoring another repeater system, weather radio, space shuttle audio, etc.

For each transmitter, you can specify the "priority" of each receiver. If two receivers of the same

priority are active (keyed up) at the same time, their audio will be mixed (the way the controller always

worked in firmware versions V1.80 and earlier). If they have different priority settings, the audio from

the lower priority receiver will be muted.

```
<006> tt p
Recall settings for TX "tt"
```

<006> tt rr p Set priority for one RX

<006> tt rr ss p Set priority for two RX

<006> tt rr ss ...qq p

## Set priority for multiple RX

#### Parameters:

- 006 is the default command name.
- 'tt' tt' is the TX number (01..12)
- 'rr' is the RX number (01..12)
- 'p' is the priority (default priority for all receivers is 4, allowed values are 0..9)

## Examples:

You have a repeater on port 1 and a weather radio on port 2. You want to mute the weather radio-

if any other receiver can be heard on transmitter 1. If all of the other receivers are still set to their \_default-

priority level (4), we just need to set the priority for RX 2 to something less than 4. We will set it \_to zero-

in this example.

<006> 01 02 0 D or unkey or <Enter>

#### Notes:

Timers (51..56) control how long lower priority receivers stay muted after higher priority receivers become inactive.

013: Set COR and PL Active Levels

This command allows you to select whether the COR and PL inputs are active low or active high. The

default is active low; when the controller sees a COR line go to ground, it thinks that the receiver is

getting a signal. If you have a radio or PL detector that goes high when active, you can use this command to tell the RLC-DSP404 to consider high to be the active level.

<013> pp c o Set Active Level

<013> pp 0 0 Reset to Defaults

Notes:

- -This command does not affect the input circuits at all; it does not disable the built-in pullup resistors on the RLC-DSP404's COR and PL inputs.
- -If you are not able to enter commands using DTMF, you may need to temporarily fool the RLC-DSP404 into thinking that your receiver's active level is different than it is. For example, if

your receiver outputs an active high COR signal to the RLC-DSP404, the DSP4 will not accept DTMF commands from that receiver until its COR polarity is changed with this command.

You

could solve this problem by temporarily disconnecting the COR line from the receiver and manually attaching it to ground. This will cause the RLC-DSP404 to think that the receiver is active (COR line is active low by default). You will have to disconnect that line from ground or

press the 'D' key to simulate unkeying after entering each command.

#### Parameters:

- 013 is the default command name.
- pp is the port to select the active levels for.
- C is the COR polarity, 0 for active low, 1 for active high.
- o is the PL polarity, 0 for active low, 1 for active high.

#### Default:

- All COR and PL inputs default to active low.

#### Example:

Change Port 2's COR input to active high:

<013> pp 1 0 D or unkey or <Enter>

Voice Response: "2 1 0"

#### 155: Enable or Disable PTT for a Port

This command allows you to turn a PTT off regardless of what else the controller is doing. It doesn't

matter whether it is a repeater or a link, what receivers are active, or anything else, if this command gets

executed with F=0, the PTT goes off and stays off. This command is not the best way to regularly shutturn

off a repeater or link (see the section "Turning a Repeater Off" at the beginning of Chapter 2 for more

<u>information</u>), but will get the job done in an emergency. The only way to make the PTT work normally-

is to execute this command with F=1 or to reinitialize the controller.

<155> tt f

#### Parameters:

- 155 is the default command name.
- P is which transmitter to turn off
- F is 1 to enable the PTT (the default) or 0 to disable it

#### Notes:

This command does not disable the receiver, so you can normally turn the repeater back on by executing this command and enabling the PTT. However, if you have the controller set up to require a

challenge password and this command is password protected, you will not be able to hear the challenge

with the PTT disabled so you won't be able to log on and enable the PTT again. In that case you will

have to access the controller another way, such as from another radio port, from the reverse autopatch,

or-

from the serial port.

#### 156: Recall Which PTT are Enabled

This command allows you to recall which PTT are enabled and which have been turned off with Command 155.

# Parameters:

- 156 is the default command name.

# Voice Response:

Ports that are set to operate normally are listed. Any ports not listed have their PTT disabled. Normal response: "010203040506070809101112".

## Chapter 3: Audio and DTMF Configurations

This chapter deals with how the controller handles DTMF digits that are received from a radio or the

reverse autopatch. You can control both what is heard on the repeater while digits are being entered and

what the controller does with those digits - whether it uses them to execute commands or ignores them.

#### Background:

The controller has a DTMF decoder that is constantly listening to each receiver. A DTMF decoder

works by watching for 8 tone frequencies, 4 that represent the row and 4 that represent the column of a

16 key DTMF keypad. If a row frequency and a column frequency are detected at the same time, the

decoder registers it as a valid digit and tells the microprocessor. This takes about 40 or 50 milliseconds

from the time the DTMF digit starts.

#### DTMF Mute:

If you have the controller set to mute DTMF digits on a transmitter (see command 007), it will turn off

the audio from the receiver that is receiving DTMF digits to that transmitter as soon as the digit is

detected. Normally you will hear the first few milliseconds of the DTMF digit before it is detected and

muted, although you can avoid hearing it at all with an audio delay module (available from Link Communications).

The audio stays muted for a few seconds (see command 020, DTMF mute timers) after each digit is

released. If you press another digit during those few seconds (while the audio is still muted), you won't

hear any part of the following digits. So when you key up to enter a command, those listening to the

repeater will hear a short beep when you hit the first digit and then your digits will be muted (unless you

wait too long between digits and the timer expires).

#### **DTMF** Cover Tone:

If you want to, you can turn on a "cover tone" that is sent while the DTMF digits are muted (see

command 007). This constant beeping while digits are being entered lets people know that someone is

programming, so they don't just key up and talk over the silence of the DTMF mute. You can change

what the cover tone sounds like by editing macro 339.

## Drop Transmitters When DTMF Muted Option:

In some cases (usually for link transmitters), it is desirable to let a transmitter unkey when DTMF is

muted rather than transmitting a dead carrier or cover tone while DTMF is muted. Command 007 has an

option to enable this. Note that after the DTMF mute starts, the transmitter's hang timer (and mini-hang

timer) will run before the PTT will be turned off (the hang time is often very short on link transmitters,-

SO

\_this may not be noticeable). Also note that if there is another reason for the transmitter to stayed

#### keyed

up (another connected active receiver, synthesized voice message, etc.), the transmitter remainkeyed and

the receiver that is entering DTMF will simply be muted. Finally, if the DTMF mute bypassis used, the

transmitter will remain keyed so the DTMF digits can be heard.

### DTMF Mute Options are Set for Each Transmitter:

The DTMF mute options are set for each transmitter (not receiver). This means, for example, that if you

turn on the DTMF mute for your repeater transmitter, that DTMF tones will be muted on the repeater

whether they are received from the repeater receiver, a link receiver, the autopatch, etc. In most systems,

the DTMF mute (and often cover tone) are turned on for repeater transmitters.

## DTMF Mute Bypass:

The DTMF mute bypass, if enabled, allows the mute to be temporarily bypassed so DTMF digits can be

heard on transmitters where they are normally muted. The mute bypass is activated when the force-

execution digit (usually 'D', see command 078 to change) is the first digit detected after a receiver becomes active (when the user keys up). The bypass feature can be used to send DTMF paging codes

over a repeater that mutes DTMF digits or for passing commands out a link transmitter that normally

mutes DTMF tones. When the DTMF mute is bypassed in this way, the controller ignores the DTMF

digits that are entered; they will not cause the controller to execute commands or send error messages.

The bypass feature is de-activated when the receiver becomes inactive (when the user unkeys).

A typical example involves a repeater and link port. Both transmitters have their DTMF mute functions

enabled (possibly with cover tone or the drop-transmitter option), so when DTMF commands are sent to

the controller, it will mute the digits. If the DTMF mute bypass feature is turned on for the link transmitter but not for the repeater transmitter, a user can key up, press 'D' to activate the bypass, then

enter the DTMF digits. Those digits will be passed out the link transmitters but will still be muted on-

the

\_repeater transmitter.

The 'D' (force-execution digit) itself will be muted as soon as it is detected. If you do not have an audio

delay module, the first part of that 'D' will be heard and might mess up whatever you are passing tones-

to.

There are a variety of ways to deal with this:

- -Some devices (such as IRLP interfaces) automatically ignore 'D', so even if they do decode the part of the 'D' that is not muted, it won't have any effect.
- -Install an audio delay module on the receiver the tones are being entered from. That will allow the 'D' to be completely muted, so the listening device won't hear it at all.
- -If the tones are going to another controller that supports the same command 007 features:
  - -Turn off the DTMF bypass on the other controller so the 'D' won't cause it to ignore the digits
  - -Or see the "Advanced DTMF Mute Bypass Option" described at the end of command 007. It lets you disable the DTMF mute bypass for selected receivers.
- -If the listening device has a force-execution digit or something similar that will cause it to ignore

any digits already received, that digit could be sent after the 'D' and before the other digits.

-If the listening device resets when the signal goes away, use command 007 DTMF mute option 2

to drop the transmitter while digits are being muted and set the transmitters hang timer (and mini-

hang timer) to zero. When the force-execution digit is detected and muted, the transmitter will drop until that digit is released. Then it will come back up allowing the other digits to be passed

through.

-Turn DTMF mute off and enter the digits without using a 'D' first.

In firmware versions V1.80 and earlier, the DTMF mute bypass could be enabled or disabled for each

receiver. If the bypass feature was used, the DTMF mute was disabled on all transmitters. In all firmware versions since then, the DTMF bypass is enabled or disabled individually for each transmitter.

It doesn't matter which receiver the DTMF digits are entered from (but see the "Advanced DTMF Mute

Bypass Option" at the end of command 007); if the force execution digit is the first digit entered, any

transmitters connected to that receiver will have their DTMF mute functions temporarily disabled (until

that receiver unkeys). This change makes it possible to normally mute DTMF on both repeater and link

outputs and to use the mute bypass to allow DTMF digits to be sent down links without those digits

being heard on the repeater output.

## Passing DTMF Digits Down Links:

Link transmitters can be handled in a variety of ways.

- -If the DTMF mute is left off for link transmitters, all DTMF tones entered on the repeater receiver
- will be passed down the link (assuming that the repeater and link ports are connected, see see command 000). If the controller at the other end of the link is has similar command names to the

the local controller, it may try to execute commands that are not intended for it. If it has completely

- different command names (command 061 can help with this), uses preaccess (see
- \_ Chapter 9), or
- has some other way of figuring out which commands it should try to process, this \_ can work fine.
- If the DTMF mute is turned on for link transmitters and you need to send DTMF tones down the

links to the repeater controller on the other end of the link, you have two options: bypass the DTMF mute or make the controller generate DTMF digits.

- -Command 007 allows the DTMF mute bypass feature to be enabled for link transmitters. Once it is enabled, digits can be passed from the repeater receiver out the link transmitters by keying up, pressing 'D' to activate the mute bypass, then entering the DTMF digits that need to go down the link.
- -User macros (see Chapter 8) can be executed in response to user-entered DTMF commands. Those macros can be named almost anything from 1 to 6 DTMF digits long using command 010. They can be programmed to send any string of DTMF digits out any

any transmitter. For example:

010 600 ABC123; name macro 600 "ABC123" 055 600; make sure macro 600 is empty 056 600 037 2; send audio out transmitter 2 056 600 031 01 02 03 04; send DTMF "1234"

Note that the DTMF digits sent by the macro ("1234") may be completely different than the digits the user entered to cause the macro to be executed ("ABC123").

## Voice Falsing:

As mentioned earlier, a DTMF decoder works by watching for 8 tone frequencies, 4 that represent the

row and 4 that represent the column of a 16 key DTMF keypad. If a row frequency and a column frequency are detected at the same time, the decoder registers it as a valid digit. Sometimes peoples'

voices have those frequencies in them and cause the DTMF decoder to think that a digit is present when

it is not. If you have the DTMF mute turned on, this will cause it to be activated and your voice will

"drop out" for a couple of seconds as the controller thinks it is muting a DTMF digit. If you have the

cover tone turned on, you will hear it as well. The voice falsing of the DTMF decoder is not the decoder's fault - it is just watching for those tones.

Occasional falsing can be made less noticeable by reducing the duration of the DTMF mute timers. If-

you

have an audio delay module installed, that timer can be set to one half second or so with no negative

consequences. The disadvantage of short DTMF mute timer setting on inputs without audio delay

modules is that if you pause between digits, the first digit entered after the pause may be heard on the

repeater output. A<u>If not using an audio delay module, a</u> mute time of one or two seconds usually works-

well.

There are a couple of things you can do to reduce falsing at its source. The first thing is to check all of

your audio levels. If you have the receive audio turned up too high at any point before it gets to the

decoder, it may be distorted, which adds harmonics and makes falsing more likely. If <u>The most important thing you can do to minimize falsing is to check</u> your audio levels

are OK, you have older versions of the hardware, and you still have falsing problems, you may be able to

change some components to minimize the problem. The resistor value change (described below) has

been standard in later revisions of the controller hardware, so if your controller is new, you can skip the

rest of this section.

There is a resistor that controls how long a DTMF digit must be present before the DTMF decoder will

consider it to be valid. Increasing the value of this resistor will increase the required time and decrease

the chances of falsing, but may keep fast autodialers from working. Some early controllers may have

used a 300K resistor, while later controllers use 470K. Even larger values (up to about 700K, where the

decoder stops working at all) can be used in extreme cases.

It is possible to add an additional circuit paralleled across the resistor described above. That circuit

consists of a resistor and a diode in series. It does not change the amount of time it takes a digit to

decode (the diode prevents that), but they help reduce falsing by "resetting" the decoder faster when a

digit goes away. This resistor is normally 220K; smaller values would "reset" the decoder even faster.

This should not be necessary except perhaps in extreme cases. This circuit is already integrated in the

DSP404's decoders, so no modification is necessary.

#### at each point in

the signal chain. If the levels are high enough to cause distortion (even if it is not audible), it will introduce harmonics that can causing DTMF falsing. Chapter 1 includes instructions for setting the

audio level received by the controller.

205: Load Personality

<205>1 ii pp Load personality from list.

#### Parameters:

- -- 'l' is the list type (0 = factory, 1 = user).
- -- 'ii' is the index number of the personality in the list.
- -- pp is the port to load personality 'ii' into.

## Examples:

- $-\underline{\mathbf{u}}$  205 0 05 07 load settings from factory personalities #5 into port 7.
- $-\underline{\dot{u}}$  205 1 03 05 load settings from user personalities #3 into port 5.

206: Save Personality

<206> pp 'ii' Save port settings from port 'pp' into personality index-'ii'

#### Parameters:

- -- pp is the port to save personality from.
- -- 'ii' is the index identifier to save settings into.

## Examples:

- $-\underline{\underline{\dot{u}}}$  206 07 05 save settings from port 7 into personality index 05.
- $-\frac{1}{2}$  206 05 03 save settings from port 5 into personality index 03.

```
<200> pp
recall audio level
of 'w' for port pp
<200> pp
w m 1...1
set
rx/tx/tone/vox-
threshold level to
mode 'm' and
level '1...1'
Parameters:
  - pp = port number to recall
   - 'w' is the receiver, transmitter, or tone level to recall.
     '0' for recall of RX level
   '1' for recall of TX level
   '2' for recall of tone level
 - 'm' sets threshold of 'w' to level 'l..l' (0..100)
     - the '*' and '#' symbols allow change of current levels by a given value.
     - '*10' means increment by 10 (won't exceed 100)
      - '#5' means decrement by 5 (won't go below 0)
Notes:
200 pp 0 m 1..1 - set receiver audio level.
      - pp = port number
      - 'm' is 0 to enable AGC, 1 to disable it.
     - 'l..!' is the level to set it to (just the starting level if using AGC)
```

202: Set Transmitter Audio Delay

```
<202> pp
recall tx audio
delay for port 'pp'
<202> pp
set tx audio delay
to level 1..1
Parameters:
    pp is the port number to recall or set
   - 'l..l' is the level (0..400 in 10 msec increments)
   - the '*' and '#' symbols allow change of delay levels by a given value.
      - '*10' means increment by 10 (won't exceed 400)
      - '#5' means decrement by 5 (won't go below 0)
Examples:
 202 01 50 - set tx audio delay for port '01' to 500 msec.
  202 01 *5 - increase audio delay by 5.
  202 01 #5 - increase audio delay by 5.
  202 01 * - increase audio delay by 1.
```

## 007: Configure DTMF Mute/Cover Tone/Bypass

202 01 \* - increase audio delay by 1.

This command allows you to configure a what is heard on the specified transmitter when a user enters

DTMF digits. By default they are passed through the controller just as any other audio would be.

some cases (such as when you are configuring the controller), it may be preferable to keep the digits-

from

being heard. This command lets you simply mute the digits, mute them and send a cover tone-(constant

beeping), or drop the transmitter completely while the digits are being entered. A "bypass"-function can

\_also be enabled to allow DTMF digits to be passed through (rather than muted) if the force-execution

## force-

<u>execution</u> digit (usually "D") is the first DTMF digit pressed after keyup. See the beginning of thischapter for more

\_detailed explanations.

<007> pp Recall settings

<007> pp m Configure DTMF mute

<007> pp m b Configure DTMF mute and bypass

<007> pp 0 1 Restore defaults

#### Parameters:

- -- 007 is the default command name.
- -- pp is the port to set up or recall
- -- M turns the DTMF mute on or off
  - -0 Disables DTMF mute on the selected transmitter (default)
  - -1 Enable DTMF mute on the selected transmitter
  - -2 Enable DTMF mute with cover tone on the selected transmitter
  - -3 Drop the transmitter when DTMF tones are being received
- -- B (optional) turns the DTMF mute bypass on or off
  - -0 Disable the DTMF bypass for the selected transmitter
  - -1 Enable the DTMF bypass for the selected transmitter (default)

#### Voice Response:

- -<port number "pp">
- -<mute on/off>
- -<cover tone on/off>
- -<drop TX on/off>
- -<bypass enabled for TX "P">
- -<br/>bypass enabled for RX "P">

#### Notes:

—A DTMF digit will be muted, cause cover tone, let the transmitter drop, etc. as long as it is held.

-It will continue to have an effect after it is release for the duration of the DTMF interdigit timer

–(see Chapter 4) controls how long after a digit is released it will continue to cause muting / cover

-tone / transmitter drop.

Example: For port 1,turn on DTMF mute with cover tone and turn off the mute bypass:

<007> pp 2 0 unkey, 'D' or <Enter>

-Voice Response "1 2 OFF"

#### Notes about the Autopatch:

-When using the autopatch, if the other end is hung up before the autopatch is, you may get a "second dial tone" which allows you to make another call without hanging up. Since the controller

doesn't know that the other end hung up, it doesn't know that you are placing another call and will not

prevent you from making a long distance call, even if long distance numbers are normally blocked. To

prevent this, you can turn on the DTMF mute for the autopatch port, although there are some drawbacks

to that. If you turn on DTMF mute for the autopatch port, command 111 will no longer let you dial, you

will not be able to enter digits to control answering machines, leave pages, etc., or do anything else that

requires passing DTMF digits entered from the radio down the phone line. In most cases, the DTMF

mute can be left off with minimal risk of abuse.

## Advanced DTMF Mute Bypass Option:

-An optional digit can be appended to command 007 as described above, using the format "<007>

pp m b rr" where "rr" is the additional digit. If "rr" is 1 (the default) and "D" is the first digit entered

from receiver "pp", the DTMF bypass will work normally. If "r" is 0, the DTMF bypass feature will not

work from receiver "pp". In that case, if "D" (the force-execution digit) is the first digit detected from

receiver "p", it will just be ignored and following digits will be processed and muted as if the 'D' was

never heard (those DTMF digits can cause commands to be executed, may cause error messages, etc.).

-It might be useful to disable the DTMF bypass for link receivers. Then if a link receiver hears

part

of the DTMF "D" coming down the link from another site that is using the DTMF bypass feature to-

pass

DTMF tones out its link transmitter, that 'D' won't cause that link receiver to ignore the following-

digits.

# Chapter 4: Timers

This chapter deals with the controllers timers and time related issues. The areas dealt with in this chapter

\_are:

—<u>u</u> Programming, starting, restarting and recalling timers
 —<u>u</u> Setting and recalling the time-of-day clock

#### 020: Set or Recall a Timer's Duration

This command allows you to set the duration of a timer.

```
<0.20> xxx
Recall timer's duration
<0.20> xxx t..t
Set timer's duration
Parameters:
 -020 is the default command name.
 <u>'xxx'xxx'</u> is the timer to be programmed (three digits)
 -tt..t' is the value to be programmed into the timer, 0 to 9999, one to four digits.
 -The first group of timers are set in 10mS increments (100 counts per second).
 -The rest of the timers are set in 1 second increments (60 counts per minute, 3600 per hour).
Note:
 -When a timer is set, a count variable associated with that timer is set equal to duration of the
timer (t..t from command 020). Once the timer is set, the count variable starts counting down
from the
timer duration 0 and then stops after expiring. If command 020 is used to set a timer's duration-
the timer is running, the count associated with that timer will be adjusted accordingly. If the-
duration is set to a value less than the current count, the timer will expire immediately.
Conversely, if the
timer is set to a value greater than the count, the appropriate time will be added to the-
count to lengthen
the timer accordingly.
Pseudo Code:
 -IF(count != 0) THEN
                                     // Timer already running
    -IF( input duration > current duration ) THEN
      -count += input duration - current duration // Add appropriate time to count
                                                  // Set new timer's duration
      -current duration = input duration
    -ELSE
                      // Stop timer, it has already run longer than input duration
      -count = 0
      -current duration = input duration
                                                  // Set new timer's duration
    -END IF
 -ELSE
                         // Timer not running
    -current duration = input duration
                                               // Set new timer's duration
```

#### List of Timers

## Message Start Delay Timer:

This timer controls how long the controller will wait before sending any tones or voice messages in two

situations. The first is when you enter a command and unkey; it controls how long it will be before the

response to that command will be sent. If the delay is set too short, you might miss the first word or two

while your HT finishes switching from transmitting to receiving. The second situation in which this-

timer

might delay tones or voice messages is when they need to be sent out of a transmitter that is not-keyed up

at the time. The transmitter will be keyed for at least the duration of this timer before the toneor voice is

started. If this timer is too short, the transmitter might not have time to come up to full power and the

\_beginning of the tone or voice message might be missed. If the tone or voice message is beingsent down

a link system with multiple hops, more time might be needed so all of the link transmitterswill have time

\_to come up.

- This timer is programmed in 10mS increments from 0..9999.
- If a timer value of 000 is entered, the timer is disabled.

#### Timer Number —Defaults

-000 .Message Start Delay Timer, Transmitter 1500mS (050)
-001 .Message Start Delay Timer, Transmitter 2500mS (050)
-002 .Message Start Delay Timer, Transmitter 3500mS (050)
-003 .Message Start Delay Timer, Transmitter 4500mS (050)
-004 .Message Start Delay Timer, Transmitter 5500mS (050)
-005 .Message Start Delay Timer, Transmitter 6500mS (050)
-006 .Message Start Delay Timer, Transmitter 7500mS (050)
-007 .Message Start Delay Timer, Transmitter 8500mS (050)
-008 .Message Start Delay Timer, Transmitter 9500mS (050)
-009 .Message Start Delay Timer, Transmitter 10500mS (050)
-010 .Message Start Delay Timer, Transmitter 11500mS (050)
-011 .Message Start Delay Timer, Transmitter 12500mS (050)

#### Courtesy Beep Delay Timer:

This timer specifies the minimum time between when a receiver unkeys and when its courtesy beep will

be sent out connected repeater ports. The courtesy beep can also be delayed by other tones in the tone

queues and the synthesized voice.

- This timer is programmed in 10mS increments from 001-9999
- If a timer value of 000 is entered, the transmitter will hang on the air forever.

#### Timer Number

#### -Defaults

- -012 .Courtesy Beep Delay Timer, Receiver 1....1 sec (100)
- -013 .Courtesy Beep Delay Timer, Receiver 2. ... 1 sec (100)
- -014 .Courtesy Beep Delay Timer, Receiver 3. .... 1 sec (100)
- -015 .Courtesy Beep Delay Timer, Receiver 4. .... 1 sec (100)
- -016 .Courtesy Beep Delay Timer, Receiver 5. .... 1 sec (100)
- -017 .Courtesy Beep Delay Timer, Receiver 6. .... 1 sec (100)
- -018 .Courtesy Beep Delay Timer, Receiver 7. .... 1 sec (100)
- -019 .Courtesy Beep Delay Timer, Receiver 8. .. . . 1 sec (100)
- -020 .Courtesy Beep Delay Timer, Receiver 9. .... 1 sec (100)
- -021 .Courtesy Beep Delay Timer, Receiver 10 ....1 sec (100)
- -022 .Courtesy Beep Delay Timer, Receiver 11 ....1 sec (100)
- -023 .Courtesy Beep Delay Timer, Receiver 12 .... 1 sec (100)

## Transmitter Hang Timer:

This timer holds the transmitter PTT active after a connected receiver goes inactive. If a courtesy beep is

sent, this is the minimum time after the courtesy beep before the PTT drops. This timer only has an-

effect

when a connected receiver has been active since the PTT went active; otherwise this timer isignored and

the mini-hang timer (timer  $\frac{036063}{0.042074}$ ) is the only thing that will cause a delay. You must set-

the mini-hang

\_timer shorter than this timer or this timer won't have any effect, as the actual delay is the-longer of the

\_two timers.

- This timer is programmed in 10mS increments from 000-9999 (000 is OK).

## Timer Number —Defaults

- -024 .Hang Timer for Transmitter 1 .... 2 sec (200)
- -025 .Hang Timer for Transmitter 2 .... 2 sec (200)
- -026 .Hang Timer for Transmitter 3 .... 2 sec (200)
- -027 .Hang Timer for Transmitter 4 .... 2 sec (200)
- -028 .Hang Timer for Transmitter 5 .... 2 sec (200)

```
-029 .Hang Timer for Transmitter 6 .... 2 sec (200) -030 .Hang Timer for Transmitter 7 .... 2 sec (200) -031 .Hang Timer for Transmitter 8 .... 2 sec (200) -032 .Hang Timer for Transmitter 9 .... 2 sec (200) -033 .Hang Timer for Transmitter 10.... 2 sec (200) -034 .Hang Timer for Transmitter 11.... 2 sec (200) -035 .Hang Timer for Transmitter 12.... 2 sec (200)
```

#### **DTMF Mute Timer:**

This timer controls the amount of time a receiver entering DTMF stays muted after a DTMF digit is

released (assuming the DTMF mute is enabled with command 007). If following digits are entered-

within

the duration of this timer after the previous digit is released, they will be completely muted. If this timer

is set shorter than the time between digits, the beginning of the following digits will be heard. In other

words, setting this timer longer allows DTMF digits to be entered more slowly without hearing-the

\_beginning of the second and following digits. The disadvantage of increasing the duration of this-

timer is

\_that if the DTMF decoder voice falses (see the beginning of Chapter 3 for more informationabout voice

\_falsing), it will mute the voice longer.

- —If an audio delay module is installed for a receiver, this timer can be set quite short (to the length
  - -of the delay, usually about 100mS) or slightly longer. The audio delay module will keep the
  - -beginning of any digits from being heard and the short delay will minimize the problems with
  - -voice falsing. If it is set too short, the end of each digit may be heard (if the controller quits -muting before the audio gets through the audio delay module).
- —This timer is programmed in 10mS Increments from 001-9999
- —If a timer value of 000 is entered, your audio will be muted forever, so if you want it to be as —short as possible, enter 001

# Timer Number —Defaults -036 .DTMF Mute Timer, Receiver 1. ....1 sec (100) -037 .DTMF Mute Timer, Receiver 2. ....1 sec (100) -038 .DTMF Mute Timer, Receiver 3. ....1 sec (100) -039 .DTMF Mute Timer, Receiver 4. ....1 sec (100) -040 .DTMF Mute Timer, Receiver 5. ....1 sec (100) -041 .DTMF Mute Timer, Receiver 6. ....1 sec (100)

```
-042 .DTMF Mute Timer, Receiver 7. ....1 sec (100)

-043 .DTMF Mute Timer, Receiver 8. ....1 sec (100)

-044 .DTMF Mute Timer, Receiver 9. ....1 sec (100)

-045 .DTMF Mute Timer, Receiver 10 ....1 sec (100)

-046 .DTMF Mute Timer, Receiver 11 ....1 sec (100)

-047 .DTMF Mute Timer, Receiver 12 ....1 sec (100)
```

# I/O Polling Timer:

This timer determines how often the controller checks to see if any of the analog/digital input lines have

changed from high to low or low to high or if any analog alarm conditions have changed. If you want

quicker response to changes, shorten this timer. If you don't want to hear about changes that happen

more often than every minute or so, lengthen it to a minute. The default is one second.

Timer Number —Defaults

-048 .I/O Polling Timer ....1 sec (100)

## Courtesy Beep After Voice or Tones Timer:

This timer keeps a courtesy beep from being sent immediately after a voice message. It sets theminimum

amount of time the controller will wait after the voice and tone generators stop before acourtesy beep

will be sent. The courtesy beep delay timers (timers 00712.023) control how long after-unkeying the

controller will wait, but if they have already expired and the courtesy beep is just waitingfor the voice to

finish, this timer will have an effect. An example of this is when you kerchunk are repeater after a long

\_period of inactivity and then wait for the initial ID then the courtesy beep.

- This timer is programmed in 10mS Increments from 001-9999

Timer Number —Defaults

-049 .Courtesy Beep After Voice Timer, Transmitter 1 . . . . .1 sec (100)
-050 .Courtesy Beep After Voice Timer, Transmitter 2 . . . . .1 sec (100)
-051 .Courtesy Beep After Voice Timer, Transmitter 3 . . . . .1 sec (100)
-052 .Courtesy Beep After Voice Timer, Transmitter 4 . . . . .1 sec (100)

```
-053 .Courtesy Beep After Voice Timer, Transmitter 5 . . . . . 1 sec (100)
-054 .Courtesy Beep After Voice Timer, Transmitter 6 . . . . . 1 sec (100)
-055 .Courtesy Beep After Voice Timer, Transmitter 7 . . . . . 1 sec (100)
-056 .Courtesy Beep After Voice Timer, Transmitter 8 . . . . . 1 sec (100)
-057 .Courtesy Beep After Voice Timer, Transmitter 9 . . . . . 1 sec (100)
-058 .Courtesy Beep After Voice Timer, Transmitter 10 . . . . . 1 sec (100)
-059 .Courtesy Beep After Voice Timer, Transmitter 11 . . . . . 1 sec (100)
-060 .Courtesy Beep After Voice Timer, Transmitter 12 . . . . . 1 sec (100)
```

## Doug Hall RBI-1 or RLC-ICM Delayed Send Timer:

Buffers inside the RBI-1 or the RLC-ICM overflow if it is sent too many changes too quickly. The

RLC-DSP404 avoids this potential problem by collecting all of the changes that occur quickly (such as

within a macro) and sends the combined result of all of them only when no changes have been made for

the duration of this timer. This timer also affects the RLC-ICM.

- This timer is programmed in 10mS Increments from 001-9999

Timer Number —Defaults

-061 .RBI-1 or RLC-ICM Delayed Send Timer .....500 mS (050)

## HF Radio Scan Delay Timer:

This timer determines how quickly the HF radio will scan by controlling how long it waits before

## sending

the next frequency step. Smaller timer values make it scan more quickly. It affects all three-scan step

sizes (slow, medium and fast) equally. It also has an effect on how quickly other changes are sent to the

radio, although reasonable changes in that time won't be very noticeable. There is a limit to-how quickly

\_the controller can send command to the radio, so if setting this timer to a smaller value-doesn't increase

\_the scan speed past a certain point, you have probably reached that limit.

Some radios such as the Yaesu FT-767 require an acknowledgment to be sent after every command.

This causes them to scan only half as fast as other radios given the same scan timer setting (since

the

controller has to send the frequency command and the acknowledgment for each step). When using

those radios, you may wish to set the scan timer to about « the duration you would for other radios.

- This timer is programmed in 10mS Increments from 001-9999

```
Timer Number —Defaults

-062 .HF Scan Delay Timer . . . . . 500 mS (050)
```

# Transmitter Mini-Hang Timer:

This timer holds the transmitter PTT active for a minimum time after any keying source (connected

receiver, synthesized voice, tone, CW, DVR message, etc) goes inactive. It can be used to keep the

transmitter from dropping out immediately after a message. To control the hang time after a connected

receiver unkeys, you can also use the normal hang timers (024..035); the actual hang time will be the

longer of the two.

- This timer is programmed in 10mS increments from 000-9999

```
Timer Number —Defaults

-063 .Mini-Hang Timer, Transmitter 1. . . . . .500 mS (050)
-064 .Mini-Hang Timer, Transmitter 2. . . . .500 mS (050)
-065 .Mini-Hang Timer, Transmitter 3. . . . .500 mS (050)
-066 .Mini-Hang Timer, Transmitter 4. . . . .500 mS (050)
-067 .Mini-Hang Timer, Transmitter 5. . . . .500 mS (050)
-068 .Mini-Hang Timer, Transmitter 6. . . . .500 mS (050)
-069 .Mini-Hang Timer, Transmitter 7. . . . .500 mS (050)
-070 .Mini-Hang Timer, Transmitter 8. . . . .500 mS (050)
-071 .Mini-Hang Timer, Transmitter 9. . . . .500 mS (050)
-072 .Mini-Hang Timer, Transmitter 10 . . . .500 mS (050)
-073 .Mini-Hang Timer, Transmitter 11 . . . .500 mS (050)
-074 .Mini-Hang Timer, Transmitter 12 . . . .500 mS (050)
```

# Keyup Delay Timer:

The keyup delay timer is used to keep short noise bursts that open the receiver's squelch from

## keying up

the repeater. It can also keep people from kerchunking the repeater. When enabled, it makes the controller totally ignore keyups shorter than the duration of this timer (the rest of this explanation will

assume « second). If the receiver is keyed for longer than « second, the first « second will be ignored,

then it will respond normally, bringing up the transmitter, triggering the ID system, etc. To keep every

keyup from being delayed, the keyup delay is automatically disabled while the repeater is being used. It-

is

only re-enabled when the repeater is not used for a default of 60 seconds (see timers 279..290). If this

timer is set to zero (the default), the keyup delay is disabled. A typical setting would be 50, which is « second.

-Defaults

# Timer Number

```
-075 .Keyup Delay Timer, Receiver 1....0 (Disabled)
```

- -076 .Keyup Delay Timer, Receiver 2....0 (Disabled)
- 070 .Reyup Delay Tiller, Receiver 2.... 0 (Disabled)
- -077 .Keyup Delay Timer, Receiver 3.... 0 (Disabled)
- -078 .Keyup Delay Timer, Receiver 4....0 (Disabled)
- -079 .Keyup Delay Timer, Receiver 5....0 (Disabled)
- -080 .Keyup Delay Timer, Receiver 6.. . .0 (Disabled)
- -081 .Keyup Delay Timer, Receiver 7.... 0 (Disabled) -082 .Keyup Delay Timer, Receiver 8.... 0 (Disabled)
- -083 .Keyup Delay Timer, Receiver 9....0 (Disabled)
- -084 .Keyup Delay Timer, Receiver 10. . . . . 0 (Disabled)
- -085 .Keyup Delay Timer, Receiver 11.....0 (Disabled)
- -086 .Keyup Delay Timer, Receiver 12. . . . . 0 (Disabled)

## Wind Speed Timer:

This timer is used to help determine the wind speed indicated by an anemometer. The number of pulses

counted during the duration of this timer becomes the pseudo-analog value. For more information, see command 109.

```
Timer Number —Defaults

-087 .Wind Speed Timer . . . . . 2.26 sec (226)
```

# Word Too Long Timer:

There is no need to change this timer! It is used to ensure that even if the voice synthesizer messes up,

that it will not cause the controller to leave a transmitter keyed. If a word takes longer than this timer, it

will be truncated and the controller will go on to the next word.

```
Timer Number —Defaults

-088 .Word Too Long Timer . . . . . 1.5 sec (150)
```

## Receiver Priority Mute Timer:

This timer keeps lower priority receivers (as set with command 006) muted for the specified time after a

higher priority receiver becomes inactive.

- This timer is programmed in 10mS increments from 000-9999

#### Timer Number —Defaults

```
-089 .Receiver Priority Mute Timer, Receiver 1. . . . . .150 mS (015) -090 .Receiver Priority Mute Timer, Receiver 2. . . . .150 mS (015) -091 .Receiver Priority Mute Timer, Receiver 3. . . . .150 mS (015) -092 .Receiver Priority Mute Timer, Receiver 4. . . . .150 mS (015) -093 .Receiver Priority Mute Timer, Receiver 5. . . . .150 mS (015) -094 .Receiver Priority Mute Timer, Receiver 6. . . . .150 mS (015) -095 .Receiver Priority Mute Timer, Receiver 7. . . . .150 mS (015) -096 .Receiver Priority Mute Timer, Receiver 8. . . . .150 mS (015) -097 .Receiver Priority Mute Timer, Receiver 9. . . . .150 mS (015) -098 .Receiver Priority Mute Timer, Receiver 10 . . . .150 mS (015) -099 .Receiver Priority Mute Timer, Receiver 11 . . . .150 mS (015) -100 .Receiver Priority Mute Timer, Receiver 12 . . . .150 mS (015)
```

## Receiver Force Half Duplex Timer:

- This timer is programmed in 10mS increments from 000-9999

Timer Number -Defaults

- -101 .Receiver Force Half Duplex Timer, Receiver 1.... 0 (disabled)
- -102 .Receiver Force Half Duplex Timer, Receiver 2....0 (disabled)
- -103 .Receiver Force Half Duplex Timer, Receiver 3.... 0 (disabled)
- -104 .Receiver Force Half Duplex Timer, Receiver 4.... 0 (disabled)

- -105 .Receiver Force Half Duplex Timer, Receiver 5.... 0 (disabled)
- -106 .Receiver Force Half Duplex Timer, Receiver 6.... 0 (disabled)
- -107 .Receiver Force Half Duplex Timer, Receiver 7....0 (disabled)
- -108 .Receiver Force Half Duplex Timer, Receiver 8.... 0 (disabled)
- -109 .Receiver Force Half Duplex Timer, Receiver 9....0 (disabled)
- -110 .Receiver Force Half Duplex Timer, Receiver 10. . . . . 0 (disabled)
- -111 .Receiver Force Half Duplex Timer, Receiver 11..... 0 (disabled)
- -112 .Receiver Force Half Duplex Timer, Receiver 12. . . . . 0 (disabled)

## Recently Active Receiver Timer:

- This timer is programmed in 10mS increments from 000-9999

## Timer Number –Defaults

- -113 .Recently Active RX/TX Timer, Port 1.....1 mS (default)
- -114 .Recently Active RX/TX Timer, Port 2. . . . . 1 mS (default)
- -115 .Recently Active RX/TX Timer, Port 3. . . . . 1 mS (default)
- -116 .Recently Active RX/TX Timer, Port 4. . . . . 1 mS (default)
- -117 .Recently Active RX/TX Timer, Port 5. . . . . 1 mS (default)
- -118 .Recently Active RX/TX Timer, Port 6. . . . . 1 mS (default)
- -119 .Recently Active RX/TX Timer, Port 7. . . . . 1 mS (default)
- -120 .Recently Active RX/TX Timer, Port 8. . . . . 1 mS (default)
- -121 .Recently Active RX/TX Timer, Port 9. . . . . . 1 mS (default)
- -122 .Recently Active RX/TX Timer, Port 10 . . . . 1 mS (default)
- -123 .Recently Active RX/TX Timer, Port 11 . . . . 1 mS (default)
- -124 .Recently Active RX/TX Timer, Port 12 . . . . 1 mS (default)

#### Patch Link Wait Before Idle Timer:

- This timer is programmed in 10mS increments from 000-9999

#### Timer Number —Defaults

- -125 .Patch Link Wait Before Idle Timer, Port 1 . . . . 200 mS (default)
- -126 .Patch Link Wait Before Idle Timer, Port 2 . . . . . 200 mS (default)
- -127 .Patch Link Wait Before Idle Timer, Port 3 . . . . 200 mS (default)
- -128 .Patch Link Wait Before Idle Timer, Port 4 . . . . 200 mS (default)
- -129 .Patch Link Wait Before Idle Timer, Port 5 . . . . . 200 mS (default)
- -130 .Patch Link Wait Before Idle Timer, Port 6 . . . . . 200 mS (default)
- -131 .Patch Link Wait Before Idle Timer, Port 7 . . . . . 200 mS (default)

- -132 .Patch Link Wait Before Idle Timer, Port 8 . . . . . 200 mS (default)
- -133 .Patch Link Wait Before Idle Timer, Port 9 . . . . 200 mS (default)
- -134 .Patch Link Wait Before Idle Timer, Port 10. ... .200 mS (default)
- -135 .Patch Link Wait Before Idle Timer, Port 11. ... .200 mS (default)
- -136 .Patch Link Wait Before Idle Timer, Port 12. ... .200 mS (default)

# Console PTT Force Inactive Timer:

- This timer is programmed in 10mS increments from 000-9999

## Timer Number –Defaults

- -137 .Console PTT Force Inactive Timer, Port 1 . . . . 100 mS (default)
- -138 .Console PTT Force Inactive Timer, Port 2 . . . . 100 mS (default)
- -139 .Console PTT Force Inactive Timer, Port 3 . . . . . 100 mS (default)
- -140 .Console PTT Force Inactive Timer, Port 4 . . . . 100 mS (default)
- -141 .Console PTT Force Inactive Timer, Port 5 . . . . . 100 mS (default)
- -142 .Console PTT Force Inactive Timer, Port 6 . . . . . 100 mS (default)
- -143 .Console PTT Force Inactive Timer, Port 7 . . . . . 100 mS (default)
- -144 .Console PTT Force Inactive Timer, Port 8 . . . . . 100 mS (default)
- -145 .Console PTT Force Inactive Timer, Port 9 . . . . . 100 mS (default)
- -146 .Console PTT Force Inactive Timer, Port 10. .... 100 mS (default)
- -147 .Console PTT Force Inactive Timer, Port 11. ... .100 mS (default)
- -148 .Console PTT Force Inactive Timer, Port 12. ... .100 mS (default)

## Impolite ID Timer:

This timer waits until either the timer expires or activity goes away before sending an ID.

- This timer is programmed in 1Sec increments from 001-9999
- If a timer value of 000 is entered, the controller will not interrupt a conversation to send an ID.

#### Timer Number – Defaults

- -160 .Impolite ID Timer, Transmitter 1. .. . .20 sec (020)
- -161 .Impolite ID Timer, Transmitter 2. ....20 sec (020)
- -162 .Impolite ID Timer, Transmitter 3. ....20 sec (020)
- -163 .Impolite ID Timer, Transmitter 4. ... .20 sec (020)
- -164 .Impolite ID Timer, Transmitter 5. ....20 sec (020)
- -165 .Impolite ID Timer, Transmitter 6. ....20 sec (020)
- -166 .Impolite ID Timer, Transmitter 7. ....20 sec (020)

- -167 .Impolite ID Timer, Transmitter 8. .. . .20 sec (020)
- -168 .Impolite ID Timer, Transmitter 9. ....20 sec (020)
- -169 .Impolite ID Timer, Transmitter 10 .... 20 sec (020)
- -170 .Impolite ID Timer, Transmitter 11 ....20 sec (020)
- -171 .Impolite ID Timer, Transmitter 12 .... 20 sec (020)

#### Initial ID Timer:

This timer times the amount of inactivity before an initial ID is sent.

- This timer is programmed in 1Sec increments from 001-9999
- If a timer value of 000 is entered, the controller will never send an initial ID.

-Defaults

## Timer Number

- -172 .Initial ID Timer, Transmitter 1 . . . . .10 min (600)
- -173 .Initial ID Timer, Transmitter 2 . . . . .10 min (600)
- -174 .Initial ID Timer, Transmitter 3 . . . . . 10 min (600)
- -175 .Initial ID Timer, Transmitter 4 . . . . . 10 min (600)
- -176 .Initial ID Timer, Transmitter 5 . . . . .10 min (600)
- -177 .Initial ID Timer, Transmitter 6 . .. . . 10 min (600)
- -178 .Initial ID Timer, Transmitter 7 . .. . .10 min (600)
- -179 .Initial ID Timer, Transmitter 8 . .. . .10 min (600)
- -180 .Initial ID Timer, Transmitter 9 . . . . .10 min (600)
- -181 .Initial ID Timer, Transmitter 10. ... .10 min (600)
- -182 .Initial ID Timer, Transmitter 11.....10 min (600)
- -183 .Initial ID Timer, Transmitter 12. ....10 min (600)

#### Pending ID Timer:

This timer times inner activity ID timer so a proper Pending ID can be send during activity.

- This timer is programmed in 1Sec increments from 001-9999
- If a timer value of 000 is entered, the controller will never send a rotating ID.
- This timer should normally be set shorter than the initial ID timer (one minute shorter works well). -

You

may need to make sure that the duration of this timer plus the duration of the impolite ID timer is-

less.

\_than 10 minutes to meet requirements for ID timing.

## Timer Number –Defaults

- -184 .Pending ID Timer, Transmitter 1 . . . . . 9 min (540)
- -185 .Pending ID Timer, Transmitter 2 . . . . . 9 min (540)

```
-186 .Pending ID Timer, Transmitter 3 . . . . .9 min (540)
-187 .Pending ID Timer, Transmitter 4 . . . . .9 min (540)
-188 .Pending ID Timer, Transmitter 5 . . . . .9 min (540)
-189 .Pending ID Timer, Transmitter 6 . . . . .9 min (540)
-190 .Pending ID Timer, Transmitter 7 . . . . .9 min (540)
-191 .Pending ID Timer, Transmitter 8 . . . . .9 min (540)
-192 .Pending ID Timer, Transmitter 9 . . . . .9 min (540)
-193 .Pending ID Timer, Transmitter 10 . . . . .9 min (540)
-194 .Pending ID Timer, Transmitter 11 . . . . .9 min (540)
-195 .Pending ID Timer, Transmitter 12 . . . . .9 min (540)
```

## **Timeout Timers:**

This timer times how long each receiver has been active. If the receiver is active longer than theduration

of this timer, it is disabled until it goes inactive, and its time out message (see Chapter 8 for list-

macros) is sent out all transmitters that are connected to it. It is reset and the time out clear message is

sent when a timed out receiver goes inactive (or when the courtesy beep is sent, if that option is enabled

# with command 041).

- This timer is programmed in 1 second increments from 001-9999
- If a timer value of 000 is entered, the controller will never time-out.
- By default the time out timer is reset as soon as a receiver unkeys. To make it wait until the courtesy

-beep to reset (which may help discourage "tailgating"), see command 041.

## Timer Number – Defaults

```
-196 .Time Out Timer, Receiver 1 . . . . 3 min (180) -197 .Time Out Timer, Receiver 2 . . . . 3 min (180) -198 .Time Out Timer, Receiver 3 . . . . 3 min (180) -199 .Time Out Timer, Receiver 4 . . . . 3 min (180) -200 .Time Out Timer, Receiver 5 . . . . 3 min (180) -201 .Time Out Timer, Receiver 6 . . . . 3 min (180) -202 .Time Out Timer, Receiver 7 . . . . 3 min (180) -203 .Time Out Timer, Receiver 8 . . . . 3 min (180) -204 .Time Out Timer, Receiver 9 . . . . 3 min (180) -205 .Time Out Timer, Receiver 10 . . . . . 3 min (180) -206 .Time Out Timer, Receiver 11 . . . . . . 3 min (180) -207 .Time Out Timer, Receiver 12 . . . . . . 3 min (180)
```

#### Dial Tone Timers:

These timers are used to limit how long the dial tone will run. The dial tone can also be stopped by other

things, such as a DTMF character being entered on the port the dial tone is being set out of or the preaccess timer expiring (since indicating that a link has been preaccessed is what dial tone is used for

most). If you want to generate dial tone that can't be stopped by any of these things, use Command 040

and generate a two tone chord with frequencies of 350 and 440 Hz.

- This timer is programmed in 1Sec increments from 001-9999
- If a timer value of 000 is entered, this timer will never stop the dial tone.

#### Timer Number

#### -Defaults

-208 .Dial Tone Timer, Transmitter 1......8 sec (008)
-209 .Dial Tone Timer, Transmitter 2......8 sec (008)
-210 .Dial Tone Timer, Transmitter 3......8 sec (008)
-211 .Dial Tone Timer, Transmitter 4......8 sec (008)
-212 .Dial Tone Timer, Transmitter 5......8 sec (008)
-213 .Dial Tone Timer, Transmitter 6......8 sec (008)
-214 .Dial Tone Timer, Transmitter 7......8 sec (008)
-215 .Dial Tone Timer, Transmitter 8......8 sec (008)
-216 .Dial Tone Timer, Transmitter 9......8 sec (008)
-217 .Dial Tone Timer, Transmitter 10......8 sec (008)

-218 .Dial Tone Timer, Transmitter 11 . . . . . 8 sec (008) -219 .Dial Tone Timer, Transmitter 12 . . . . . 8 sec (008)

## **Preaccess Timers:**

These timers control how long the "window" of access is between when you enter the preaccess code-

and

when you have to enter a DTMF digit or be locked out. It starts running again as soon as each-DTMF

digit is released, and will lock you out if it expires. When it expires, it throws away whatever DTMF

\_digits have been entered so far and won't accept any more commands until the controller isaccessed

\_again. It also stops the dial tone when it expires.

- This timer is programmed in 1Sec increments from 001-9999
- If a timer value of 000 is entered, this timer will never expire.

Timer Number

-Defaults

```
-220 .Preaccess Timer, Port 1 ... .8 sec (008)
-221 .Preaccess Timer, Port 2 ... .8 sec (008)
-222 .Preaccess Timer, Port 3 ... .8 sec (008)
-223 .Preaccess Timer, Port 4 ... .8 sec (008)
-224 .Preaccess Timer, Port 5 ... .8 sec (008)
-225 .Preaccess Timer, Port 6 ... .8 sec (008)
-226 .Preaccess Timer, Port 7 ... .8 sec (008)
-227 .Preaccess Timer, Port 8 ... .8 sec (008)
-228 .Preaccess Timer, Port 9 ... .8 sec (008)
-229 .Preaccess Timer, Port 10... .8 sec (008)
-230 .Preaccess Timer, Port 11... .8 sec (008)
-231 .Preaccess Timer, Port 12... .8 sec (008)
```

## **User Timers:**

These timers are not normally used by the controller. They are provided for your use. You can start

them running by executing Command 022 and stop them with 023 (or they will stop automatically when

they expire). Also, when one of these timers expires, the corresponding special macro (see Chapter 8) is

automatically executed. This allows you to start these timers when certain things in the controller

happen, and do something when the timer expires. These timers are programmed in one second increments.

# Timer Number —Defaults

```
-232 .User Timer 00 ... .0 sec (000)
-233 .User Timer 01 ... .0 sec (000)
-234 .User Timer 02 .... 0 sec (000)
-235 .User Timer 03 .... 0 sec (000)
-236 .User Timer 04 .... 0 sec (000)
-237 .User Timer 05 ... .0 sec (000)
-238 .User Timer 06 .... 0 sec (000)
-239 .User Timer 07 .... 0 sec (000)
-240 .User Timer 08 .... 0 sec (000)
-241 .User Timer 09 .... 0 sec (000)
-242 .User Timer 10 ... .0 sec (000)
-243 .User Timer 11 .... 0 sec (000)
-244 .User Timer 12 .... 0 sec (000)
-245 .User Timer 13 .... 0 sec (000)
-246 .User Timer 14 .... 0 sec (000)
-247 .User Timer 15 .... 0 sec (000)
```

DTMF Interdigit Timers or Auto-execution timers (See Command 078):

These timers are used to get rid of stray DTMF digits after several seconds without entering any more

digits. For example, if you key and press a DTMF digit, then start talking, this timer will throw that digit

away after a default of 5 seconds. That way if, after you talk a while, you try to enter a command, the

digit you entered 30 seconds ago won't mess it up. Of course if you unkeyed during that time, all of the

digits would be either executed or discarded anyway. This also reduces problems caused by voice-

falsing

the DTMF decoder, by discarding the incorrectly received digits if no more digits are received-during the

\_duration of this timer. This timer starts running when the DTMF digit is released, so you canhold a

\_DTMF digit as long as you like without it being discarded.

# Timer Number –Defaults

- -248 .DTMF Interdigit Timer, Receiver 1 ....5 sec (005)
- -249 .DTMF Interdigit Timer, Receiver 2 ....5 sec (005)
- -250 .DTMF Interdigit Timer, Receiver 3 .... 5 sec (005)
- -251 .DTMF Interdigit Timer, Receiver 4 .... 5 sec (005)
- -252 .DTMF Interdigit Timer, Receiver 5 .... 5 sec (005)
- -253 .DTMF Interdigit Timer, Receiver 6 .... 5 sec (005)
- -254 .DTMF Interdigit Timer, Receiver 7 .... 5 sec (005)
- -255 .DTMF Interdigit Timer, Receiver 8 .... 5 sec (005)
- -256 .DTMF Interdigit Timer, Receiver 9 .... 5 sec (005)
- -257 .DTMF Interdigit Timer, Receiver 10....5 sec (005)
- -258 .DTMF Interdigit Timer, Receiver 11....5 sec (005)
- -259 .DTMF Interdigit Timer, Receiver 12....5 sec (005)

## Reverse Patch Ring Timer:

This timer sets the maximum time between rings allowed for the reverse patch to work. If this timer

expires between rings, the ring count starts over. This would keep the reverse patch from everanswering

the phone.

- This timer is programmed in 1 second increments from 001-9999

Timer Number -Defaults

-260 .Reverse Patch Ring Timer . . . . . 10 sec (010)

# User Log-off Timer:

This timer specifies the amount of time between correctly executed command entries that a user

before the controller logs the user off the system.

Timer Number	-Defaults
THICK NUMBER	Detauns

- -261 .Log-off timer for Port 1....300 sec (300)
- -262 .Log-off timer for Port 2....300 sec (300)
- -263 .Log-off timer for Port 3....300 sec (300)
- -264 .Log-off timer for Port 4....300 sec (300)
- -265 .Log-off timer for Port 5....300 sec (300)
- -266 .Log-off timer for Port 6....300 sec (300)
- -267 .Log-off timer for Port 7....300 sec (300)
- -268 .Log-off timer for Port 8....300 sec (300)
- -269 .Log-off timer for Port 9....300 sec (300)
- -270 .Log-off timer for Port 10. . . . . .300 sec (300)
- -271 .Log-off timer for Port 11. . . . . .300 sec (300)
- -272 .Log-off timer for Port 12. . . . . .300 sec (300)
- -273 .Log-off timer for the Serial Port .300 sec (300)
- -274 .Log-off timer for the Webserver . .300 sec (300)
- -275 .Log-off timer for Telnet Server 1 .....300 sec (300)
- -276 .Log-off timer for Telnet Server 2 .....300 sec (300)
- -277 .Log-off timer for Telnet Server 3 .\_\_\_300 sec (300)
- -278 .Log-off timer for Telnet Server 4 .....300 sec (300)

## Beacon Timer:

This timer specifies the amount of time the controller will wait before trying to send the next

See Chapter 19 for more information about the beaconing system.

Timer Number

**Defaults** 

# 279 .Beacon Timer .... 1 sec (001)

# Re-Enable Keyup Delay Timers:

These timers determine how long a receiver must be inactive after being keyed up before the keyup delay

will be re-enabled. See the description for timers 075..086 for more information.

## Timer Number

## -Defaults

```
-27980 .Re-Enable Keyup Delay Timer, RX 1 ... .60 sec (060) -2801 .Re-Enable Keyup Delay Timer, RX 2 ... .60 sec (060) -2812 .Re-Enable Keyup Delay Timer, RX 3 ... .60 sec (060) -2813 .Re-Enable Keyup Delay Timer, RX 4 ... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 5 ... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 6 ... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 6 ... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 7 ... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 8 ... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 9 ... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 10... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 11... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 11... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 11... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 11... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 11... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 11... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 11... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 11... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 11... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 11... .60 sec (060) -2814 .Re-Enable Keyup Delay Timer, RX 12... .60 sec (060)
```

# 021: Restart a Timer (if already running)

The controller automatically starts and stops most timers, but you can override the controller's normal

way of doing things with this command. You can also use this command with the user timers (timers

```
<del>232-247</del>232..247).
```

This command allows you to restart a timer if it is currently running. This means that the count associated with the timer has not yet expired (count = 0). When recall the timer, get a message like this,

"Timer TTT LL count CC" where TTT is the timer number, LL is the duration it is set to, and CC is the

current count, the amount of time left before it expires if it is currently running. Also see command 022.

```
< 0.21 > xxx
```

#### Parameters:

- -- 021 is the default command name.
- -- XXX is the timer to restart (three digits, see command 020 for list of timers)

#### Pseudo Code:

```
-IF( count != 0 ) THEN  // Timer already running
-count = timer_duration  // Start timer over at beginning
-END IF
```

## 022: Start/Restart a Timer

The controller automatically starts and stops most timers, but you can override the controller's normal

way of doing things with this command. You can also use this command to make the user timers (timers

```
232-247232..247) start running.
```

This command sets the count variable associated with a specific timer equal to the duration of the timer

set with command 020 or to a value specified in this command. Once the count variable is set, the

countdown to expiration begins. If the timer is already running, this command will make it start over.

```
<022> xxx
Start timer 'xxx' xxx' for the duration set with command 020

<022> xxx t..t
Start timer 'xxx' xxx' for duration 'tt..t'
```

#### Parameters:

- -- 022 is the default command name.
- <u>- 'xxx'xxx'</u> is the timer to start (three digits, see command 020 for list of timers)
- = -'tt.t' is the duration the timer should run for this time only. This does not permanently change

-the duration of the timer; that is what command 020 is for.

#### Notes:

- —<u>u</u> Some timers (such as the ID timers) are reset to their normal duration periodically by the –firmware, so command 022 may be ineffective on those timers.
- —<u>u</u> If a timer's normal duration has been set to 0 with command 020, it will not run even if you –specify a value for t..t with command 022. A duration of zero set with command 020 totally –disables the timer.

## Pseudo Code:

```
    -IF( Setting new temp_time ) THEN
    -count = input_duration // Start timer for temporary duration
    -ELSE
    -count = timer_duration // Start timer for duration set by command 020
    -END IF
    023: Stop a Timer
```

This command allows you to stop a timer, so that it will not finish counting down and eventually expire.

The controller automatically stops most timers as needed, so the only time you should need to use this

command is when you want to change the way the controller normally works. Most timers automatically

stop when they expire.

<023> xxx

## Parameters:

- -- 023 is the default command name.
- -- XXX is the timer number

```
Pseudo Code:
```

-count = 0 // Stop timer

025: Sets the Time of Day Clock

This command allows you to set the time of day clock on the RLC-DSP404.

<0.25> hh mm a/p

## Parameters:

- -- 025 is the default command name.
- -- HH is the actual hours with leading zeros
- -- MM is the actual minutes with leading zeros
- -- a/p is the AM/PM selection (1=PM, 0=AM)

# Example:

-Want to set the time to 3:25 PM

<025> 03 25 1 D or unkey or <Enter>

-Voice Response: "<Hour> <Minute> <AM/PM>"

026: Recall the Time of Day Clock in Male Speech

This command allows you to read the Time of Day Clock. The readback is Male time reading. Refer to

Command 025 for setting the clocks time.

< 026>

#### Parameters:

-- 026 is the default command name.

# Voice Response:

-"Male voice: <Hour> <Minute> <AM/PM>"

# 027: Recall the Time of Day Clock in Female Speech

This command allows you to read the Time of Day Clock. The readback is Female time reading. Refer

to Command 025 for setting the clocks time.

< 027>

## Parameters:

-- 027 is the default command name.

# Voice Response:

-"Female voice: <Hour> <Minute> <AM/PM>"

028: Sets the Date

This command allows you to set the date on the RLC-DSP404 Clock.

<028> mm dd yy w

#### Parameters:

- -- 028 is the default command name.
- -- MM is the month with leading zeros
- -- DD is the day of the month with leading zeros
- -- YY is the last two digits of the year

W is the day of the week

Number

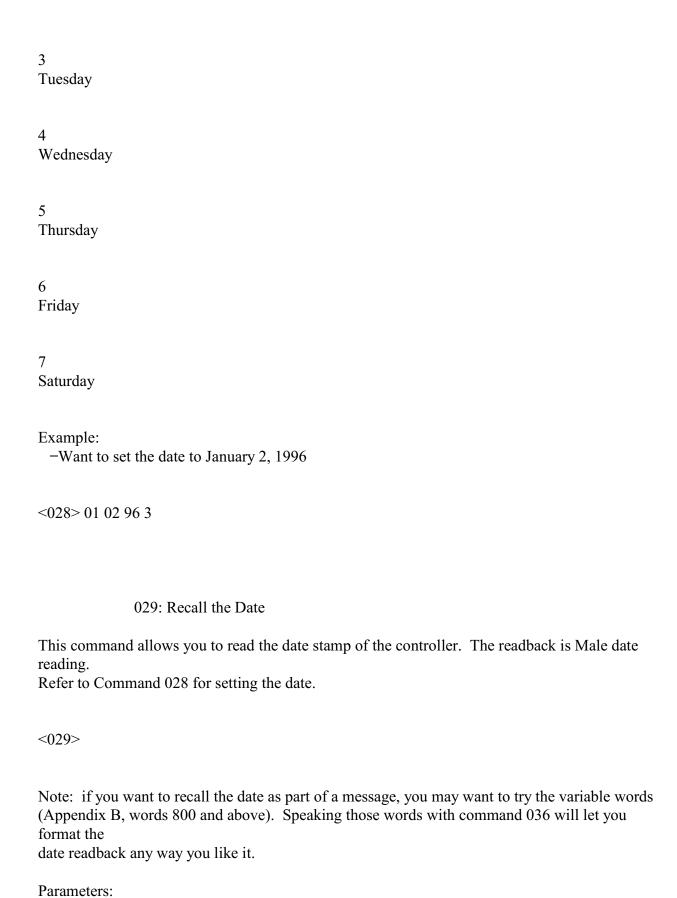
Day

1

Sunday

2

Monday



-- 029 is the default command name.

Voice Response:
-"This is <Day of Week> <Month> <Day> <pause> <Year>"

## Chapter 5: Command Names

This chapter deals with command names and controlling when those command names will be accepted

and executed by the controller.

-<u>u</u> Command name programming, checking and recalling

-<u>u</u> Blocking and allowing command execution

How Command Names and Command Numbers are Used:

The RLC-DSP404 controller has 1000 commands. The first 300 are commands that do a specific task

and are described in this manual. The rest of the commands are macros that automatically execute a

sequence of other commands. The controller automatically uses some of the macros to send IDs, courtesy beeps, and other things. These macros that are called automatically are described in Chapter 8.

The remainder of the macros can be used for anything you want, such as turning on a link and sending a

message for example.

#### Command Names:

Any of the 1000 commands can be executed by entering DTMF digits from a radio, from the reverse

autopatch, or with a computer or serial terminal that is connected to the controller's RS-232 serial port.

To execute the commands, you enter the command's name and unkey or press enter. To execute some of

the first 300 commands, you have to enter more digits after the command name, to give the controller

more information.

The command names default to 000, 001, 002..999. So to recall the time (command 026), you would

just enter 026 and unkey. To set the time (command 025), you would enter "025" followed by the

current time (two digits for the hour, two digits for the minute, and one digit to specify AM or PM). All

of the other commands are similar.

You can change the name of any or all of the commands using command 010. The name can be changed

to any combination of DTMF digits up to six digits long. Normally you should avoid using the

'D' as-

part

of the command names to avoid conflicting with the force-execution digit. If you are doing your programming from a computer or serial terminal, you can use characters that aren't DTMF digits in your

command names, but then you won't be able to execute them from a radio.

#### Command Numbers:

The controller keeps track of both what the command was originally named (what it is in the manual)-

and

what you may have renamed it to (they start out the same, 000, 001...). The original name issometimes

\_called the command number and it never changes. The command number is used for several-things. One

of them is renaming commands. To rename command 009 to ABC, you would enter "010-009 ABC",

where 010 is the rename command, 009 is the command number, and ABC is the new name. - If you then

change your mind and want it to be called CBA, you would enter "010 009 CBA". Note that you still use

\_009, not ABC, when renaming it to CBA. You always rename the command number to thenew name,

not the old name to the new name. This eliminates any confusion if you forget a command's-name or if

\_you have more than one command with the same name.

Command numbers are also used when programming macros (see commands 053 and 056), setting

DTMF execution masks (commands 130 and 131) and several other things. Remember that you use the

command name to execute the commands; you sometimes use the command number as part of the

information you enter after a command name.

When you execute a command from the serial port, you can enter the command name just as you would

from a radio or the reverse patch, hitting enter instead of unkeying when you are finished. That is why

the prompt you get when you press enter is "DTMF>"; you can enter digits just like they were DTMF

digits. There is also a way to execute commands from the serial port using the command number. This-

is

handy because the command number never changes. To execute a command using its number, just-

put an

N at the beginning of the line, followed by the command number and any other digits thatcommand

might need (see command 080 for information about how this works internally). We could-rename

command 009 to ABC from the serial port just as we did from the radio, by entering "010 009-ABC" and

\_pressing enter (spaces are always accepted but never required). But if the name of command-10 was

changed, that would no longer work. If we enter "N010 009 ABC", it will work even if command 10 has

 $\underline{\hspace{0.5cm}}$  been renamed because the N makes the controller use the command number for command 010 rather than

\_its name. This is especially useful if you store a list of commands in a file ona computer (so you can

\_upload the whole file to the controller and set it up all at once), as you don't haveto worry about whether

any of the commands you use in that file have been renamed. The N cannot beused from a radio, since

there is no DTMF digit N. You wouldn't want it to be possible from a radio-anyway, or it would be a major security problem.

Converting Command Name <--> Command Number:

Command Number ---> Command name is accomplished with Command C011

If you have forgotten the name of command number 009, you can find out what it is by entering "011

009" and unkeying or pressing enter, or you can just change it to the name you want it to have with

010.

Command Name ---> Command number is accomplished with Command 012

If you know that entering a command name of "ABC123" causes a command to execute but you

- \_ don't
- know what command number it is executing, you can use command 012 to find out by entering
- ABC123" and unkeying or pressing enter.

Advanced Command Naming Topics:

You probably don't need to read this section, but it is here just in case. If it doesn't make sense to you,

just skip it.

The controller has a table which it uses to keep track of the information for each command. This information is used when the controller tries to find out what command you have entered the name for.

If

more than one command have the same name, it can also be used to intelligently figure out which one-

you

wanted. Some of the entries are:

- —<u>u</u> Command name (including the length of the name).
- $-\dot{\mathbf{u}}$  Data length: that is how many digits, if any, are needed after the command name.
- $-\underline{\underline{\dot{u}}}$  If the data length is not zero, whether the amount must be exact or whether more digits can be

-entered.

- <u>u</u> DTMF execution mask (see command 130)
- $\underline{\phantom{a}}$  User level required to execute (see Chapter 18)

For example, Command 009 would have a data length of zero, command 000 would have a data length-

of

2 which must be exact, and command 036 would have a minimum data length of 3, but could belonger.

Other checking such as making sure that the data for 036 is a multiple of three digits and-limiting the

maximum length is done by the commands themselves. Where the checking is done is important. The

checks that can be done with the information in the table can be used to help figure outwhich command

\_you want to execute when the names are ambiguous, while the checks that are donewithin the commands

\_themselves are too late.

When you enter a command and unkey or press enter, the controller scans the whole table of commands

looking for a match. It ignores any commands that would be blocked by the DTMF execution mask or

that require that you log on using a password to execute. It also ignores any that it knows have

wrong number of data digits after the command name (using the information in the table as discussed

above), although there are some cases where it can't tell until the command is chosen and causes

an-

error.

\_ From the remaining commands, it chooses the one with the longest name that matches what was

entered. In case of a tie, it chooses the one with the lowest command number.

For example, if you have commands named "1", "12", "123", "1234" and "12345" and you enter "12399".

\_assuming that all of them pass the initial execution mask and password and data length checks, the

controller will select the command named "123" and will execute it with the data digits "99". That is-

it

will find the longest match, then use the rest of the digits as data. Keep this in mind when you change

command names to be less than three digits. If you change the "Retrieve Public Mail" command (177)-

to

have the name "12", then enter "123" to get the mail from mailbox 3, you may instead execute-command

\_"123" because it also matches and has a longer name. If command 123 needs additional digits-after the

command name, the controller will figure out what you mean, but sometimes it just can't tell. - So when

\_you rename commands, keep in mind that any name that is the same as the beginning ofanother name

\_might be ambiguous.

This ability of the controller to find the longest matching name can be used in several practical ways.

For

example, command 000 connects two ports together. It normally sends "X connect Y" as the voice

response. If you have a repeater on port 1 and a link to another site on port 2, you might want the message to be "Link up" instead. You could make a macro named "00012" or "00021" that would

connect the two ports and send that message. Then entering "00012" or "00021" would cause your

custom message to be sent, while "00013" or any other command starting with "000" would access the

normal command 000 and cause the normal "X connect Y" message. Another example: your autopatch

up code is '\*' and your autodial slot is number 43. Pressing "\*43" normally causes the response, "Autodial 43". You want to make it say "KC7HXB home" instead. To do this, make a macro called

"\*43" and make it speak that voice response, then make the call. '\*' followed by any other number will

still make it say "Autodial", but "\*43" will find the macro and cause your custom message. This technique can also be used to turn off the time out timer for emergency numbers.

It is possible, although not recommended, to give several commands the same name. For example, 000,

009 and 036 could all be named "ABC" and the controller would always be able to figure out which one

you wanted because of the information stored in the command table. Command 000 always takes-

exactly

\_two data digits, 009 never takes any, and command 036 requires three or more. So "ABC"-would select

 $\c command 009, "ABC12" would select command 000 and connect ports 1 and 2, and "ABC001002003"$ 

would make command 036 speak "one two three". This feature is most often usedwhen trying to clone

the command codes used on a previous controller, using more than one commandon this controller.

In summary, the controller lets you name commands just about any way you want to, even if it is confusing for you and it. It does its best to figure out what you mean, using the data length, DTMF

execution masks and passwords to eliminate some possibilities, but sometimes it is impossible. If you

can't get it to work the way you want it to, check the command names with commands 011 and 012, then

start naming them back to their original names with 010 until the confusion goes away. The most

common confusion is having one command that is named the same as the beginning of another-command,

so the longer one gets executed when you expected the shorter one. When all of the-commands have

their original names, there is no confusion because every command has its own uniquethree digit name,

the command number.

## 010: Re-Program Command Names

This command allows you to re-name the command names on the controller. The names can be from 1-

to

\_6 digits in length.

<010> xxx yyyyyy

#### Shortcut:

-If you want to change the first few digits of a whole range of command names, check out command 062.

## Notes:

-You should avoid renaming command 080, or the 'N' method of entering commands from the serial port will quit working. See Appendix F for more information about using 'N'.

#### Parameters:

- -- 010 is the default command name.
- -- XXX is the command's number. It is the same as the last three digits of the command name as
  - -listed in the manual. Examples: the command number for this command (010) is 010.
  - -For command 123, the command number is 123. The command number is always three
  - -digits. Renaming the command does not change the command number you still use the
  - -command number as listed in the manual.
  - -- YYYYYY is the new command name.
    - --- You only enter as many digits for the command name as the length you want the new -name to be. You do not need to enter any leading digits for the command name.

## Acceptable entries:

XXX Y

- New command name is 1 digit in length

- New command name is 2 digits in length

- New command name is 3 digits in length

- New command name is 4 digits in length

- New command name is 5 digits in length

- New command name is 6 digits in length

- New command name is 6 digits in length

#### Default:

-- Command names begin with 000 and end with 999

## Voice Response:

-"Change <command number>"

-The new name is not read back for security. To check that the command was renamed correctly,

-use "011 < command number>".

## Example #1:

- -Want to re-name command 013 to ABC12
- -1) Command Number is 013
- -2) New command name is ABC12
- -3) 010 013 ABC12 D or unkey or <Enter>
- -4) Voice response: "Change thirteen"

# Example #2:

-You changed your mind. Now you want command number 013 (which we just renamed to ABC12) to ABC123 instead.

- -1) Command Number is 013
- -2) New command name is ABC123
- -3) 010 013 ABC123 D or unkey or <Enter>
- -4) Voice response: "Change thirteen"

-Note that the current command name does not matter at all, only the command number (the last

-three digits of the command name in the manual) and the new name.

## 062: Change the Beginning of Command Names

This command allows you to change the first one, two or three digits of the names of a range of commands. If you specify one digit, all of the command names in the range you specified will become

four digits long. If you specify 2, they will be 5 long (and 3, 6). The last three digits of a command's

name can not be changed with this command (see command 010). This is to avoid accidentally-assigning

the same name to multiple commands.

<062> bbb eee d

Change the first digit of the name in a range

<062> bbb eee dd

Change the first and second digits of the name in a range

<062> bbb eee ddd

Change the first, second and third digits of the name in a range

<062> bbb eee

Strip off enough leading digits to make each command name three digits or less. This will "undo" most of the changes made with the above formats.

#### Parameters:

- -- 062 is the default command name.
- -- BBB is the number of the first command in the range that you want to change
- -- EEE is the number of the last command in the range that you want to change
- -- D or DD or DDD are the new first digits of the command names

#### Notes:

- —<u>w</u> You should avoid renaming command 080, or the 'N' method of entering commands from the –serial port will quit working. See Appendix F for more information about using 'N'.
- $-\underline{\underline{\dot{u}}}$  Any commands in the range that have names shorter than three digits long will have zeros added
- -before their names to make them three digits long before this command changes the other digits.
- -For example, 062 010 050 A changes C010 to A010, 123 to A123, A1 to A0A1, and # to A00#.

# Example 1:

-You want to change the names of all of the commands in the controller to start with '#' so that they can be executed from a 12-key touch tone pad:

<062> 000 999 # D or unkey or <Enter>

## Example 2:

-You want to make the names of commands 010 through 050 more difficult to guess by making

them 6 digits long, starting with the digits 96C:

<062> 010 050 96C D or unkey or <Enter>

#### 011: Recall Command Name

This command allows you to recall the name of a command. It also tells you whether it requires more

digits to be entered after the command name, if so how many, and whether more digits than that will be

accepted. You specify the command number (the name of the command in this manual) and the controller will look up its name.

<0.11> xxx

#### Parameters:

- -- 011 is the default command name.
- -- XXX is the command number ranging from 000-999

## Voice Response:

- -The voice response is XXX YYYYYY 'ED' (Number of Digits of Extra Data)
- --- "ED" signifies that the following number is the amount of additional data needed for that -command.
- --- If the word "Variable" is spoken, the controller will accept more than the specified number of
  - -digits. If not, exactly that many digits must be entered. See the discussion about
  - -command names and numbers at the beginning of this chapter for more information.

#### Parameters:

-- 011 is the default command name.

- --- This command recalls the command number for the associated command name
- -- YYYYYY is the command name with default command name of 000-999

# Voice Response:

-The voice response is "Command Number (000-999)" is YYYYYY

## 012: Find Commands Named ...

This command tells the controller to find all of the commands that have the name you specify. Normally

it will only find one command, but if you have several commands with the same name, it will list them-

all.

<012> y..y

## Parameters:

- -- 012 is the default command name.
- -- Y..Y is the command name with default command name of 000-999

Voice Response: The voice response is "y..y is <cmd number>, <cmd number>..." or "y..y is not used"-

if

there are no commands that have that name.

# Blocking Execution from Certain Ports

## Purpose of these commands:

The following two commands allow you to mark (or unmark) certain commands so that they can not be

executed from certain ports. You might want to use them to make it so your autopatch can not be accessed from the link ports. If you are using one of the ports as a control port, you could make all of

the commands in the controller so they could only be executed from that control port. You could call

these commands from the scheduler to disable some or all of the commands at night. This adds a lot of

security to your controller.

#### Caution:

Because these commands can keep you from executing commands, they can lock you out of your own

controller. If you have a terminal or computer hooked up to the serial port, these commands can not lock

you out, so you don't have to worry about it. Also, you can always re-initialize the controller (see Appendix D), but that erases all of your programming and you have to be at the site to do it. In other

words, be careful what commands you block and what ports you block their execution from. If you don't

want to use these functions and you want to erase their names so that they can not be entered accidentally, enter the following commands:

- -Command 010 130 D or unkey or <Enter>
- -Command 010 131 D or unkey or <Enter>

These commands erase the names of command numbers 130 and 131 so that they can not be executed

without renaming them to a valid name.

If you think you have locked yourself out, execute the following command from every port you can get

touch tones to, or from the serial port. If they are executed they will allow access to every command

from every port and the reverse autopatch.

- -Command 131 x 000 999 D or unkey or <Enter>
  - ---- x is the port number you are trying to restore access to

## 130: Block Command Execution From Port

This command allows you to block execution of a command or a range of commands by a port. Before

using it, please read the cautions on the previous page.

<130> ccc

Recall which ports are blocked from executing this command

<130> pp ccc

Block execution for a single command

<130> pp ccc ddd

Block execution for a range of commands

## Parameters:

- -- 130 is the default command name.
- -- pp is the port to block access by (use '0\*' for the current port, see Appendix L)
- -- CCC is the first command number to block
- -- DDD is the last command number in the range of commands to block

## 131: Allow Command Execution From Port

This command allows you to reverse the effects of Command 130 and allow the specified port to execute.

a command or range of commands again. This command is not dangerous - it can not lock you out of

your own controller.

<131> ccc

Recall which ports are blocked from executing this command

<131> pp ccc

Allow execution for a single command

<131> pp ccc ddd Allow execution for a range of commands

# Parameters:

- -- 131 is the default command name.
- -- P is the port to allow access by (use '0\*' for the current port, see Appendix L)
- -- CCC is the first command number to allow
- -- DDD is the last command number in the range of commands to allow

# Chapter 6: CW, DTMF, Voice and DVR Messages

This chapter deals with all of the different types of messages that can be sent from the controller: CW,

DTMF, synthesized voice and real voice from the digital voice recorder.

- <u>u</u> Sending of CW Messages
  - -- CW speed and tone control
- <u>⊸ù</u> DTMF regeneration
  - -- Regeneration parameters
- <u>u</u> Send a Voice message
- -<u>u</u> Play, Record and Erase a Digital Voice Recorder message
- $-\underline{\dot{\mathbf{u}}}$  Generate one and two tone sequences
- <u>u</u> DTMF Keypad test

The controller normally figures out which transmitters each message should go to. Responses to commands go to the port that executed the command, IDs go to the port that needs them, and courtesy

beeps go to all of the repeaters that could hear the audio from the receiver that caused the ID. Almost all

of these defaults can be overridden by the user, if you so desire. For more information about how the

messages are routed and how you can change the default routing, see Chapter 16 and Appendix A.

# 030: Send a CW Message

This command allows you to send a CW message. It will be sent to the ports that are in the audio

# routing

variable at the time this command is executed (for more info, see Appendix A). The messagewill be sent

\_at the speed and frequency that has been set up for the specific port with 042 and 043.

<030> cc..cc

# Parameters:

-- 030 is the default command name.

CC is the CW data, two digits per character

CW

XX

•

CW

XX

<del>CW</del><u>C</u>

W

 $\overline{\overline{X}}X$ 

. CW

XX

CW XX

0

00

A

10

K

20

.

U 30

. SPACE 40

1 01

. B 11

. L 21

. V

31

. PAUSE

41

2 02

. C 12

. M

22

. W

32

3 03

. D 13

N 23

. X 33

4 04

. E 14

. O 24

. Y 34

5 05 . F 15 . P 25

. Z 35

6 06

G 16

. Q 26 . / 36

7 07 . H 17

. R 27 . 0 37

8 08 . I 18

. S 28

. ? 38

```
9
09
.
J
19
.
T
29
.
AR
39
```

# Notes:

 $-\underline{\underline{\dot{u}}}$  This table is duplicated in Appendix C for ease of reference.

# 118: Send a Morse Code Message

This command allows you to send a morse code message.

# Example:

118 KC7HXB/R — Sends the string "KC7HXB/R" via morse code.—

## 031: Send a DTMF Sequence

This command allows you to send DTMF tones. For each DTMF digit sent, two digits must be entered

(that allows special characters like pause and the force-execution digit (see command 078) to be sent).

They will be sent to the ports that are in the audio routing variable at the time this command is executed

(for more info, see Appendix A). See Command 044 to set up the duration of the tones and pauses

between tones. See command 069 (below) for an alternate way to send DTMF tones.

<031> DD..DD

#### Parameters:

- -- 031 is the default command name.
- -- DD is the DTMF data (See Below)

### Number

**DTMF** Digit

00

0

01

1

02

2

03

3

04

4

5

6

7

8

9

A

В

C

D

\*

#

<Pause>

### Example:

-Want to send the DTMF data '0 0 0 1 1 D'

<031> 00 00 00 01 01 13 D or unkey or <Enter>

### 069: Send a DTMF To Specified Transmitter

This command allows you to send DTMF tones to a specified transmitter. The digits are sent as entered,

with one DTMF digit sent for each DTMF digit entered (because of that, the force-execution digit (see

command 078) cannot be sent with this command - use command 031 if that is necessary). See Command 044 to set up the duration of the tones and pauses between tones.

<069> tt D..D

#### Parameters:

- -- 069 is the default command name.
- -- tt is the transmitter number the DTMF digits should be sent to (use '0\*' for the current port, see
  - -Appendix L)
  - -- D..D are the DTMF digits to be sent.

## Example:

-Send DTMF "026" out transmitter 2:

<069> tt 026 D or unkey or <Enter>

### Example #2:

- -Make a macro to send user-entered DTMF digits out transmitter 2:
  - -010 600 ABC; name macro "ABC"
  - -067 600 01 1; allow macro to take data (see command 067)
  - -055 600; make sure macro is empty
  - -056 600 069 2; user-entered data will be appended here
- -Now entering "ABC 026" will cause DTMF "026" to be generated out transmitter 2.

### Example #3:

-Same as Example #2, but send a 'D' after the user-entered digits (if 'D' is the force-execution digit

-for whatever is listening to that transmitter, it will make the command execute right away).

-Add the following onto the macro started in Example #2:

-056 600 037 2; send the following data out TX 2

-056 600 031 13; send DTMF 'D'

#### Notes:

—Remember that this command cannot be used to send the force execution digit (usually 'D'\_D') of the

-the port that is entering the command because as soon as that digit is pressed, the command will be

-<u>be</u> executed. Example #3 above shows one way to deal with this. See command 078 for more –information about the force-execution digit.

—If this command is entered from the serial port, any invalid DTMF digit (anything but 0..9, A..D,

-\* and #) will be sent as a pause (and "Debug code 38" will be output on the serial port). Spaces

-will not have any effect, as they are always stripped out of commands entered from the serial port

-before the controller executes them.

## 066: Send a Voice Message Using English Words

This command is a more convenient alternative to commands 036, 063 and 064 when entering voice

messages using a computer. It allows you to type voice messages in English rather than looking up word

numbers (in Appendix C). It is not useful when programming using a radio with a DTMF pad, as you

can't directly enter the whole alphabet using DTMF.

066 "door open" 066 "[polite] door open" 066 "[polite:CCC] door open"

<u>To make the controller speak a message using command 066, just enter the command number, then the</u>

message surrounded in double-quotes (without the quotes, the controller will remove the spaces from the

message). The controller will look for each word in its library (see Appendix C for a list of

words), and

speak it if it is found. If the word is not found, the controller will spell it (this works well for callsigns).

Note that if you forget the quotes, the controller will skip the spaces, run all of the words together into

one long string, and will likely spell the whole message. This format corresponds with how command

036 generates voice messages.

<u>If the special word "[polite]" (entered with the square brackets) is found in the message, the</u> remainder of

the message will be spoken "politely", that is the controller will stop speaking and discard the remainder

of the message if someone keys up a connected receiver. This is useful for non-essential announcement

messages, and corresponds with how command 063 works.

It is also possible to use this command to speak a polite message that if interrupted, will do something

else. This is commonly used to speak ID messages which if interrupted will cause a CW ID to be sent.

This corresponds with how command 064 works.

036: Send a Voice Message

This command allows you to send a voice message out of the radio ports on the controller. This is handy

for building voice messages for macro sequences, sending voice IDs, etc. Which ports will send the

message is determined by the current audio routing variable at the time the command is executed (see

Appendix A).

<036> vvv..vvv

#### Parameters:

- -- 036 is the default command name.
- -- VVV is the Voice word to be spoken
  - --- See Appendix B for voice word numbers

### Notes: i

If you want the voice message to stop if someone keys up in the middle of the message (a polite voice message), see commands 063 and 064. These commands are often used for IDs.

Command 066 may be a more convenient alternative to this command if you are entering

\_\_\_\_0663: Send a Polite Voice Message Using English Words

#### Text Moved Here: 1

This command is identical to 036 except that audio from receivers is given priority over the voice message. If a receiver that is on the same port as, or is connected to, any transmitter that is sending the

voice message keys up, the voice message will be discarded so you can hear the receiver instead. In-

other

words, if someone is talking, the controller won't interrupt (it is "polite). If someone interrupts the

controller (keys up while it is speaking), it will finish the word it is currently speaking and then throw-

the

rest of the message away. This is commonly used for speaking scheduled messages, such as reading-

the

\_time at the top of every hour. It could also be used for IDs, but if you want a CW ID to be sent when-

the

\_voice ID is interrupted, use command 064 instead.

<063> vvv..vvv

#### Parameters:

- - 063 is the default command name.

#### End Of Moved Text

This command allows you to send a voice message out of the radio ports on the controller, just like

command 036 does. The difference is that you have to look up word numbers to use command 036.

while this command lets you just type in the words in English, with underscores between the words. If

you enter a word that isn't in the controller's voice library, it will spell it. Since DTMF keypads only have

the letters A..D (if that), this command is only useful when working from the serial port. There is no

polite version of this command (see commands 063 and 064).

### <066> w..w [polite][:mac]

#### Paramete rs:

- 066 is the default command name.
- <u>- VVV..VVV is a list of</u> <u>- w..w are the synthesized voice</u> words to be spoken, in English, with underscores between words
- "polite" is an option to send the message politely. this field is optional, and if omitted, the
- message is send impolitely by default.
- ":mac" is a second optional macro number. Allows for substitution of polite macro with another.

#### Example:

- 066 this is a test message sends message this is a test message impolitely.
- 066 this\_is\_a\_test\_message [polite: 360]- sends message this\_is\_a\_test\_message politely, via macro 360.

### **Sending DVR-1 Messages:**

- If you have the optional DVR-1 (Digital Voice Recorder), you can include DVR tracks in the messages you
- generate with this command. Simply put "DVRxxx" where 'xxx' is a track number wherever you want the
- DVR track to go in the message. For example: "066
- this is a test pause DVR123 repeater DVR32"
- will make the synthesized voice speak "This is a test", then the DVR will play track 123, then the
- synthesized voice will speak "Repeater", and finally the DVR will play track 32.
  - (See Appendix B for word numbers)

## Example:

- <u>ù Speak the time only if it won't play over someone talking: "063 810". Note that word 810 is a special word that speaks the current time. To put that command into macro 600, enter: "053 600</u>
- <u>063 810". You can then call macro 600 from a macro, the scheduler, a tail message, etc. to speak</u>
- the time politely.

#### Notes:

- <u>ù</u> The autopatch will not interrupt polite voice messages. In other words, a polite voice message that is spoken to the autopatch port will not be interrupted by the autopatch "receiver," even though it is always active during a call.
- <u>ù Command 066 may be a more convenient alternative to this command if you are entering messages using a computer (rather than a DTMF pad).</u>

### 064: Send a Polite Voice Msg, If Interrupted Execute Cmd

This command is identical to Command 063 except that if a receiver is active and causes the voice

message to be thrown away, it will cause another command to be executed. This is used to make a voice

<u>ID that gets interrupted cause a CW ID to be sent instead (see the example below).</u>

### <064> ccc vvv..vvv

#### Parameters:

- 064 is the default command name.
- CCC is the command number to execute if the message is interrupted
- VVV is the Voice word to be spoken
  - -- See Appendix B for voice word numbers

### Example:

You want to program a polite voice pending ID message for port 1 that will send a CW ID if it is

<u>interrupted</u>. Since the first pending ID for port 1 is sent by macro 332, we will program that macro to

execute command 064. We will tell command 064 to either speak the voice ID, or if it is interrupted, to

execute the impolite ID (command number 380) instead. We will make the voice ID say the words "I D"

with are word numbers 039 and 034 (you would want to change this - see Appendix B for other word

numbers):

\_\_\_\_\_053 332 064 380 039 034 unkey, D or <Enter>

The above string uses command 053 to program macro 332 to execute command number 064. When

<u>command 064 executes</u>, it checks for receiver activity. If the receiver is active, it executes command

380 (the impolite ID). Otherwise it speaks the voice message "ID". See Chapter 11 for more information about programming IDs.

#### Notes:

- <u>ù The autopatch will not interrupt polite voice messages. In other words, a polite voice message</u>
  <u>that is spoken to the autopatch port will not be interrupted by the autopatch "receiver," even</u>
  <u>though it is always active during a call.</u>
- <u>ù Command 066 may be a more convenient alternative to this command if you are entering</u>

messages using a computer (rather than a DTMF pad).

### 040: Send One or Two Tone Sequence

This command causes a tone "sequence" to be sent out the ports specified by the routing variable (see-

Appendix A

for information about the routing variable). A "sequence" is composed of one or two toneswhich are generated

simultaneously for a specified duration and followed by a specified pause. Most-courtesy beeps use only one tone

at a time, although many have several tones in sequence. This type ofcourtesy beep would be generated by calling

this command several times from a macro, sending a one-toneone-

tone chord each time (see examples on the following

\_pages). DTMF digits and dial tone are familiar-

two-tone combinations, and can be easily generated using this command.

Sequence

Command Type

Single Tone

<040> ttt ppp ffff

Single Tone

<040> tttt pppp fffff

Dual Tone

<040> ttt ppp ffff gggg

**Dual Tone** 

<040> tttt pppp ffff gggg

#### Parameters:

- TTT or TTTT is a number representing the duration of the tone in 10mS increments. If you use four
- \_ digits for the
- duration of the tone, you must also use four digits for the duration of the pause. <del>The tone duration is</del>
- limited to 60 seconds (6000).

- PPP or PPPP is a number representing the duration of the pause to follow the tone in 10mS increments. If you
- use four digits for the duration of the tone, you must also use four digits for the duration of the pause. The
- pause
- The tone duration is limited to 60 seconds (6000).
- <u>- PPP or PPPP is a number representing the duration of the pause to follow the tone in 10mS increments.</u>
- <u>If you use four digits for the duration of the tone, you must also use four digits for the duration</u> of

the pause. The pause duration is limited to 60 seconds (6000).

- FFFF is the frequency of the primary tone in hertz. All four digits must be entered.
- GGGG is the frequency of the secondary tone in hertz. All four digits must be entered. It is only used when you

when you want both tones active at the same time, like a DTMF tone. If you want a beep at one

- \_ frequency then a
- beep at another frequency, call this command twice from a macro and only
- \_ specify one frequency each
- time.

## Note about Courtesy Beeps

The RLC-DSP404 courtesy beeps are not simply a programmable beep. When it is time to send a-

courtesy beep,

the RLC-DSP404 decides which ports should receive the courtesy beep, sets the audiorouting variable to those

\_ports (see Appendix A), and calls that port's courtesy beep automatic macro-(see Chapter 8). This makes it

\_possible for you to make your courtesy beep do a lot more than just beep. -

If you call command 040 (send One,

Two or Three Tone Chord), it will beep. If you call 040 more than-

once in the courtesy beep macro, it will beep

more than once (examples below). If you call 036 (speak-

voice message), you will get a voice message for your

\_courtesy beep. If you call 030, it will send CW. -

If you call 031, it will send DTMF. If you really want to, you can do several of the above.

Since most people want a sequence of beeps for their courtesy beep, we will provide some examples. -

Note that to

get a single-beep courtesy beep, you just call 040 once from the courtesy beep macro. Toget a three tone sequence,

you call 040 three times within that macro. Each time command 040 is called,

it can send one or two simultaneous

\_tone frequencies. Below are some widely used courtesy beep-sequences.

## Examples:

-All tone frequencies are in hertz. All times are in milliseconds.

Sequence Name

Tone 1

Tone 2

Duration

Pause

Command to Program Beep

Replace "mmm" with macro num

1 - Bumble Bee

0330

N/A

```
100mS
0mS
053 mmm 040 010 000 0330
0500
N/A
100mS
0mS
056 mmm 040 010 000 0500
....
0660
N/A
100mS
0mS
056 mmm 040 010 000 0660
2 - Yellow Jacket
0330
N/A
50mS
0mS
053 mmm 040 005 000 0330
....
0500
N/A
50mS
0mS
056 mmm 040 005 000 0500
0660
N/A
50mS
0mS
056 mmm 040 005 000 0660
```

```
3 - Shooting Star
0800
N/A
100mS
0mS
053 mmm 040 010 000 0800
....
0800
N/A
100mS
0mS
056 mmm 040 010 000 0800
••••
0540
N/A
100mS
0mS
056 mmm 040 010 000 0540
4 - Comet
0500
N/A
100mS
0mS
053 mmm 040 010 000 0500
....
0500
N/A
100mS
0mS
056 mmm 040 010 000 0500
0750
N/A
100mS
0mS
```

## 056 mmm 040 010 000 0750

```
5 - Stardust
0750
N/A
120mS
0mS
053 mmm 040 012 000 0750
0880
N/A
80mS
0mS
056 mmm 040 008 000 0880
••••
1200
0880
80mS
0mS
056 mmm 040 008 000 1200 0880
6 - Duncecap
0440
0500
200mS
0mS
053 mmm 040 020 000 0440 0500
....
0440
0350
200mS
0mS
056 mmm 040 020 000 0440 0350
```

7 - Dial Tone 0440 0350 100mS 100mS 053 mmm 040 010 010 0440 0350

8 - Low-High Beep 0500 N/A 100mS 0mS 053 mmm 040 010 000 0500

.... 0665 N/A 100mS 0mS 056 mmm 040 010 000 0665

9 - High-Low Beep 0665 N/A 100mS 0mS 053 mmm 040 010 000 0665

.... 0500 N/A 100mS 0mS 056 mmm 040 010 000 0500

10 - Cover Tone 0440 N/A 200mS 300mS 053 mmm 040 020 030 0440 11 - Audible Ring

Tone

0440

0480

400mS

400mS

053 mmm 040 040 040 0440 0480

### Example:

- -I want port 1's courtesy beep to be number 5 as listed above.
- 1) Locate the courtesy beep macro for port 1 in Chapter 8.
  - -- 256 is Port 1's courtesy beep macro
- 2) Command 055 erases the old contents of a macro
  - -055 256 D or unkey or <Enter>
- 3) Command 056 appends a command onto the end of a macro we will do the first tone -056 256 040 012 000 0750 D or unkey or <Enter>
  - -012 is the duration of the beep in 10 millisecond increments
  - -000 is the duration of the pause in 10 millisecond increments
  - -0750 is the frequency of the tone in hertz
- 4) Command 056 appends a command onto the end of a macro the second tone
  - -056 256 040 008 000 1200 D or unkey or <Enter>
    - -008 is the duration of the beep in 10 millisecond increments
    - -000 is the duration of the pause in 10 millisecond increments
    - -1200 is the frequency of the tone in hertz
- 5) Command 056 appends a command onto the end of a macro the third beep
  - -- It is a dual tone beep
  - -056 256 040 008 000 1200 0880 D or unkey or <Enter>
    - -008 is the duration of the beep in 10 millisecond increments
    - -000 is the duration of the pause in 10 millisecond increments
    - -1200 is the frequency of one tone in hertz
    - -0880 is the frequency of the other tone in hertz
- 6) Now when port 1's courtesy beep needs to be sent, the courtesy beep macro will call Command 040
  - -three times to generate the three beeps.

## 041: Set/Recall Courtesy Beep Settings

This command allows you control several options for courtesy beeps. In most cases the default values

will work fine, so you may not need to use this command at all.

One thing this command allows you to do is to turn to set the conditions under which courtesy beeps on or off for a selected transmitter.

Normally courtesy beeps are sent out of repeater transmitters and not out of link transmitters, so if that is

what you want, you won't have to change anything. If you want a courtesy beep out of a link transmitter

or you want to turn courtesy beeps off for a repeater transmitter, then you should use this command.

If you want a particular receiver to quit generating courtesy beeps (to be sent out any transmitter), erase

will be sent to the specified

<u>transmitter</u>, or <u>disable them completely</u>. <u>Note that this command deals with transmitters</u>; <u>if you want to</u>

<u>disable the courtesy beep for a receiver, just erase</u> the courtesy beep macro for that receiver (see Chapter 8 for more details about the courtesy beep macros).

### **Normally**

8) using command 055.

The default is to send courtesy beeps only to transmitters that are on ports configured as repeaters, not

<u>links or remote bases (see Chapter 2).</u> By <u>default,</u> courtesy beeps are <u>not sent</u><u>disabled during</u> <u>autopatch calls</u>

(see chapter 13) and when using the autopatch or HF remote base. This command allows you to change that.

Normally the <u>interactive HF remote base (see Chapter 15)</u>, although this <u>command will allow you to override either or both of those settings.</u>

The final option may help discourage "tailgating" (keying up before the courtesy beep).

Normally the

time out timers are get reset each time immediately when a receiver unkeys. This command lets you change that,

so they aren't If, however, this option is set to 1 (rather

<u>than 0)</u>, the time out timers won't be reset until the courtesy beep for that receiver is sent. This setting may help discourage

"tailgating."

## <041> pp e

Enable/disablewill increase the chance of a "tailgater" getting cut off by the time out timer expiring.

## <041> pp 0

Disable all courtesy beeps for TX pp

## <041> pp 1

<u>Enable</u> courtesy beeps <u>for TX pp only if it is a repeater (default setting)</u>

### <041> pp 2

Enable courtesy beeps for TX pp regardless of whether it is a repeater or link (default setting)

## <041> pp e a

Enable/disable, autopatch As before, plus control whether courtesy beeps are sent during autopatch calls. Set 'a' to 0 to disable (default), 1 to enable.

### <041> pp e a h

Enable/disable, autopatch, HFAs before, plus control whether courtesy beeps are sent while using the interactive HF mode. Set 'h' to 0 to disable (default), 1 to enable.

## <041> pp e a h t

Enable/disable, autopatch, HF, TOTAs before, plus control when the time out timers get reset. Set 't'

to 0 to reset them immediately when a receiver goes inactive (default) or to 1 to wait until the courtesy beep.

#### Parameters:

- -- 041 is the default command name.
- -- pp is the selected port (01..12)
- -- E sets the conditions under which courtesy beeps are enabled

Description

0

Disable courtesy beeps for this transmitter

1

Enable courtesy beeps for this transmitter only if it is a repeater (the default)

2

Enable courtesy beeps for this transmitter, even if it is a link

- A 0 to disable courtesy beeps during autopatch calls (the default), 1 to enable them for this \_ transmitter.
- H 0 to disable courtesy beeps while using HF remote base (the default), 1 to enable them for this
  - -transmitter.
- T 0 to reset the time out timer for this receiver when the receiver drops (the default), 1 to wait until
- -the courtesy beep. Setting it to wait for the courtesy beep will encourage users to not to reply -until the courtesy beep has been sent to avoid being cut off by the time out timer. Once a \_receiver
- has timed out, even a momentary unkey will clear the timed-out condition (since no = courtesy beep
- is sent at that time, no delay is necessary).

## 042: Set CW Speed for a Selected Port

This command allows you to set up the CW systems speed in words per minute. The maximum CW

speed the FCC allows for identification is 20 WPM, but the controller will handle 05..50 words per

minute.

<042> pp-

Parameters:

- -- 042 is the default command name.
- -- pp is the selected port (01..12)
- -- SS is the words per minute send value

#### Default:

-All ports default to 20 words per minute

#### 043: Set CW 2-Tone Frequencies for a Selected Port

This command allows you to set up the CW tone frequencies used by the CW system.

<043> pp aaaa Set CW to a single tone

<043> pp aaaabbbb Set CW to dual tones

#### Parameters:

- -- 043 is the default command name.
- -- pp is the selected port (01..12)
- -- AAAA is the first tone frequency (0000..9999) Hz
- -- BBBB is the second tone frequency (0000..9999) Hz

#### Default:

- -Tone 1 is set to 1064 Hz.
- -Tone 2 is set to 0000 Hz.

#### Notes:

—You should not set "aaaa" and "bbbb" to the same value or they will cause the output of the two

-tone generators to be superimposed. Depending on the phase shift between them, the amplitude

-may be louder or software than a single tone, and may change at seemingly random times.

### 044: Set Up DTMF Regenerate Parameters

This command allows you to set up the DTMF regenerate parameters for each attached port. You may

need to use this command to slow your DTMF tones down if a scanning DTMF decoder is on

any of the

attached systems that you want the RLC-DSP404 to control.

<044> pp aaaa-bbbb

#### Parameters:

- -- 044 is the default command name.
- -- pp is the selected port (01..12)
- -- AAAA is the duration of the DTMF sequence in 10mS steps (0000..9999)
- -- BBBB is the pause between DTMF digits in 10mS steps (0000..9999)

#### Default:

-Both duration and pause set to 100mS

051: Start Dial-Tone

This command allows you to generate a dial tone down for a given time down the port that requested this

command. This command is used to give you an indication that access to the controller has been accomplished. This is not pre-access, simply dial tone generation. The dial tone is routed to the port-

that

\_DTMF requested the command. This command is used in conjunction with the pre-access macros.

< 051>

#### Parameters:

- 051 is the default command name.

Notes:

How to cancel the dial tone once it is running:

- 1) You can cancel the dial tone with a DTMF digit on the port dial tone is present.
- 2) When the dial tone timer expires (See Command 020)

### Text Was Moved From Here: 1

- VVV..VVV is a list of synthesized voice words to be spoken
- (See Appendix B for word numbers)

### Example:

- Speak the time only if it won't play over someone talking: "063-810". Note that word 810 is a special word that speaks the current time. To put that command into macro 600, enter: "053-600
- 063 810". You can then call macro 600 from a macro, the scheduler, a tail message, etc. to speak
- the time politely.

### Notes:

- The autopatch will not interrupt polite voice messages. In other words, a polite voice message
- that is spoken to the autopatch port will not be interrupted by the autopatch "receiver," even
- though it is always active during a call.

— 064: Send a Polite Voice Msg, If Interrupted Execute Cmd

This command is identical to Command 063 except that if a receiver is active and causes the voice

message to be thrown away, it will cause another command to be executed. This is used to make a voice

ID that gets interrupted cause a CW ID to be sent instead (see the example below).

<064> ccc vvv..vvv

#### Parameters:

- 064 is the default command name.
- CCC is the command number to execute if the message is interrupted
- VVV is the Voice word to be spoken
- -- See Appendix B for voice word numbers

### Example:

You want to program a polite voice pending ID message for port 1 that will send a CW ID if it is

interrupted. Since the first pending ID for port 1 is sent by macro 326, we will program that macro to

execute command 064. We will tell command 064 to either speak the voice ID, or if it is interrupted, to

execute the impolite ID (command number 350) instead. We will make the voice ID say the words "I D"

with are word numbers 039 and 034 (you would want to change this - see Appendix B for other word

numbers):

- 053 226 064 250 039 034 unkey, D or <Enter>

The above string uses command 053 to program macro 326 to execute command number 064. When

command 064 executes, it checks for receiver activity. If the receiver is active, it executes command 350

(the impolite ID). Otherwise it speaks the voice message "ID". See Chapter 11 for more information

about programming IDs.

#### Notes:

- The autopatch will not interrupt polite voice messages. In other words, a polite voice message
- that is spoken to the autopatch port will not be interrupted by the autopatch "receiver," even
- though it is always active during a call.

# 163: Keypad Test

This command will read back whatever digits are entered. This allows you to check your DTMF keypad

and make sure that the controller is accepting all of the digits.

The '\*' character will be spoken as "Star" and '#' will be "Pound".

<163> d..d

### Parameters:

- -- 163 is the default command name
- -- D..D are the digits to be read back

## The DVR Digital Voice Recorder Functions

#### What the DVR is:

The DVR is an optional device that allows you to record sounds, store them in memory and play them at

any time. It

On most other repeater controllers, a digital voice recorder is an option, if available at all. The DSP404

has a built in DVR with many advanced features. Messages can be stored temporarily in RAM or

permanently in flash memory using an optional SD memory card or USB flash drive, which provide

<u>virtually unlimited storage</u>. The <u>DVR</u> can be used to personalize your controller by recording any-

message or sounds that you want

and playing them back for ID messages or in place of most other-

synthesized voice messages. Some of

these messages are played in response to commands that you or the users enter; ed by DTMF, while others are played at

<u>certain timesautomatically</u>, such as <u>for an ID messages</u>. Both types of messages <u>will be are</u> described below.

#### **DVR Tracks**:

All DVR recordings are stored in numbered "tracks." Certain tracks have special purposes and are

played automatically at certain times. Others are available for you to use in any way you wish. The

length of each track is limited only by available memory. Each track uses only as much storage space as

is actually needed.

The first  $\frac{250900}{1}$  tracks (numbered 000..249) have no predetermined use - you may use them for ID

messages, command responses (by calling Command 173 from a macro), or anything else you can think

of. Tracks 250..260 or so are used for prompting. They are discussed further in the section below titled

"Recording the Prompting Tracks". The remaining tracks are not directly accessible by number. They

are used to support the mailbox features and are automatically accessed by the mailbox commands.

#### Public Mailboxes:

The DVR uses special internal tracks to provide two types of mailboxes: public and private. Both types

allow you to leave messages for other repeater users. You can leave a message in a public mailbox by

simply entering the "Leave Public Mail" command (after setting up the prompting tracks as described

below). The DVR will then ask you who the mail is for. You key up and say their name or call sign.

The DVR will then ask you to record your message. When you are through, it will tell you that your

message has been stored. You can check if there is mail for you by simply entering the "Check Public

Mail" command. It will list the names or call signs of the people that there is mail for, or will tell you-

that

there is no mail. If there is mail for you, you can listen to your message by entering the "Retrieve-

Public

\_Mail" command. Up to nine public mailboxes can be in use at a time.

#### Private Mailboxes:

Private mailboxes allow you to leave voice mail in someone's private mailbox. To do this you have to

know the number of their mailbox. There are 500 private mailboxes, so everyone in your club can have

their own. Each private mailbox can hold up to five messages at a time. You can retrieve or delete the

mail in your own mailbox without affecting anyone else's mailbox.

#### **Audio Quality/Recording Time:**

The audio quality of tracks played with the DVR is nearly identical to the original. You will probably not

be able to distinguish between a recording and someone talking "live." Technically, the DVR samples

and plays audio at 8KHz with 8 bit resolution (256 voltage levels). This uses 64000 bits per second,

which is 8000 bytes per second. At this rate, each megabyte of memory will hold 131 seconds of recorded audio. A small portion of the memory is used for other purposes, so the actual amount of

storage will be slightly less than 131 seconds per megabyte. In a future software version, it may be

possible to record with lower quality to extend the recording time.

The Audio Check Command:

Before executing any DVR commands on the RLC-DSP404 you should enter Command 182 1 D or

unkey to tell the RLC-DSP404 that the DVR is installed. The controller will respond by saying "one". If

you do not do this, some of the commands will work, but others will not.

The easiest way to test the DVR is to execute the "Audio Check" command. To use it, simply key your

radio and enter "Command 170", then unkey. Key up again and say something. When you unkey, the

DVR will play whatever you said back to you, then erase it. If this command works, you have the DVR

connected and working. You can execute this command as many times as you want to without harm and

without wearing anything out. It can also be used to help you know if your signal is noisy into the

repeater; just use this command to record a test message and you can listen to your own audio. Yet

another use for this command is to find out how much record time (memory) is still available. To do-

this,

start recording and count off the minutes and seconds you have been recording. When the DVR's

memory is full, it will stop recording. When you unkey and the message is played back, you will hear

yourself count as long as the DVR was able to record before it ran out of memory (this could take a long

time if the memory is not almost full - if it takes too long, the max record length timer could stop it-

before

the memory is full).

### Recording DVR Tracks:

Before recording a track, you should make sure it is empty. If a track has already been recorded, you-

will

not be able to record it again until you erase it. All tracks are empty when the DVR is powered up. -

To

record a track using COR to start and stop the recording, you should enter the record command-followed

\_by the track number, "171 TTT" (where TTT is the track number), then unkey (to tell the controller to

execute that command and get ready to record). Then key up and start speaking your-message. When

\_you are finished, simply unkey. The DVR will automatically delete a fraction of a-second of the

\_beginning and end of your message to get rid of any noise caused by keying or unkeying.

If you wish to record a track without using COR, such as from the reverse autopatch in programming

mode, you can use a DTMF digit to start and stop the recording. For example, to record track 0, you

could enter "Command 171 000 D". As soon as you release the 'D', the DVR will begin recording.

When you are finished speaking your message, press any DTMF digit to stop the recording. The DVR

will automatically delete a fraction of a second at the end of your message to make sure that the sound of

the DTMF digit is completely erased. Note that some phones (especially ones that can be used as speaker phones) mute about the first « second of each phrase you say; this makes recording nice DVR

messages with them very difficult.

After you have recorded the prompting tracks (described later), you can use a more friendly version of

the record command. Command 172 performs the same function as Command 171, but plays a DVR

track that says something like "Please record your message now" after you enter the command and unkey

(or press 'D').

When recording using either the prompted or non-prompted command, you must start recording within

10 seconds of entering the record command and unkeying or you will have to enter the command again.

This is so a record command can't be entered and end up recording someone that keys up an hour later

not knowing that the record command was the last thing entered. The default 10 second window can be

changed with Command 020; it is the "DVR Start Recording Timer".

The only limit on the length of message that can be recorded is the amount of memory that is still available. To keep people from leaving long mailbox messages, the DVR record length limit timer-

(timer

164) can be set to limit the length of message that can be left. It defaults to 30 seconds, but can be

lengthened or shortened as desired using Command 020. You may also need to lengthen your time out

timer to record very long messages. Note that because some of the audio switching circuits are shared

between the voice synthesizer and DVR, that only one may be playing at a time. If you play an exceptionally long DVR message, it may postpone the sending of synthesized voice IDs and other

messages. For this reason, you should keep your DVR messages relatively short.

### Playing Messages:

There are many things that can cause a DVR message to be played. For example, Command 170 records

a message, then plays it back automatically. Command 172 plays a message to tell you to start recording

a new message, then lets you record it. To simply play a message that has already been recorded, you

can use Command 173. It works a lot like Command 036 does with the synthesized voice, playing the

messages you request. Command 173 can be called from any macro to provide DVR IDs, courtesy

beeps, autopatch off messages, etc.

### Erasing Tracks:

There are several reasons to erase tracks. Tracks that have been recorded before must be erased before

they can be recorded again. Tracks that are no longer being used should be erased to make more storage

space available for new messages. Once a track has been erased, there is no way to recover it, so be

careful when deleting tracks, especially when deleting a whole range at once. Deleting tracks can take

several seconds, so don't be surprised if it takes a while before you hear the message erased message. If

you are erasing a single message, the controller will continue to run normally while it waits for the DVR

to finish deleting the message and send "message erased". If you delete a range of DVR messages with

one command, the controller will stop everything else it is doing while it tells the DVR to delete each of

the tracks. When it is finished, the DVR will speak "message erased" to let you know it is finished.

### Recording the Prompting Tracks:

There are several special messages that are played automatically at certain times. They should be recorded before attempting to use the prompted record command or the mailboxes. The messages-

shown

\_below are only suggestions; you can record them to say anything you want them to. To record-them,

enter the commands and speak the messages shown below. For more information about recording-

tracks.

\_see the "Recording Tracks" section above.

Command Enter 171 250 D or 900", unkey, then key and say, "Please rRecord your message now"

Command 171 251 D or unkey "Your message is stored"

Command 171 252 D or unkey Enter "171 901", unkey, then key and say, "Message stored".

After this and the following

commands, the DVR should respond "message stored".

Enter "171 902", unkey, then key and say, "Message erased"

(track 253 is not used)

Command Enter "171 254 D or 903", unkey, then key and say, "Who is your message for?"

Command Enter "171 255 D or 904", unkey, then key and say, "There are no messages."

Command Enter "171 256 D or 905", unkey, then key and say, "There is mail for..."

If you want to see how your messages sound, you can play most of them by entering. Command 173 250

900 < unkey> (for track 250). Message 256 can not be checked this way, so record it and don't worry about

checking it until you try out Command 175..178. track 900).

If you want to erase one of these tracks so you can

\_record it again, enter Command 174 250 <unkey>900 <unkey> (to-

erase track 250900). After recording these messages,

\_the DVR is ready for use. Flip through the manual-

and try all of the commands until you are comfortable

with them. If you want to erase all of your-

messages and start over, you can erase them with Command

174 or you can unplug the DVR and controller for several seconds, then power them back up (and wait

for the DVR to finish its memory test) 174. For an example of how each of the DVR commands can be used, see

http://linkcomm.com/wiki/index.php?title=DSP404\_DVR\_Example..

# Making DVR Messages Polite:

Currently, DVR command 173 is similar to the synthesized voice command 036 in that they are both

impolite (see commands 063 and 064 for more information about "polite" messages). There are no DVR

commands similar to the synthesized voice commands 063 (speak politely) or 064 (speak politely and do

something if interrupted) in this firmware version (they are planned for a future version), but they can be

simulated on the DVR=1 (the big DVR, not the small one) by programming macros similar to those

\_shown<del>\_below</del>

<u>belowDVR</u>. To make polite DVR messages, the DVR<del>-1</del> must be running V1.50 or later firmware;

\_older-

versions of DVR firmware will continue to work but will not be polite and may cause the following

(harmless) message to be printed to the controller's serial port: "DVR is not responding (1), Error sending command to DVR".

```
<u>u</u> Speak polite DVR message (like command 063):
                     ; erase macro 600
 -055600
 -056 600 036 801
                            ; start polite mode
                                   ; play dvr tracks
 -056 600 173 <dvr tracks>
 -056 600 036 802
                            ; stop polite mode
<u>u</u> Speak polite DVR message and do macro 250380 if interrupted (like command 064):
 -055 601
                     ; erase macro
 -056 601 036 801
                            ; start polite mode
 -056 601 173 <dvr tracks ; play dvr tracks
                                  ; stop polite mode, do 250380 if interrupted
 -056 601 036 803 <del>250</del>380
```

# 170: Record and Play Audio Test

This command makes the DVR start recording. When you unkey or press a DTMF digit to stop recording, it automatically plays it back. This is useful for testing the DVR and for checking how your

signal sounds into the repeater. To use this command enter 170 and unkey, then key up and talk or enter

"170 D" and start speaking immediately. When through speaking, unkey and your recording will be

played back immediately. The track is automatically erased after it is played back.

<170>

#### Parameters:

-- 170 is the default command name

# 171: Record DVR Track (non-prompted)

This command makes the DVR start recording a track. To use this command enter Command 171 TTT

D or unkey. Either way, you message will be recorded and stored in track TTT.

<171>t

Record track 0..9

<171>tt

Record track 00..99

<171> ttt

Record track 000..260

Please note that a DVR track that has been recorded before must be erased before it can be recorded

again. This is to avoid accidentally recording over an existing message.

Parameters:

- -- 171 is the default command name
- -- T, TT, TTT is the DVR track number (1..3 digits, track 0..260)

# 172: Record DVR Track (prompted)

This command has the same result as Command 171: it records a DVR track. The difference is that-

after

entering the Command 172 TTT and unkeying, this command plays a special DVR track to tell you-

it is

\_ready to start recording. This is useful because it lets you know that the command has been-executed and

the DVR is ready. After the prompting message is finished, you can key up and start-recording. The

\_disadvantage of this command compared with Command 171 is that you have to waituntil the prompting

message is finished before you can start recording. If you are recording a lot oftracks, it is faster to use

Command 171.

<172>t

Record prompted track t

<172>tt

Record prompted track tt

<172> ttt

Record prompted track ttt

Please note that a DVR track that has been recorded before must be erased before it can be recorded

again. This is to avoid accidentally recording over an existing message.

#### Parameters:

- -- 172 is the default command name
- -- T, TT, TTT is the DVR track number (1..3 digits, track 0..260)

173: Play DVR Tracks

This command makes the DVR start playing the specified track or tracks. They will be heard on the

ports that are in the current audio routing variable (see Appendix A), just like the other commands that

send tones or synthesized voice are. This is the command that you would use in an ID macro to send a

DVR ID.

<173> ttt

Play single track

<173> t..t

Play multiple in-a-row tracks

<173> ttt ttt..ttt

Play multiple separate tracks

#### Parameters:

- -- 173 is the default command name
- -- TTT is a DVR track number. If only one track specified, can enter 1..3 digits. If more than one

-track is specified, must enter groups of three digits.

# 174: Erase DVR Tracks

This command makes the DVR erase the specified track or range of tracks. There are several reasons to

erase tracks. Tracks that have been recorded before must be erased before they can be recorded again.

Tracks that are no longer being used should be erased to make more storage space available for new

messages. Once a track has been erased, there is no way to recover it, so use this command with caution,

especially when erasing a range of tracks.

<174> ttt

Erase single track

<174>t..t

Erase multiple in-a-row tracks

<174> ttt ttt..fff

Erase multiple separate tracks

#### Parameters:

- 174 is the default command name
- TTT is a DVR track number to be erased. If only specify one track can use 1..3 digits.
- FFF (optional). If specified, DVR tracks TTT through FFF will be erased. FFF must be larger than

-TTT.

Note: If the DVR track for "message erased" is not heard, make sure you have entered Command 182 1

D or unkey to set up the DVR and that the "message erased" track has been recorded. You may have to

wait for several seconds after entering the command for the DVR to finish deleting the message and send

"message erased".

### 175: Record Public Mail

This command allows the user to record a message and who it is for and stores it in a public mailbox. It

uses some of the special tracks to prompt the user to record the name or call sign and the message, and to

tell him that the message has been stored. For more information, see the "Public Mailboxes" section at

the beginning of the DVR section.

<175>

#### Parameters:

-- 175 is the default command name

176: Check Public Mailboxes

This command recalls who has mail in the public mailboxes. The DVR will either play the special track

that says, "There is mail for", then the name or call sign for each of the messages that are stored in the

public mailboxes or it will play the special track, "There is no public mail". The names or call signs will

be spoken in the order that the messages were recorded. If you want to check the public mail without the

DVR saying anything if there is no mail, enter "173 256 257".

<176>

#### Parameters:

-- 176 is the default command name

### 177: Retrieve Public Mail

This command allows a user that has mail in a public mailbox to retrieve it. This command is usually

used after checking the public mailboxes with Command 176. When you check the public mailboxes-

with

Command 176, you should keep track of where your name or call sign are in the list of people that-

have

mail. For example, if Command 176 says, "There is mail for Joe, Mary, Bob, Jim", and you are Bob,

\_your mail will be stored in public mailbox #3, because your name is third in the list. To retrieve-your

\_mail, you would enter "Command 177 3 D or unkey".

<177> s

#### Parameters:

- -- 177 is the default command name
- -- s is which mailbox your mail is in (1..9)

178: Erase Public Mail

This command throws away the contents of a public mailbox, the last one that was retrieved. It must be

used only after retrieving a public mailbox message with Command 177. It erases only the last public

mailbox message that was retrieved; all of the others remain unchanged (although they may be moved-

up

to a lower numbered mailbox to avoid leaving gaps).

<178>

## Parameters:

-- 178 is the default command name

# 179: Record Private Mail

This command allows the user to record a message and store it in a private mailbox. You must know the

mailbox number you wish to leave a message in to use this command. Since each user has his own

mailbox, there is no need for you to record his name or call sign as with the public mailboxes.

<179> sss

## Parameters:

- -- 179 is the default command name
- -- SSS is the number of the mailbox to leave the message in

## 180: Retrieve Private Mail

This command allows a user to retrieve the mail that has been left in his private mailbox. If he has no

mail, the special DVR track "You have no mail" will be spoken. If there is more than one message in his

mailbox, all of them will be spoken consecutively.

<180>sss

## Parameters:

- -- 180 is the default command name
- -- SSS is the number of the mailbox get the mail from

# 181: Erase Private Mail

This command throws away the contents of a private mailbox, the last one that was retrieved. It must be

used only after retrieving a private mailbox message with Command 180. It erases all of the messages in

that mailbox, but does not affect any of the other private mailboxes.

<181>

## Parameters:

-- 181 is the default command name

# Chapter 7: Serial Port Commands

This chapter deals with the following topics:

- —ù Information about serial transfers
- $-\underline{\mathbf{u}}$  RS-232 band rates
- $-\underline{\mathbf{u}}$  Other serial port options
- -<u>u</u> Sending serial messages out of the main serial port
- <u>→</u> Sending SPI serial data with the output lines

#### Where the Serial Ports Are:

\_The RLC-DSP404 has a serial port on the motherboard (which is the DB-9 located on the front panel)

that is used for entering commands on the controller. This is called the main serial port. Each radio <del>cardport</del>

<u>connector</u> also has a serial port <u>connections for</u> controlling remote base radios (the top DB-9 connector on revision A radio cards,

combined onto the single DB-9 on revision B and C cards). with RS-232 serial ports (see Chapter 1 for the DIP switches that enable them). There is also a type of serial data ("SPI") that can

be sent with the open collector output lines on the I/O connectors that is usually used for controlling

remote base interfaces (RLC-ICM, Doug Hall RBI-1, or BCD-controlled radios).

## Controlling what Serial Messages are Sent:

This section only refers to the main serial port, since it is the one you use for entering commands and-

that

the controller uses to tell you when there is an error. When the controller is reset (such as when the

power is turned on), it sends a serial message that tells you the controller type, software version, etc. Of

course you will only see this message if you have a computer or serial terminal connected to the main

serial port. If you then type a command on the computer or serial terminal and press enter, the controller

will process the command and print on the screen either what it did (except for a few commands that

don't print anything) or an error message telling you what went wrong.

If you enter a command from a radio using DTMF, the controller normally will not print anything on the

serial screen. It "suppresses" that serial so if you are programming from the serial port at the

same time

someone is entering DTMF commands, the responses to their commands won't confuse you.

keep the responses to commands entered by DTMF from being suppressed by turning serial suppression

off with command 060. This can be handy for figuring out what is going wrong when entering DTMF

commands.

Commands 162 and 169 bypass the check to see if serial is suppressed so they always print. Since you

will normally want serial suppression to be turned on, these commands are useful for sending messages

that you always want to be printed, even if the command to send them is entered from a radio port or

executed by the scheduler or some other internal device.

## The RS-232 Serial Protocol:

Most serial devices (computers, mice, external modems, serial terminals, etc.) use the RS-232 serial

protocol. The main serial port on the RLC-DSP404 is RS-232 compatible. All you need to connect it to

a computer, terminal or modem is the proper cable. The serial ports on the radio cards can be made to be

RS-232 compatible by installing a Dallas DS275 chip into the socket labeled U8 (underneath the tone

level pot). Make sure that there are no jumber blocks on header J5 (right next to U8) when you plug in

the DS275, or you could destroy the chip

<u>Each radio port on the DSP404 also has a RS-232 serial port which can be enabled using DIP switches</u>

near the radio port DB-9 connector (see page 1-2 and following for more information).

## TTL versus RS-232 Signal Levels:

Some devices, like HF remote base radios, require an adapter to convert their serial ports to the signal

levels used for RS-232 (-12 and +12 volts). Without that adapter, they use TTL signal levels (0 and 5

volts). You should never connect a serial port that uses TTL level signals to one that uses RS-232. It is

possible to make the serial ports on the radio cards use TTL level signals by installing jumper blocks on

header J5, rather than installing a DS275 in socket U8. The jumper blocks should short pins 1 and 2

together and 3 and 4 together.

# The SPI Serial Format:

There is another type of serial protocol that is totally unrelated to RS-232. It is used for controlling some

remote base interfaces, such as the Doug Hall RBI-1, RLC-ICM and BCD radio interfaces.

Instead of

<u>using a data in and data out line like RS-232, it uses two lines for output: data out and clock out.</u>

<u>There</u>

is no input to the controller; data is transferred only one way. Since there is a clock line, there is no

need to specify a baud rate (although there are a few timing restrictions). The RLC-DSP404 uses the

open collector output lines to send this type of serial. It is sent automatically by the RBI-1 / RLC-ICM

<u>commands and can be sent manually using command 138. Remember that the outputs are open collector</u>

and require pullup resistors (pullups are built into the RBI-1 and RLC-ICM).

# 024: Set Up RS-232 Serial Baud Rate

This command allows you to set up the baud rate for the RLC-DSP404's main serial port. The baud rate

for the main serial port should be set to match the computer, serial terminal, or modem that you have

connected to it to program the controller with (it defaults to 9600 baud). <u>If you are using the serial port</u>

<u>for controlling an HF remote base (see Chapter 15), the controller will set the baud rate automatically for</u>

the type of HF radio you are using.

<0.24>x..x

#### Parameters:

-024 is the default command name.

-x..x is the baud rate. Any baud rate from 300-19200 including non-standard rates can be specified. The baud rate you enter will be rounded slightly to the nearest available rate, but should always be compatible with the actual rate selected. The standard baud rates supported are

300, 600, 1200, 2400, 4800, 9600 and 19200 baud.

# Example:

To set the baud rate to 2400 baud

<024> 2400 unkey, 'D' or <Enter>

# 060: Set Up Serial Port Options

This command allows you to turn several options on or off for the main serial port. Each of these

options

is discussed below.

The first is whether or not the serial port converts all characters that you type to upper case or not. The

default is to convert them, because all of the default command names are in upper case (they must be to

be executed by DTMF). Converting all of the characters makes it impossible to do a few thingshowever,

such as programming serial messages that contain lower case letters.

The second allows you to choose whether the controller will send a carriage return and line feed at the

end of each line (the default) or just a carriage return. The latter might be useful in situations where the

line feed messes up a modem or packet radio. Most communications programs can automatically add-

the

\_line feeds back in when they receive a carriage return so that the screen will scroll, rather thanprinting

each line over top of the last one. If you are trying to make a modem dial you, you will have toturn line

\_feed sending off or when you send "ATDT<phone number>" the controller will follow it with a-CR/LF

(carriage return and line feed). The CR will tell the modem to start dialing. The LF will make it

stop

\_dialing - if a modem receives any characters from the controller while it is dialing, it will abort.

The third determines whether serial messages that are generated by commands that are executed by

DTMF are suppressed or printed. If they are suppressed (the default), the only serial messages that will

be printed are: the reset/copyright message, serial responses to commands executed from the serial port

(not DTMF), and serial messages sent with Command 162.

The fourth is whether the serial is queued (buffered) or not. Normally it is buffered so that the controller

can continue to run while the serial is sent in the background. Occasionally, usually for debugging

purposes, you may want the serial to be sent before execution continues. In this case, you can turn

queuing off. It automatically gets turned on whenever the controller is reset.

Set case sensitivity and line feeds.

Set case sensitivity, line feeds and suppression.

Set case sensitivity, line feeds, suppression and queuing.

Set all settings to default values.

#### Parameters:

- 060 is the default command name.
- X is 1 to make the serial port case sensitive (no automatic conversion to upper case) 0 to make the serial port convert all characters entered to upper case
- Y is 1 to send line feeds (the default) or 0 to suppress them
- Z (optional) is 1 to suppress serial (the default) or 0 to send serial caused by commands entered

# from DTMF

- Q (optional) is 1 for queued serial (the default) or 0 to send it before continuing

## 032: Send Serial Message

This command allows you to send a custom message out the controller's serial port. If the message is

entered with DTMF the serial message will only contain DTMF digits. If the message is entered using

the RS-232 port, then the message will contain whatever characters you enter. This command is used to

display serial error messages (they are sent from macros 200300..219319 using this command), among other

things. The message will only be sent if you cause this command to be executed from the serial port or-

if

\_you turn suppressed serial off with command 060, to minimize the amount of stuff being sent out of-

the

\_serial port. If you want a message to be sent no matter what, use command 162.

<032> s..s

### Parameters:

- 032 is the default command name.
- s..s is the data to be sent over the RS-232 port
  - -- The message length is limited to the maximum command length (about 200 characters) or if used in a macro, by the space left in a macro (less than 100 characters). If you need a longer message, split it up between several macros and use one macro to call the next macro in the sequence.

# Voice response:

There is no voice response for this command

#### Notes:

To change the baud rate, see command 024.

Serial output is normally queued (buffered) so that controller operation does not wait for the message to be sent before continuing. Queueing can be controlled with command 060.

-<u>u</u> Spaces are automatically stripped when the controller processes commands, including commands

that send serial messages. This allows upload files to contain spaces without affecting the format

of the input data. If a user wishes to have a 'space like character' sent the '\_' (underscore) data can be used.

# 162: Always Send Serial Message out the Main Serial Port

This command is identical to Command 032 except that it always sends its message, regardless of

whether command 060 is set to suppress serial sending or not.

# 169: Always Send Serial out Main Serial Port by ASCII Code

This command does the same thing as Command 162, but lets you enter characters by their ASCII codes.

For each character you want to send, you have to enter a three digit number - that character's ASCII code

(in decimal, not hex). This allows you to send characters that are not on the keyboard, or to send characters that are not on a DTMF pad when programming by DTMF. For a table of the ASCII codes,

see Appendix G.

<169> ccc ccc ... ccc

# Parameters:

- 169 is the default command name
- CCC is the ASCII code for one serial character.

## Notes:

- $-\dot{\mathbf{u}}$  To send a space with this command, use the ASCII code 032 (hex 0x20).
- $-\underline{\underline{u}}$  This command does not automatically send carriage returns (ASCII 013) or line feeds (ASCII
- 010). If you do send a carriage return, the controller may automatically send a line feed \_\_\_ afterward
- = (see command 060).

# 138: Direct SPI Send using Open Collector Output Lines

This command is provided only for advanced use controlling SPI devices. Unless you need to control a

serial shift register, ignore this command (it could be used to send data to the Doug Hall RBI-1 or the

RLC-ICM, but using the specialized commands is much easier). This command accepts data in hex (two

digits per byte) and sends that data in an SPI format (with data and clock line) using the open collector

output lines on the Deluxe/Deluxe II board.

<138> xx Send individual byte

<138> xx..xx Send multiple bytes

#### Parameters:

- 138 is the default command name.
- XX is the hex number (00..FF) representing a byte of data to send. To send codes with 'E' or 'F',

you will have to enter this command from the serial port. You may have to change your force execution digit (see command 078) to be able to enter some hex codes. You must enter an even number of XX digits since it takes two hex digits to make one byte of data.

## Notes:

External shift registers like the 74HC164 will decode the shifted data and return it to 1's and 0's for

for external BCD radio control.

- $\underline{\underline{\mathbf{u}}}$  Each hex digit entered corresponds with four binary digits. If you are sending only digits 0..9,
- \_\_ they can be
- used as BCD data.

Key Entered Data Sent

Key Entered

# Data Send

. 8 1000

. 9

. A 1010

В

0100

. C

. D

```
6
0110
.
E
1110
7
0111
.
F
1111
```

 $-\underline{\dot{\mathbf{u}}}$  The data is output on the pins of the outputs connector shown below:

```
Data Output - Output #7 (Pin 6)
Clock - Output #8 (Pin 2)
Ground - Pin 1
```

## Chapter 8: Macros

#### How Macros Get Executed:

Macros can be executed just like any other commands: you can enter the name of the macro from a-

radio

and unkey (or press the force execution digit), you can enter the macro name from the serial port,-

you

enter an 'N' followed by the macro number from the serial port, etc. In addition, the controller will

automatically execute macros at certain times, such as to send an ID or a courtesy beep. The macros that

the controller calls in this way are called "automatic macros" because they are called automatically. The

automatic macros are listed in this chapter along with descriptions of when they get executed. When the

controller is reinitialized (at the factory or if you do it), many of these macros are programmed with

examples of what you might want to do: the ID macros speak sample IDs, the courtesy beep macros

send beeps and the I/O macros send messages that tell you what changed. You can change what is in any

or all of the automatic macros to make them do what you want.

Macros numbered 600 and higher are not listed with descriptions, because the controller doesn't have a

specific purpose for them; they are called "user macros". They are extras that can be used for anything

else you might want to do. You will probably want to keep a list of what you use each one for so you

can remember it later. After you program them, you may want to change their names and execute them

from your radio with DTMF, program the automatic macros to execute them, or tell the controller to

execute them at certain times using the event triggers (see Chapter 20).

#### What a macro is:

There are at least two common understandings of what a macro is. The RLC-DSP404 currently supports

the more flexible of the two types; eventually it may support both. The kind the RLC-DSP404 supports

could be called a "multiple command macro" because it provides a way to execute a sequence of

internal

commands in response to one command from the user. In other words, this kind of macro contains a list

of commands that are executed in order when the macro is executed. If you commonly want to connect

your repeater port to a link port and turn DTMF muting on and change your courtesy beep, you could

program a macro to execute the appropriate commands. This type of macro is very similar to the macros

that many word processors and other computer programs allow you to make to automate things that you

do often.

The other commonly used kind of macro (that the RLC-DSP404 does not currently support) could be

called a "snapshot macro". It allows you to set up the controller the way you like it, take a snapshot of it,

and restore the controller to that configuration at any time by recalling the snapshot. While this may be

convenient, it is also limiting. Consider an example: you have two stand alone repeaters running off of

one RLC-DSP404 controller. You are setting up one repeater today and plan to set up the other tomorrow. You set up the repeater with a certain courtesy beep and take a snapshot. You then set it up

with a different courtesy beep and take another snapshot. Now you can easily switch back and forth

between the two courtesy beeps just by recalling the appropriate snapshot. The next day you set up the

other repeater port in a similar way, with two different courtesy beeps. Now you start having problems.

Whenever you change the courtesy beep on one repeater, it messes up the courtesy beep on the other

repeater as well, since everything gets stored in one big snapshot macro. You can't make a snapshot

macro that does just what you want; it always restores a whole configuration at once.

The solution to the dilemma illustrated above is to use multiple command macros that do exactly what

you want them to and nothing else. If you want a macro to connect you to Link A and not to Link B,

make a multiple command macro to disconnect your repeater from Link B and connect it to Link  $_{\Delta}$ 

Executing this macro will not interfere with anything else that is going on in the controller like asnapshot

\_would.

## **Advanced Macro Topics:**

#### Limits on Macros:

Since one macro can call another macro, you may wonder if macro 600 could call 601, which could call

602, which could call 603, etc. until you had called 100 macros or so. The answer is not quite. There-

are

\_two limits. One is that if the total time it takes the processor to decode and execute the whole-chained

macro sequence is more than 1/2 second or so, the controller may reset itself. It is unlikely that you will

ever reach this limit (it would probably take more than 20 macros all hooked together to evencome close

\_to this limit). The other limit restricts how deeply the macros can be nested (called from-another macro).

\_This is not a limit on how many commands can be called inside of a macro. It is not alimit on how many

\_macros can be executed from one macro. It is a limit on one macro calling another macro that calls

another macro that calls another macro. You can think of it as a limit on how deep anoutline can go.

\_For example, you execute macro 600. It calls Command 038, macro 601, and Command 000. This can

be shown as the level with Roman numerals:

- I Call Command 038
- II Call macro 601
- III Call Command 000 and connect port 1 and 3

Macro 601 could contain Command 007 and call macro 602. Since macro 601 is called from macro 600,

it is nested one level deeper, to level 2. This could be shown as capital letters in the outline:

- I Call Command 038
- II Call macro 601
  - A Call Command 007
  - B Call macro 602
- III Call Command 000 and connect port 1 and 3

Macro 602 could call macros 603,604 and 605. Macro 602 is nested one level deeper than 601, so it is at

level 3.

- I Call Command 038
- II Call macro 601
  - A Call Command 007
  - B Call macro 602
    - 1 Call macro 603
    - 2 Call macro 604
    - 3 Call macro 605

III Call Command 000 and connect port 1 and 3

Macros 603, 604 and 605 are at level 4. Note that they are all at the same level. Any commands that-

are

\_called from these macros will be at level 5. This is about as deep as the RLC-DSP404 will let you-

nest

macros, 5 or 6 levels. If you ever exceed this limit, error macro 209309 will be executed. This is the-

nested

\_macro depth limit.

Macros that Accept Data at Runtime:

Normally macros must be programmed with all of the data they will need to execute. For example, a

macro that dials a phone number could be programmed as follows:

```
055 600; erase macro 600
056 600 112 123 4567; call 123-4567
```

Such a macro will always call the same phone number. It can be executed by entering "600". There is a

way to make macros that accept more information at the time they are executed, and pass that data into

the commands that are executed by the macro. For example:

```
o55 600; erase macro 600
o56 600 112; phone number will be supplied at runtime
```

contains everything it needs to know to make the call, except for what phone number it is supposed to

use. You can tell the controller to get the rest of the information needed to execute the macro at the time

you tell it to execute the macro with command 067. For the above example, you could enter:

067 600 07 0; make macro 600 accept exactly seven digits

Command 067 tells the controller that a macro will need more information at runtime. In this case, we

specified that the user would enter exactly seven digits. It would also be possible to let the user enter

seven or more digits ("067 600 07 1"), or any number of digits ("067 00 1"). See command 067 for-

more

information.

## 300..599: Execute an Automatic Macro

These commands allows you to manually recall program macro sequences. These sequences are executed

- \_automatically by the controller to send IDs, courtesy beeps, alarm analog lines, recall inputconditions,
- \_etc. These macros are programmed the same way as user macros, but are automatically called by the
- controller when certain events occur. You can also execute them manually by entering thecommand
- \_name (300 through 599). This is useful for testing the macros to make sure that they are-programmed the
- way you want them to be. They are described in the "Automatic Macro Explanations"-section at the end of this chapter.

<300>..<599>

# Parameters:

- 300..599 is the default command name.

### 600..999: Execute a User Macro

These commands allow you to execute user macro sequences. These macros are not used by the controller for any specific purpose, so you can use them for any purpose.

<600>..<999>

#### Parameters:

- 600..999 is the default command name.

## 055: Erase Macro

This command erases a macro. If it is executed after it has been erased, nothing will happen. There is-

no

\_way to "unerase" a macro that has been erased.

<055> mmm

## Parameters:

- 055 is the default command name.
- MMM is the command number of the macro to erase.

056: Add Command to a Macro

This command allows you to add a command to a macro. If the macro was empty (contained no commands), it becomes the first command in the macro.

<056> mmm ccc d..d

### Parameters:

- 056 is the default command name.
- MMM is the macro number for this sequence to be stored in
- CCC is the command number within a macro
- D..D is the additional data associated with command CCC

# Example:

```
Want to execute command 031 using macro 600 031 with 20 additional digits: 00 01 02 03 04 05 06 07 08 09 (sends 0, 1, 2, 3, 4, 5, 6, 7, 8, 9 in CW)
```

```
<056> 600 031 00 01 02 03 04 05 06 07 08 09 D or unkey or 
<Enter>
```

## 053: Erase Then Add Command To Macro

This command is just a shortcut for entering command 055 then 056 (to erase then add a command to a macro).

<053> mmm ccc d..d

The following examples are equivalent:

```
; Example #1
055 600; erase macro (make sure it is empty)
056 600 066 TEST; make macro speak "test"
; Example #2
053 600 066 TEST; erase macro then make it speak "test"
```

## Parameters:

- 053 is the default command name.
- MMM is the macro number for this sequence to be stored in
- CCC is the command number to be executed by the macro
- D..D is the additional data associated with command MMM

# Example:

```
Want to execute command 031 using macro 600 031 with 20 additional digits: 00 01 02 03 04 05 06 07 08 09 (sends 0, 1, 2, 3, 4, 5, 6, 7, 8, 9 in CW)
```

<053> 600 031 00 01 02 03 04 05 06 07 08 09 D or unkey or <Enter>

#### 054: Recall Macro Contents

This command recalls the contents of a macro so that you can find out what the macro is programmed to

do. It does not execute the commands in the macro, only recalls them to the serial screen or speaks them

with the voice synthesizer. The format of the response is explained below.

<054> mmm

#### Parameters:

- 054 is the default command name.
- MMM is the macro number to recall

# Format of the Voice Response:

- "M" [macro number]
- "N" [number of commands in the macro]
- "C" [which command in the macro] [command number]
- "D" [number of digits of data] [the digits of data]

repeat last two lines until all commands in macro have been recalled

? "percent" how many percent full the macro is

## Example:

Recall Default Contents of Macro 300 (Command length not matched error handling macro):

You enter the command "054 300 D or unkey or <Enter>"

# The serial response is:

Macro 300 contains 2 commands:

- #1 Command #032 with 31 digits of data: Command name length not matched
- #2 Command #036 with 09 digits of data: 133002028

# The voice response is:

- "M 300" macro number 300
- "N2" number of commands in the macro is 2
- "C1 32" the first command in the macro is command number 032 (send serial message)
- "D31" this command has 31 digits of data which are: "Command name length not matched" (speaks each letter, with pauses for spaces)
- "C2 36" the second command in the macro is command number 9
- "D9" this command has 9 digits of data which are:
- "133002028" the words "Error Two-Hundred"

# 057: Copy a Macro

This command allows you to copy a macro. It erases whatever used to be in the destination macro and

replaces it with a copy of whatever is in the source macro.

<057> mmm ddd

#### Parameters:

- 057 is the default command name.
- MMM is the number of the source macro
- DDD is the number of the destination macro

058: Erase a Command in a Macro

This command allows you to erase a command in a macro without erasing the whole macro. The commands inside of the macro are numbered 00, 01, 02... so the first command is numbered 00. It may

be helpful to execute command 054 to recall the contents of the macro so that you know which-command

\_to erase.

<058> mmm nn

## Parameters:

- 058 is the default command name.
- MMM is the number of the macro
- NN is the number of command inside of the macro to erase (00, 01, 02...)

## Voice Response:

"M <macro number> <pause> <number of command erased> 059: Insert a Command in a Macro

This command allows you to insert a command in a macro without erasing the following commands.

This is useful for adding a command to the beginning or middle of a macro. The commands inside of-

the

macro are numbered 00, 01, 02... so the first command is numbered 00. It may be helpful to execute

command 054 to recall the contents of the macro so that you know where you want to insert the

new

command.

<059> mmm nn ccc d..d

# Parameters:

- 059 is the default command name.
- MMM is the number of the macro
- NN is the where inside of the macro to insert the new command (00, 01, 02...) If NN is larger than the number of commands in the macro, the new command will be appended to the macro.
- CCC is the command number of the command to insert
- D..D is the data for the above command

# Voice Response:

"M <macro number> <pause> <number of command inserted>

# 067: Set Macro Data Length

This is an advanced command that lets you specify that a macro should gather some extra information

(more digits entered after the name of the macro) when it is executed and pass that information on to the

commands inside of the macro. See the examples below for some of the possible uses of this command.

```
<067> mmm xx y

'mmm' mmm' is the macro number

'xx' xx' is number of digits of data

'y' y' is '0' 0' if the amount of data must be exact or

'H'or 1' if more data is OK.
```

recall data length for macro 'mmm' mmm'

#### Notes:

<067> mmm

When the macro executes, any commands in the macro that require a fixed amount of data will

first take the data that was specified when the macro was programmed, then will take as many of

the digits specified at runtime as needed.

Commands in the macro that will accept a variable amount of data get all of the remaining digits

specified at run-time.

<u>·</u><u>u</u> Any extra digits will be discarded.

### Default:

```
-\dot{\mathbf{u}} <067> mmm 00 0
```

## Examples:

```
Extra autopatch up code:

067 600 01 1; allow macro 600 to take 1 or more digits

053 600 112; make macro 600 call patch up command

; the phone number will be specified at runtime

010 600 n..n; rename new patch up code to "n..n"

Usage: "n..n < phone number>"
```

-<u>u</u> Connect port 3 to the port that user specifies: 067 601 01 0; allow macro 600 to take 1 digit

053 601 000 3; connect port 3 to port specified at runtime Usage: "601 x" will connect port 3 to port x

#### **Automatic Macros**

The following is a list of the macros that are automatically executed by the controller at certain times.

Because they are executed automatically when something happens (like a timer expiring) rather than

because a user specifically told it to execute by entering the macros name, they are called "automatic"

macros. The only difference between automatic and user macros is who (or what) decides that they

should be executed. They are named according to the function that they usually perform. If you want to

change how something works, you can change what commands the macro executes to suit your own

desires. An example of this would be changing an impolite ID macro to send your repeater's ID rather

than the example ID that is programmed in at the factory.

You can execute any of these macros by entering its name which corresponds to its macro number

followed by a 'D' or unkey or <Enter> (example 300 would execute macro 300). This is useful for

finding out what is already in the macros. You find out even more about what is in a macro by recalling

its contents with Command 054 D or unkey or <Enter> then the macro's number. If you do this from a

serial terminal, it will be relatively easy to understand. If you do it from a DTMF pad, the voice message

may seem long and complicated. This is because the synthesized voice must spell out the messages that

are programmed in the macros. You can learn a lot about how the controller works by looking at what is

inside of the macros with Command 054. Command 054 also tells you how many percent full a macro-

is.

Each macro can store 100 bytes of information, about 100 keystrokes.

# **Automatic Macro Explanations**

Macros 300..319 are where your error messages come from. Whenever an error occurs in the controller,

it will cause one of these macros to be executed. To find out what caused the error, remember what the

error number is and look at the description of the corresponding macro number below. You can

change

the error messages to say anything you want them to, or nothing at all, by changing these macros.

note, however, that if you remove the error messages completely, that you may not be able to tell when

an error occurs. See the section about error messages in Chapter 1 for more detailed descriptions.

Macro

Definition

.

Macro

Definition

300

No matching Command Name

310

Invalid data value

301

Too few data digits

311

Command does not exist

302

Too many data digits

312

Bad Autopatch number

303

Invalid number of data digits

313

Autopatch error

Execution blocked from port 314 Invalid User 305 User level to low 315 DVR is busy 306 Reserved 316 Macro is full 307 Command executed OK 317 HF Error 308 Internal problem 318 Not Defined 309 Macro depth problem 319 Not Defined

Macros 320..391 These macros are automatically called when it is time to send an ID. You will want to erase (with Command 055) what is in these macros when you get the controller and put your own ID

messages in these macros. It would be worth your time to study the way these IDs are programmed at

the factory (see Command 054) so that you can make yours work the same way. Note that Command

064 is used to speak the voice IDs so that they will be polite and will automatically call the impolite ID

macro (which is usually CW) if they are interrupted. Shortcut: if you want all four of the pending IDs

for a port to send the same message, program that message in the first of the four pending ID macros,

then program the other three to execute the first one. To change the ID timers, see Command 020.

## Macro Definition Macro Definition

- 320 . . Initial ID, Port 1
- 321 . . Initial ID, Port 2
- 322 . . Initial ID, Port 3
- 323 . . Initial ID, Port 4
- 324 . . Initial ID, Port 5
- 325 . . Initial ID, Port 6
- 326 . . Initial ID, Port 7
- 327 . . Initial ID, Port 8
- 328 . . Initial ID, Port 9
- 329 . . Initial ID, Port 10
- 330 . . Initial ID, Port 11
- 331 . . Initial ID, Port 12
- 332 . . Pending ID #1, Port 1
- 333 . . Pending ID #1, Port 2
- 334 . . Pending ID #1, Port 3
- 335 . . Pending ID #1, Port 4
- 336 . . Pending ID #1, Port 5
- 337 . . Pending ID #1, Port 6
- 338 . . Pending ID #1, Port 7
- 339 . . Pending ID #1, Port 8
- 340 . . Pending ID #1, Port 9
- 341 . . Pending ID #1, Port 10
- 342 . . Pending ID #1, Port 11
- 343 . . Pending ID #1, Port 12
- 344 . . Pending ID #2, Port 1
- 345 . . Pending ID #2, Port 2
- 346 . . Pending ID #2, Port 3
- 347 . . Pending ID #2, Port 4
- 348 . . Pending ID #2, Port 5
- 349 . . Pending ID #2, Port 6

- 350 . . Pending ID #2, Port 7
- 351 . . Pending ID #2, Port 8
- 352 . . Pending ID #2, Port 9
- 353 . . Pending ID #2, Port 10
- 354 . . Pending ID #2, Port 11
- 355 . . Pending ID #2, Port 12
- 356 . . Pending ID #3, Port 1
- 357 . . Pending ID #3, Port 2
- 358 . . Pending ID #3, Port 3
- 359 . . Pending ID #3, Port 4
- 360 . . Pending ID #3, Port 5
- 361 . . Pending ID #3, Port 6
- 362 . . Pending ID #3, Port 7
- 363 . . Pending ID #3, Port 8
- 364 . . Pending ID #3, Port 9
- 365 . . Pending ID #3, Port 10
- 366 . . Pending ID #3, Port 11
- 367 . . Pending ID #3, Port 12
- 368 . . Pending ID #4, Port 1
- 369 . . Pending ID #4, Port 2
- 370 . . Pending ID #4, Port 3
- 371 . . Pending ID #4, Port 4
- 372 . . Pending ID #4, Port 5
- 373 . . Pending ID #4, Port 6
- 374 . . Pending ID #4, Port 7
- 375 . . Pending ID #4, Port 8
- 376 . . Pending ID #4, Port 9
- 377 . . Pending ID #4, Port 10
- 378 . . Pending ID #4, Port 11
- 379 . . Pending ID #4, Port 12
- 380 . . Impolite ID, Port 1
- 381 . . Impolite ID, Port 2
- 382 . . Impolite ID, Port 3
- 383 . . Impolite ID, Port 4
- 384 . . Impolite ID, Port 5
- 385 . . Impolite ID, Port 6
- 386 . . Impolite ID, Port 7
- 387 . . Impolite ID, Port 8
- 388 . . Impolite ID, Port 9
- 389 . . Impolite ID, Port 10
- 390 . . Impolite ID, Port 11
- 391 . . Impolite ID, Port 12

Macros 392..403 are executed when it is time to send a courtesy beep. You would normally call Command 040 from this macro to generate the tones of your courtesy beep. If you want your courtesy

beep to contain several beeps in sequence, you can call Command 040 multiple times within one macro,

once for each beep.

Note: Before this macro is automatically called after you unkey, the audio routing variable is set to-

make

\_the tones go to the proper ports, so you do not have to worry about that at all. Just call the-commands

\_you want to be executed when it is time for a courtesy beep (you could send beeps, DTMF-digits, voice

\_messages...) and the audio will automatically be sent to the correct ports. To change the courtesy beep

\_timers, see Command 020.

## Macro Definition

- 392 .Courtesy Beep Slot, Port 1
- 393 .Courtesy Beep Slot, Port 2
- 394 .Courtesy Beep Slot, Port 3
- 395 .Courtesy Beep Slot, Port 4
- 396 .Courtesy Beep Slot, Port 5
- 397 . Courtesy Beep Slot, Port  $6\,$
- 398 .Courtesy Beep Slot, Port 7
- 399 .Courtesy Beep Slot, Port 8 400 .Courtesy Beep Slot, Port 9
- 401 .Courtesy Beep Slot, Port 10
- 401 .Courtesy Beep Slot, Port 10
- 402 .Courtesy Beep Slot, Port 11
- 403 .Courtesy Beep Slot, Port 12

Macros 404..419 are called when the analog input lines go into a High alarm. You may want to use

these macros to speak an voice message indicating the alarm, start a beaconing alarm (see Chapter 19)

and/or take some other action such as turning off an open collector output line. To change how often the

RLC-DSP404 checks to see if an alarm has occurred, see the I/O polling timer in Chapter 4. The default

is once per second.

#### Macro Definition

```
404 .High Alarm, Analog Line 1
405 .High Alarm, Analog Line 2
406 .High Alarm, Analog Line 3
407 .High Alarm, Analog Line 4
408 .High Alarm, Analog Line 5
409 .High Alarm, Analog Line 6
410 .High Alarm, Analog Line 7
411 .High Alarm, Analog Line 8
412 .High Alarm, Analog Line 9
413 .High Alarm, Analog Line 10
414 .High Alarm, Analog Line 11
415 .High Alarm, Analog Line 12
416 .High Alarm, Analog Line 13
417 .High Alarm, Analog Line 14
418 .High Alarm, Analog Line 15
419 .High Alarm, Analog Line 16
```

Macros 420..435 are called when the analog input lines go into a Low alarm. You may want to use-

these

\_macros to indicate an alarm condition.

#### Macro Definition

420 .Low Alarm, Analog Line 1 421 .Low Alarm, Analog Line 2 422 .Low Alarm, Analog Line 3 423 .Low Alarm, Analog Line 4 424 .Low Alarm, Analog Line 5 425 .Low Alarm, Analog Line 6 426 .Low Alarm, Analog Line 7 427 .Low Alarm, Analog Line 8 428 .Low Alarm, Analog Line 9 429 .Low Alarm, Analog Line 10 430 .Low Alarm, Analog Line 11 431 .Low Alarm, Analog Line 12 432 .Low Alarm, Analog Line 13 433 .Low Alarm, Analog Line 14 434 .Low Alarm, Analog Line 15 435 .Low Alarm, Analog Line 16 Macros 436..451 are called when the analog input lines go out of either High or Low alarm into a Normal condition. You may want to use these macros to indicate that the analog reading is no longer

causing an alarm.

#### Macro Definition

```
436 .Alarm to Normal, Analog Line 1
437 .Alarm to Normal, Analog Line 2
438 .Alarm to Normal, Analog Line 3
439 .Alarm to Normal, Analog Line 4
440 .Alarm to Normal, Analog Line 5
441 .Alarm to Normal, Analog Line 6
442 .Alarm to Normal, Analog Line 7
443 .Alarm to Normal, Analog Line 8
444 .Alarm to Normal, Analog Line 9
445 .Alarm to Normal, Analog Line 10
446 .Alarm to Normal, Analog Line 11
447 .Alarm to Normal, Analog Line 12
448 .Alarm to Normal, Analog Line 13
449 .Alarm to Normal, Analog Line 14
450 .Alarm to Normal, Analog Line 15
451 .Alarm to Normal, Analog Line 16
```

Macros 452..467 are called when the digital inputs lines go from Low to High. You may want to use

these macros to indicate an alarm condition. These macros are only called if the input alarms are enabled

with command 092 (see Chapter 12).

### Macro Definition

```
452 .Low to High, Input Line 1
453 .Low to High, Input Line 2
454 .Low to High, Input Line 3
455 .Low to High, Input Line 4
456 .Low to High, Input Line 5
457 .Low to High, Input Line 6
458 .Low to High, Input Line 7
459 .Low to High, Input Line 8
460 .Low to High, Input Line 9
461 .Low to High, Input Line 10
462 .Low to High, Input Line 11
```

```
463 .Low to High, Input Line 12
464 .Low to High, Input Line 13
465 .Low to High, Input Line 14
466 .Low to High, Input Line 15
467 .Low to High, Input Line 16
```

Macros 468..483 are called when the digital input lines go from High to Low. You may want to use

these macros to indicate an alarm condition. These macros are only called if the input alarms are enabled

\_with command 092 (see Chapter 12).

## Macro Definition

```
468 .High to Low, Input Line 1
469 .High to Low, Input Line 2
470 .High to Low, Input Line 3
471 .High to Low, Input Line 4
472 .High to Low, Input Line 5
473 .High to Low, Input Line 6
474 .High to Low, Input Line 7
475 .High to Low, Input Line 8
476 .High to Low, Input Line 9
477 .High to Low, Input Line 10
478 .High to Low, Input Line 11
479 .High to Low, Input Line 12
480 .High to Low, Input Line 13
481 .High to Low, Input Line 14
482 .High to Low, Input Line 15
483 .High to Low, Input Line 16
```

Macros 484..495 are called when the Time-Out Timer expires. You may want to program these messages to indicate when a time-out condition occurred. They default to speaking "One Time Out" (or

whatever receiver it is that just timed out). To adjust the time out timers, see Command 020.

#### Macro Definition

```
484 .Time-out Timer Message, Port 1
485 .Time-out Timer Message, Port 2
486 .Time-out Timer Message, Port 3
487 .Time-out Timer Message, Port 4
488 .Time-out Timer Message, Port 5
489 .Time-out Timer Message, Port 6
```

```
490 .Time-out Timer Message, Port 7
491 .Time-out Timer Message, Port 8
492 .Time-out Timer Message, Port 9
493 .Time-out Timer Message, Port 10
494 .Time-out Timer Message, Port 11
495 .Time-out Timer Message, Port 12
```

Macros 496..507 are called when the Time-Out Timer comes out of a time-out condition. You may

want to program these messages to indicate that a time-out condition has just been cleared.

#### Macro Definition

```
496 .Time-out Condition Clear Message, Port 1
497 .Time-out Condition Clear Message, Port 2
498 .Time-out Condition Clear Message, Port 3
499 .Time-out Condition Clear Message, Port 4
500 .Time-out Condition Clear Message, Port 5
501 .Time-out Condition Clear Message, Port 6
502 .Time-out Condition Clear Message, Port 7
503 .Time-out Condition Clear Message, Port 8
504 .Time-out Condition Clear Message, Port 9
505 .Time-out Condition Clear Message, Port 10
506 .Time-out Condition Clear Message, Port 11
507 .Time-out Condition Clear Message, Port 12
```

Macros 508..519 If you don't use preaccess, you can totally ignore these macros. Even if you do use

preaccess, you don't have to worry about them. They are automatically renamed and programmed when

you configure a port for preaccess with Command 070 or 071. If you are curious, however, read on.

When a port is set to require preaccess (either with Command 070 or 071), these macros are automatically programmed and renamed. The access code ("\*" for a repeater, "#??" for a link) isactually

the new name of these macros. Also, the command decoder is told to ignore every command-that is

entered from that port except for these macros. When you enter the access code, one of these macros is

executed. The commands that are automatically programmed into these macros may do a lotof things

(such as start dial tone for a link), but they always do this one thing, they execute Command-074.

Command 074 tells the command decoder to let that port access all of the commands in the controller

\_again, but only until the preaccess timer (see Command 020) runs out.

You should never have to change the contents of these macros by hand (since Command 070 and 071 do

the work for you), but you might want to change their names. When you use Command 070 to configure

a port as a preaccess repeater, it assumes that you want the local-mode access code to be "\*". If that is

not true, you can simply rename the first preaccess macro for that port to something else. Similarly, the

link access code that is usually "#" plus two digits, can be changed to any valid command name up to six digits long.

## Macro Definition

508 .Pre-Access Storage, Port 1

509 .Pre-Access Storage, Port 2

510 .Pre-Access Storage, Port 3

511 .Pre-Access Storage, Port 4

512 .Pre-Access Storage, Port 5

513 .Pre-Access Storage, Port 6

514 .Pre-Access Storage, Port 7

515 .Pre-Access Storage, Port 8

516 .Pre-Access Storage, Port 9

517 .Pre-Access Storage, Port 10

518 .Pre-Access Storage, Port 11

519 .Pre-Access Storage, Port 12

Macro 520 is called whenever the controller is reset, whether it is reset because the power was just

turned on, because you pressed the reset button, or because you executed the remote reset command.

You can use it to execute any commands that you want to be executed on reset. If you run out of space

in this, or any other macro, because you are trying to do too much, just call another macro, or several of

them, from this macro and split up the work.

### Macro Definition

#### 520 .Macro Called on Reset

Macro 521 is a temporary macro that is used when appending macros etc. It is of no use to you because

it will be overwritten often.

# Macro Definition

# 521 .System Temporary Macro

Macros 522..537 are called when the corresponding user timer (see Command 020) expires. These

timers can be started with Command 022 and stopped with Command 023. They are not normally used,

but are provided for users that have a special purpose for them.

Macro Definition	Macro	Definition
522 User Timer # 00		
523 User Timer # 01		
524 User Timer # 02		
525 User Timer # 03		
526 User Timer # 04		
527 User Timer # 05		
528 User Timer # 06		
529 User Timer # 07		
530 User Timer # 08		
531 User Timer # 09		
532 User Timer # 10		
533 User Timer # 11		
534 User Timer # 12		
535 User Timer # 13		
536 User Timer # 14		
537 User Timer # 15		

Macro 538 is automatically executed immediately before the autopatch is taken off hook when a call is

made. It can be used to disconnect link ports before the call begins.

Macro Definition

538 .Called before Autopatch is taken Off Hook

Macro 539 is automatically executed immediately after the autopatch is hung up. It can be used to

reconnect the links that were disconnected in macro.

Macro Definition

539 .Called after Autopatch is placed On Hook

Macro 540 is used to speak "Autopatch Busy" when you try to use the patch when it is already in use. It

is automatically programmed when the controller is reinitialized. You can erase it and program your-

own

\_autopatch busy message if you wish.

Macro Definition

540 .Called when the Autopatch is Busy

Macro 541 is used to speak "Autopatch" before the phone number is read back and dialed. It is automatically programmed when you set up the autopatch with Command 110. You can erase it and

program your own message if you wish, but be sure that you recall the pre-programmed message first-

and

understand what it does (it may do some other things depending on the number readback mode).

You

can also change the number of pauses that are spoken after the word "Autopatch" to change the delay

\_before the number readback begins. See also macro 542.

Macro Definition

541 .Called before Autopatch number is read-back

Macro 542 is used to speak pauses after the number is read back. It is automatically programmed when

you set up the autopatch with Command 110. You can change it if you wish, but be sure that you recall

the pre-programmed macro first and understand what it does. You can change the number of pauses that

are spoken to change the time that you can wait after the number is read back and still be able to kerchunk to make it dial/not dial (depending on the number readback mode).

Macro Definition

542 .Called after Autopatch number is read-back

Macro 543 is an autopatch macro that is used for number readback mode 2.

Macro Definition

543 .Internal Autopatch Macro

Macro 544 is used to speak "Call complete at <time>" when you hang up the patch. It is automatically

programmed when the controller is reinitialized. You can erase it and program your own autopatch off message if you wish.

Macro Definition

544 .Called when the Autopatch is hung-up.

Macro 545 is called when the DTMF cover tone is requested. It normally sends a 440 Hz tone using

command 040. It can be set back to the default beep by entering: "053 545 040 020 030 0440". Any

other tone, CW character, or voice message could also be used, although you will want to keep the

duration fairly short.

Macro Definition

545 .DTMF cover tone macro

Macro 546 is called when a user logs on using his password. First his callsign is spoken, then this-

macro

is called. It is normally programmed to speak "control up". It can be programmed to speak other

messages if you wish.

Macro Definition

546 .User Logon Message

Macro 547 is called when a user tries to log on but gets the password wrong. It normally says "fail".

Macro Definition

547 .User Logon Fail Message

Macro 548 is called when a user logs off. First his callsign is spoken, then this macro is called. It is normally programmed to speak "control down".

Macro Definition

548 .User Logoff Message

Macros 549..550 are automatically programmed by command 048 when it sets up a beacon. If you are

setting up beacons without using command 048, you can use any macros you wish.

Macro Definition

549 .Beaconing Message Macro

550 .Beaconing Message Macro

Macro 551 is used to speak "Autodial" before an autodial call is made. It corresponds to macro  $55\underline{4}1$ 

which is used for non-autodial calls.

Macro Definition

551 .Called before autodial number is read-back

Macro 552 can be used to make a two-stage autopatch call (command 111 style) with long distance-

checking and

\_DTMF regeneration. It makes the controller generate up to 8 seconds of dial-tone (whichcan be controlled by the

dial tone timers for each port) and seed the command buffer (see command 079) with command 112, so any digits

entered when the dial tone is heard will be passed as data to-

command 112. Both this macro and command 112 can

\_be given the same name, often '\*' (using-

command 010). Then if the user enters '\*' and a phone number before

unkeying, the controller will-

execute command 112 and make the call in one step. If the user just enters '\*' and unkeys, the controller-

will know that it doesn't have enough information to call command 112, so it will do this macro instead.

The macro will make the controller send dial tone, after which the user can key up again to enter the

phone number.

Macro Definition

552 .Make two-stage autopatch call

Macros 553..599 are reserved for future applications Macros 600..999 are user macros. They can be used for anything you want.

# Chapter 9: Pre-Access Commands

## What preaccess is:

Preaccess is a system used by several large linking systems to specify which controller in the network a

DTMF command is intended to go to. A common configuration would be to enter the "\*" key before

commanding the local repeater, "#99" before commanding a distant controller via a link, and "#98"-

before

commanding a different controller on the linking system. The advantage of requiring the user to "preaccess" a controller before commanding it is that you can use the same command names on each

controller without confusion as to which one you are talking to. This is a very simplified description,-

but

\_it should give you the idea.

## What you need to know:

Because the preaccess system works quite differently from the way the RLC-DSP404 normally works,

there is a lot involved with changing back and forth. Commands 070 and 071 have been provided to

make the conversion to preaccess easy and painless. If you have converted a port to preaccess and want

to change it back, use command 072.

You always configure one port at a time for preaccess, so you can set up one port for preaccess and leave

another port alone. This allows you to have a mixed system. This might be useful if you want to try out

preaccess on one port without forcing all of the users of a repeater on a different port to change the way

they do things. It also allows you to use the RLC-DSP404 to interface between linking systems that do

things differently.

# 049: Set Link Access Tone Frequencies

This command allows the user to set the tone frequencies that will be heard when the preaccess code is

entered on a link. The default is to send dial tone (350 and 440Hz).

```
<049> pp xxxx yyyy
```

## Parameters:

049 is the default command name pp is the port number to set the tone frequencies for

1 - Port 01 2 - Port 02 3 - Port 03 4 - Port 04 5 - Port 05 6 - Port 06 7 - Port 07

8 - Port 08 9 - Port 09

10 - Port 10 11 - Port 11

11 - Port 12

XXXX is the first tone of the 2-tone combination

YYYY is the second tone of the 2-tone combination

## Default:

XXXX is 0440 hertz YYYY is 0350 hertz

# Description

Tone 1

Tone 2

Dial Tone

0440 Hertz

0350 Hertz

Warble

0440 Hertz

## 070: Configure a Repeater for Preaccess

This command sets up a port to be a preaccess repeater. To execute commands from the repeater, key

up, press the '\*' key and enter the command. The command will be executed immediately, without

waiting for you to unkey. This allows you to execute multiple commands in sequence without unkeying

after each one. Also, when you pressed the star key, you were removed from any other repeaters or links

you may have been connected to. In other words, the '\*' puts you into a local control mode. This mode

will expire if you unkey for 8 seconds (see command 076).

If you key this repeater and do not press the '\*' key, you will not be in the local control mode and will be

connected to other ports normally (see Chapter 2).

<070> \_pp

#### Parameters:

- 070 is the default command name.
- P is the port to make a preaccess repeater

## 071: Configure a Link for Preaccess

This command sets up a link to use the preaccess system. Links that are configured for preaccess will

ignore any DTMF tones that are not preceded by Z..Z where Z..Z is the site access code you specify

below. This allows commands to be sent down a linking system without every controller along the way

trying to execute them, sending error messages, etc. To execute a command from such a link port, key

up, enter Z..Z and the command. It will be executed when you unkey or press 'D'

<0.71> pp y z..z

#### Parameters:

- 071 is the default command name.

- pp is the port to set up as a preaccess link
- Y is 0 for no dial tone when accessed, 1 for dial tone
- Z..Z is the site access code. Typical site access codes are "#11", "#75", "#99", etc., that is a

followed by two decimal digits. The controller will allow any preaccess code from 1 to 6 digits long with any of the 16 DTMF digits in it, although you may have to change your force-execution digit temporarily (see command 078) while you execute this command to use the force-execution digit as part of the access code.

## 072: Disable Preaccess Requirement for a Port

This command allows you to turn off preaccess as set with Commands 070 or 071. It sets the specified

port back to factory defaults:

- -Force-execution digit is 'D'
- -Autoexecution is off
- Preaccess is off

It also restores the preaccess macro for that port back to factory defaults:

- -Empty (contents are erased)
- DTMF execution mask cleared

<072> \_pp

#### Parameters:

- 072 is the default command name.
- P is the port for which to turn the preaccess requirement off (01..12)

# 073: Recall Ports with Preaccess Requirement

This command allows you to determine which ports require preaccess.

< 073>

#### Parameters:

- 073 is the default command name.

# 074: Allow Access To a Port that Requires Preaccess

This command allows commands to be executed on the port the command is executed from until the

preaccess timer which it starts (see command 020 for more info on timers) runs out. It is usually called

from the preaccess macro (see Chapter 8) for that port so that when that preaccess macro is executed, it

temporarily allows access to the rest of the commands in the controller.

# Parameters:

- 074 is the default command name.

## 075: Set Stop Access Conditions

When a port is configured for preaccess, it will not be allowed to execute commands until the access-

code

has been received. Typically this access code is "\*" for a repeater port or "#" plus two digits for a-

link.

\_When the access code is received, the controller executes command 074 (among other things)—which sets

a flag indicating that it is OK to execute commands entered from that port. The controller-will continue

\_to accept and execute commands until that flag is cleared, at which point it will require theaccess code to

be entered again. This command controls which conditions will clear that access flag.

<075> pp Recall Current Settings

<075> pp x y z I f Set Stop Access Conditions

#### Parameters:

- 075 is the default command name.
- pp is the port for which to set or recall the stop access conditions (01..12)
- X is 1 to enable / 0 to disable stopping access when a command is executed
- Y is 1 to enable / 0 to disable stopping access when an invalid command is entered
- Z is 1 to enable / 0 to disable stopping access when the receiver drops after a DTMF tone has been entered
- I is 1 to enable / 0 to disable stopping access when the DTMF interdigit timer expires.
- F is 1 to enable / 0 to disable stopping access when the force-execution digit is pressed

### Notes:

-<u>u</u> All digits following parameter pp are optional.

The preaccess timer (see Chapter 4) will always clear the access flag when it expires. It cannot be

<u>be</u> disabled with this command. It starts running when you enter the access code and is re-started

whenever you release a DTMF digit. It will never expire while you are holding down a DTMF

digit. When no digits have been entered for the duration of the timer, it clears the access flag. These conditions provide additional ways to clear the flag.

-<u>u</u> Parameter X: A command is executed or tries to execute and causes an error. If X is 1, you will

not be able to execute the access code once, then multiple commands. You will be able to enter

the access code, one command, access code, one command...

Parameter Y: An error occurs because the digits entered are not a valid command name. If you

make a mistake and this condition is enabled, you will have to enter the access code before you

can try again.

Parameter Z: DTMF digits have been entered since the access code was entered and you unkey.

This condition doesn't care how many commands you enter or whether they were valid or not; if

you enter anything and unkey, you will be forced to enter the access code again.

Parameter I: The DTMF interdigit timer expired. This may occur if you enter a few digits then

pause for a while without unkeying or if your voice falses the DTMF decoder.

-<u>u</u> Parameter F: The force-execution digit (usually <u>D'D'</u>) was entered. If the force-execution digit is

part of the access code, it will not trigger this condition, otherwise it will.

## 076: Recall Stop Access Conditions

This command allows you to recall the conditions that will stop access on a port. See Command 075 for

descriptions of the conditions.

<076> \_pp

#### Parameters:

- 076 is the default command name.
- pp is the port for which to recall the stop access conditions (01..12)

# 077: Isolate a Port from the Rest of the System

This command breaks the audio and PTT links between the specified port and all other ports in the

system until the preaccess timer (which it starts) runs out. It temporarily overrides but does not change

the crosspoint connections you may have set <u>(see Chapter 2)</u>. It is useful for isolating a port while you-

enter local control

\_commands without the tones going down any connected links. It is usually called-from the preaccess

\_macro of a port configured as a repeater. This macro is usually named '\*', the local-control key.

<077>pp

## Parameters:

- 077 is the default command name.
- ppP is the port for which to allow access (01..12)

## Chapter 10: Scheduler

#### How the Scheduler Works:

The scheduler provides you with the ability to have up to 100 events occur automatically at hourly, daily,

weekly, monthly or yearly intervals. The information used to store when event is supposed to occur and

what it is supposed to do is stored in a "scheduler slot". The information about each event you want to

set up must be stored in a different scheduler slot. You can change the contents of a scheduler slot by

simply programming something different into that slot. Each event can call one command or user-

macro.

If you call a macro, you can execute as many commands as you want in response to that-scheduler event.

\_You can use command 084 to keep a scheduled event from happening (disabling it)-and to re-enable it

\_later. Programming is explained in the command descriptions.

# 082: Set Up a Scheduler Event

This command sets up when a scheduler event will occur and what will happen at that time.

<082> ss ccc mm Hourly Event "at 15 minutes after each hour..."

<082> ss ccc hh mm p Daily Event "every day at 3:30 PM..."

<082> ss ccc d hh mm p Weekly Event "every Tuesday at 3:30 PM..."

<082> ss ccc dd hh mm p Day-of-Month Event "on the 3rd of every month at..." <082> ss ccc ww d hh mm p
Week-of-Month Event
"on the 2nd Tuesday of every month..."

<082> ss ccc nn dd hh mm p
Yearly Event
"on January 6th of every year..."

#### Parameters:

- 082 is the default command name.
- SS is the number of the scheduler slot to set up [00..99]
- CCC is the number of the command to be executed by the scheduler

  Note: The command that the scheduler executes must not require any data (like is
  normally entered after the "\*" key), because there is no way to supply that data. If you
  want the scheduler to execute a command that requires data, you must make the scheduler
  call a user macro, then program that macro to call the command with the appropriate data.
- MM is how many minutes after the hour the event will occur
- HH is the hour that the event will occur (12 hour time)
- P is 0 to indicate A.M. or 1 to indicate P.M.
- D is the day of the week (one digit)

Number
Day

1
Sunday

2
Monday

3
Tuesday

4
Wednesday

7 Saturday

- DD is the day of the month (two digits, 00..31)
- WW is the week of the month (01..05, must be two digits)
- NN is the month of the year

Note about audio responses:

The default audio routing variable for commands executed by the scheduler is set by command

050. If you want to change where the audio goes, either change the default with command 050 or

change

\_it inside of a macro with command 037.

Example #1 (hourly):

You want to have the controller speak the time (command 026) at the top of every hour. We will-

program

an hourly event in scheduler slot 00 to execute command number 026 when the minutes are 00:

082 00 026 00 D or unkey or <Enter>

Example #2 (daily):

Next you decide that you don't want it to recall the time at night, just from 8 A.M. through 10-P.M. This is

really two events, one to enable it in the morning, another to disable it at night. The command to enable or disable

scheduler slots is 084. Because 084 requires data after the commandname, we will have to call it from a macro.

First we will write the macros to enable and disable reading-

the time, then we will make the scheduler call those

\_macros.

```
053 600 084 00 1 D or unkey
053 601 084 00 0 D or unkey
082 01 600 07 30 0 D or unkey
—at 7:30 A.M. every day
082 02 601 10 30 1 D or unkey
—at 10:30 P.M. every day

Make macro 600 enable scheduler slot 00

Make macro 601 disable scheduler slot 00
—Program scheduler slot 01 to execute command 600 at
—at 10:30 P.M. every day
```

Example #3 (weekly):

Friday (day 6 to the scheduler) at 5:00 P.M. you want the message "TGIF" (word numbers 050,-

037, 039,

\_036) spoken out all radio ports on the controller. Again, we need to use a macro (number 602-for this example) to

\_set the audio routing mask to all ports and speak the message:

053 602 037 010203040506070809101112 D or unkey Program macro to set audio audio routing variable to all radio to all radio ports

056 602 036 050 037 039 036 D or unkey Append macro to speak voice message "TGIF"

Now we will program weekly scheduler event 03 to execute macro 602:

082 03 602 6 05 00 1 D or unkey

Example #4 (day-of-month):

One minute after midnight on the first day of each month, you want the controller to speak "this-

is" then the

\_name of the month out ports 1 and 2. The word numbers for "this is" are 353 and 205. We-will use the variable

word number 816 to speak the current month (see Appendix B for word numbers). - To program macro number 603,

we enter:

O53 603 037 12 D or unkey Program macro to set audio routing variable to ports—

1 and 2
O56 603 036 353 205 816 D or unkey Append macro to speak "this is" and the name of the month

Now we will make scheduler slot 04 call macro 603 monthly on the first day of the month at 12:01 A.M.

082 04 603 03 12 01 0 D or unkey

Example #5 (week-of-month):

On the second Tuesday of every month at 5:45 PM you want the message "Club meeting at 6:30"-

spoken

out all radio ports on the controller. Again, we need to use a macro (number 604 for thisexample) to set the audio

routing mask to all ports and speak the message:

053 604 037 010203040506070809101112 D or unkey

Program macro to set audio

<u>audio</u> routing variable to all radio

to all radio ports

056 604 036 131 311 086 006 021 D or unkey Append macro to speak voice message "Club meeting at

"Club meeting at 6:30"

Now we will program weekly scheduler event 05 to execute macro 604:

082 05 604 02 3 05 45 1 D or unkey

Example #6 (yearly):

You want to turn DTMF mute off on the repeater on port 1 at 10 minutes after noon on Aprilfools day.

\_First we program macro 605 to call command 007:

053 605 007 1 0 D or unkey

Macro will call command 007

Then we program scheduler slot 06:

082 06 605 04 01 12 10 1 D or unkey

#### 083: Recall a Scheduler Event

This command recalls when a scheduler event will occur and what will happen at that time.

```
<0.83> ss
```

#### Parameters:

- 083 is the default command name.
- SS is the number of the scheduler slot to recall [00..99]

## Explanation of the voice response:

```
"S ?? On/Off" Recalling Scheduler slot ?? and stating whether it is enabled (see command 084).
```

"C???" When the scheduler event occurs, it will execute command number???.

"Frequency?" How often the event happens (these changed in version 2.11)

- 5 hourly
- 4 daily
- 3 weekly
- 2 day-of-month
- 1 week-of-month
- 0 yearly

From this point on, the response depends on the frequency.

# Hourly:

"?" How many minutes after the hour the event happens.

## Daily:

"Time????" What time of day the event happens.

## Weekly:

"????" The day of the week.

"Time????" What time of day the event happens.

### Day of Month:

"D?" What day of the month the event happens.

"Time????" What time of day the event happens.

## Week of Month:

"W?" What week of the month the event happens.

"????" The day of the week.

"Time????" What time of day the event happens.

### Yearly:

"????" The month of the year that the event happens.

"D?" What day of the month the event happens.

"Time????" What time of day the event happens.

## 084: Enable/Disable a Scheduler Event

This command allows you to temporarily disable a scheduler slot, then re-enable it later without having-

to

\_reprogram it from scratch.

<0.84> ss c

Enable or Disable One Event

<084> ss tt c

Enable or Disable Range Of Events

## Parameters:

- 084 is the default command name.
- SS is the (first) number of the scheduler slot to enable or disable [00..99]
- TT is the last number of the scheduler slot to enable or disable [00..99]
- C is 1 to enable the event, 0 to disable it

## Chapter 11: The ID System

How the IDs Work:

Whenever an ID needs to be sent, a macro is called automatically by the controller. Those macros can-

hе

\_programmed to do anything, but typically they send a voice or CW message. There are six different-

ID

\_macros for each port, one initial ID macro, four pending ID macros, and one impolite ID macro.

## Only

the initial ID macro and impolite ID macros need to be programmed, as all four of the pending ID-

macros

\_default to doing the same thing as the initial ID macro.

Even though the default is for all of the pending IDs to do the same thing as the initial ID macro, its adds

variety to make them different. The initial ID macro is called the first time the repeater is kerchunked

after not being used for a while. It is usually programmed to send a relatively long descriptive voice

message. Each of the pending ID macros gets called occasionally during a conversation. They are

usually programmed to send a shorter voice ID. The controller can either rotate through them or do

them

in random order (see command 087). The controller tries to wait until you unkey to send an initial

or

pending ID, but if it is time to send an ID and you don't unkey, it has to ID while you are still keyed to

stay legal. When this happens, the controller calls the impolite ID macro, which is usually programmed-

to

\_send a CW message.

#### Polite Voice IDs:

When the controller is sending a voice initial or pending ID, you might want to be able to key up during

that ID and have the controller switch to CW. This is known as a polite ID, and is set up by programming the ID macro to send a polite voice message (see command 064 for details).

#### Example:

We want to program the IDs for the repeater on port 1. The initial ID and all of the pending IDs will be,

"Welcome to the KC7HXB repeater in Sidney, the time is <time>". The impolite ID will be, "KC7HXB/R" in CW.

To make a file on a computer to enter this ID (<u>using a computer is</u> strongly recommended, see Appendix-

F for more

\_information), you could enter it like this:

; Initial ID: Welcome to the KC7HXB repeater in Sidney, the time is <time> N053 320 064 380 526 487 476 041 033 007 038 054 032 411 257 661 476 484 270 810 ; Impolite ID: KC7HXB/R N053 380 030 20 12 07 17 33 11 36 27

To enter it from a radio using the DTMF pad, key up and enter a whole line, then unkey (note that the 'N'

at the beginning of each line and the comments - everything following a ';' - are omitted):

```
053 320 064 380 526 487 476 041 033 007 038 054 032 411 257 661 476 484 270 810 053 380 030 20 12 07 17 33 11 36 27
```

Since the pending IDs default to doing the same thing as the initial ID, they don't have to be programmed

separately unless you want to them to send a different message. If you did, you could program them as

follows:

```
; Pending IDs: This-is the KC7HXB repeater N053 332 064 380 480 476 041 033 007 038 054 032 411 N053 344 064 380 480 476 041 033 007 038 054 032 411 N053 356 064 380 480 476 041 033 007 038 054 032 411 N053 368 064 380 480 476 041 033 007 038 054 032 411
```

To Program Your Own IDs:

The following instructions and the above example should be enough to get your IDs programmed for-

port

1. More details about how everything works internally will follow, but aren't needed just to get-started.

```
N053 320 064 380 <word numbers from Appendix B>; initial ID N053 380 030 <CW characters from Appendix C>; impolite ID If you want to program your pending IDs to be different from the initial ID:
```

```
N053 332 064 380 <word numbers from Appendix B>; pending ID 1 N053 344 064 380 <word numbers from Appendix B>; pending ID 2 N053 356 064 380 <word numbers from Appendix B>; pending ID 3 N053 368 064 380 <word numbers from Appendix B>_; pending ID 4
```

To program the IDs for port 2, use the following:

```
N053 321 064 381 < word numbers from Appendix B>; initial ID N053 381 030 < CW characters from Appendix C>; impolite ID
```

If you want to program your pending IDs to be different from the initial ID:

```
N053 333 064 381 <word numbers from Appendix B>; pending ID 1
N053 345 064 381 <word numbers from Appendix B>; pending ID 2
N053 357 064 381 <word numbers from Appendix B>; pending ID 3
N053 369 064 381 <word numbers from Appendix B>_; pending ID 4
```

As long as you want your initial IDs to be voice and polite and your impolite ID to be CW, you don't

need to worry about how the above commands program macros that execute commands and supply

information to those commands. If you want to do something different, read the following section.

# More about Programming IDs:

The above instructions for programming IDs are typical of how all of the macros in the controller can be

programmed. It may look complicated at first, but it all follows a pattern. The 053 at the beginning of

each line tells the controller to erase anything that might already be in the macro because you want to

start over and put the following stuff in instead. The next three digits are the number of the macro. A-

list.

of all of the macros can be found in Chapter 8. Then comes the stuff that gets put into the macro.

064

and 030 are command numbers - you can look them up elsewhere in this manual - that speak polite-

voice

messages and send CW messages. The rest of the line is information that is used by command 064-

or 030

when the macro is executed. 064 needs to know two things: what message to speak, and what

to-

do if

\_you key up during the message. The first three digits after the 064 is the number of the impolite ID

macro, which is usually CW; that is what 064 does if you key up during the message. The rest of the

digits are the word numbers that tell it what to say. 030 doesn't need to know what to do if you key up

while it is sending CW, so it just needs to know what CW characters you want to send. Chapter 8 has

more information about programming macros and commands 064 and 030 have more information about

the information they need.

Some variations on these macros would be:

-<u>u</u> Make all of the IDs CW. To do this, use 030 and CW character numbers rather than 064, just

\_\_ like

— the impolite ID macro in the example.

Make the voice IDs do something besides the impolite ID CW message. To do this, put a different command number after the 064 when you program the macro. That command will be

executed if you interrupt the ID (but not if you are keyed when it is time for the ID to be sent - the impolite ID macro will be called in that case).

Make the voice IDs just quit if you key up while they are being sent. To do this, just replace command 064 with 063 and remove the following three digits (063 doesn't need to know what to

do if it is interrupted).

Make the voice IDs impolite, that is make them keep talking even if you key up. To do this, just

replace command 064 with 036 and remove the following three digits (036, like 063, doesn't need

— to know what to do if it is interrupted).

Make the initial and pending IDs use the optional digital voice recorder. To do this, instead of

using command 064, use 173 for the DVR followed by the DVR track numbers you want to play.

There is no way at this time to make DVR IDs polite except on the DVR (see the section titled "Making DVR Messages Polite" in Chapter 6).

## ID Timing:

You may have wondered how the controller knows when to send an ID. It uses three timers, the initial

ID timer, the pending ID timer and the impolite ID timer (see command 020 for more timer

information).

\_The default values are 10 minutes, 9 minutes and 20 seconds, respectively. If it has been more than 10

\_minutes since the repeater was last used, the next time it is keyed up, the controller will tryto send the

\_initial ID. It will attempt to wait until you unkey so it can send the (typically) voice ID-without it talking

over you or switching to CW (if it is polite). It will wait up to the duration of the impolite ID timer for

\_you to unkey. If you do not unkey within this time, it will cancel the initial ID andsend the impolite one

instead. If you do unkey so it starts to speak the initial ID and that ID isprogrammed to be polite,

\_keying up will make it switch to CW.

The pending ID timer is started whenever any ID is sent. When the pending ID timer expires, it checks-

to

see if anyone has keyed the repeater since the last ID. If they have not, there is no need to ID - the last

transmission was already identified. If someone has keyed since the last ID, the controller starts trying to

send a pending ID. Like with the initial ID, it will wait a while for you to unkey to avoid sending a voice

ID while you are keyed up. If you unkey, it checks to see if you have chosen to have the pending IDs

rotate through their cycle, or whether you want them selected randomly, and sends that ID. If you don't

unkey before the impolite ID timer runs out, it calls the impolite ID instead.

To summarize, with the default timer settings, the controller will ID every 9 minutes during a conversation and one more time after the last time the repeater is keyed. If it can, it will send a voice ID;

otherwise it will send a impolite CW ID. It will not ID at all if no one is using the repeater. You can

change the ID timers if you want to, but make sure you set the pending ID timer to be shorter than the

initial ID timer (at least a second) and that the duration of the pending ID timer plus the impolite ID-

timer

is less than 10 minutes (or whatever the legal maximum time between IDs is). The initial ID timer-

can be

as long as you like. Since the only thing that causes IDs to be sent is someone keying up, you-should also

include your ID in messages that may be sent spontaneously such as scheduled messages (time on the

hour for example) or analog alarms.

# 085: Enable/Disable IDing a Port

This command allows you to enable or disable the IDing functions for a port. Normally all ports are

identified, including link ports. Often this is not desired. This command allows you to turn off the-

**IDing** 

\_functions.

This command also lets you specify whether the controller should use the pending ID messages or the

impolite CW message during conversations. If you choose the latter, the controller won't even try to

send voice IDs during conversations (after the initial ID); it will always use the impolite CW ID-message.

If you choose voice IDs, it will try to sneak in a voice ID when you unkey. If you key upduring the

voice ID and it is programmed to be polite, it will switch to CW at that point.

<085> pp I

Enable or disable ID

<085> pp I 0

Enable or disable ID. Use pending

IDs during conversations

<085> pp I 1

Enable or disable ID. Use impolite

CW ID during conversations.

#### Parameters:

- 085 is the default command name.
- pp is the port for which to enable or disable the IDs (01..12)
- \frac{\frac{1}{2}}{2} is 1 to enable IDs, 0 to disable them

#### Defaults:

IDs are enabled only on port 1.

The controller tries to use voice IDs during conversations.

#### Notes:

If you only want to disable some of the IDs for a port, keeping the pending IDs but not the

initial

ID, for example, just erase the ID macro that you don't want to do anything (see Chapter 8 for macro definitions).

086: Recall Which Ports have IDs Enabled

This command lists the ports that have IDing enabled. If all ports do, it speaks "010203040506070809101112".

< 086>

# Parameters:

- 086 is the default command name.

087: Set Random or Rotating Pending IDs

This command allows you to select whether the four pending IDs for a port will be sent in random order or whether they will just be rotated through (1, 2, 3, 4, 1, ...).

<087> pp-

#### Parameters:

- 087 is the default command name.
- pp is the port for the IDs (01..12)
- C is the ID control, 1 for random, 0 for rotating (default is rotating)

088: Recall Random or Rotating Pending ID Selection

This command allows you to recall which ports rotate through the pending IDs (1, 2, 3, 4, 1, 2, 3, 4, 1, 2,

) and which ones select them in random order. others are random.	Voice response will list the ones that rotate, the
<088>	
Parameters: - 088 is the default command name.	

## Chapter 12: I/O System

# About the I/O System

Note that you can control how often the RLC-DSP404 checks the analog/digital input lines and analog

alarms by using Command 020 to change the duration of timer 48. The default is to check the alarms

once per second.

# Open Collector Output Lines

When turned on, an open collector output gets connected to ground; when turned off it is an open

circuit. The open collector output lines never output any voltage. The way they are commonly used is to

connect one lead of the coil of a relay (or whatever else you want to control) to 12 volts and the other

lead to an open collector output line. When the open collector output is turned on and applies a ground,

the coil of the relay will be energized and will turn the relay on. The open collector output line can-

"sink"

\_(apply a ground of) about 150 milliamps. Connecting an open collector output line directly to appower

supply and turning it on will destroy the output driver. Make sure that whatever you are turningon and

\_off draws less than 150mA.

The open collector output lines can be turned on and off with Commands 093 and 094. You can recall

whether a line is currently on or off with Command 095. If you want to speak a custom message when

you turn an open collector output on or off, program one of the user macros to speak the message you

want, execute Command 038 (to suppress the rest of the voice responses), and then turn the open collector output line on or off.

# Digital Input Lines

Digital inputs lines can only distinguish between two levels, high and low. If the voltage on the input is

below 0.5V, it will consistently read low. If it is above 2.0V, it will consistently read high. If it

is

between 0.5 and 2.0V, it may read inconsistently. If the connected device does not keep the voltage high

enough or low enough to read consistently, you may need to buffer it with a relay or transistor. Do not

apply negative voltage to an input line.

If the digital input line has a pullup resistor, it can be directly interfaced with an open collector output or

a switch with one lead connected to ground. When open collector output or switch does not pull the line

low, the pullup resistor will make sure it reads high.

Digital input lines can be used in three ways.

- -Command 090 can read an input line and tell you whether it is high or low.
- A custom voice message can be assigned to each state of an input line, such as "door open" and

"door shut" (instead if high and low). To do this, program the voice messages you want to be spoken for the high and low states into the input line macros (see automatic macros in Chapter 8).

- You can then cause the appropriate message to be spoken by executing Command 091.
- If you want a message to be spoken whenever an input line changes from high to low or low to

high, you can cause the macros you programmed in the step above to automatically be executed

at those times by enabling an "input line alarm" with Command 092. You could use this feature

along with a door switch to tell you when someone opens or closes a door.

# **Analog Input Lines**

When an input line is used as an analog line, the way the voltage is interpreted can be customized, so

rather than telling you the voltage directly, the controller can convert the voltage to a temperature,

percentage, wind speed, etc. The information needed to set up a variety of common conversions is

provided in a chart (see command 102). If you have an unusual application, it is possible to set up a

custom conversion scale.

If you need to set up a custom conversion scale, you will need to deal with the following issues:

"Resolution" refers to how many digits after the decimal place you want to know about. Temperature is

usually read to the nearest degree, zero digits after the decimal. When reading a battery or power supply's voltage, you probably want to hear more than "thirteen volts" or "fourteen volts", something like

"thirteen point six volts". To obtain this kind of reading, you would specify one digit after the decimal point.

The "conversion ratio" specifies how the controller interprets the voltage it detects. It could also be

called the "scale" or "meter faceplate". If you are measuring wind speed, you may want a reading that

varies from zero to 100 MPH. If wind direction, zero to 360 degrees. If pH, zero to 14. If temperature,

way below zero to a hundred degrees or more. No matter what scale you want the reading to use, the

voltage going into the analog line must be between 0 volts and 5 volts. If you have a sensor to measure

something in the physical world that can provide a voltage that varies between 0 volts and 5 volts, you

can set up the conversion ratio to handle it. The point of this discussion is to make it clear that the

controller does not care what the real-world quantity is, it just needs a variable voltage and the proper

conversion ratio. You tell the RLC-DSP404 what the conversion ratio is by specifying two points:

The first is what real world quantity would cause the sensor to output 0 volts. In many cases this

is zero. For example, if you are using a small motor with a propeller to detect wind speed and the

<u>the</u> wind is not blowing, you will get 0 volts. But what about temperature? If our sensor outputs  $\theta$ 

ovolts for zero degrees, how would we get negative temperature readings? The analog lines can

only accept positive voltages. The answer is that we use a temperature sensor that outputs about

2.5 volts at zero degrees, less than that when below zero and more than that when above zero.

So our first conversion point for temperature says that it would have to be 460 degrees below zero to

get 0 volts out of the sensor.

The second point we set specifies what real world quantity would cause the sensor to output 5 volts. If your wind speed detector outputs 5 volts when the wind is blowing 150 MPH, this point

would be 150. For the temperature sensor we use (the LM335), it would have to be 440 degrees

out to get 5 volts out of the sensor.

"Calibration" refers to correcting for small errors in a reading. If the controller tells you it is 85 degrees

when it is 88, you can calibrate it to correct for the small error. If it is way off, you probably have the

conversion set wrong.

You can also set "analog alarms". These will cause a macro to be executed whenever the value read on

one of the analog lines goes above or below a preset value. See Commands 104..107 for more information.

# 090: Read Whether Digital Input Line is High or Low

This command allows you to read the digital input lines. The controller will speak a message that

indicates whether the line is high or low. <u>Each input has a pullup resistor; it will read high if</u> <u>not</u>

connected.

<del><090>11</del><090>11

Read single digital input line

<090> <del>11..</del>\_11

Read multiple digital input lines

#### Parameters:

- 090 is the default command name.
- ll is the digital input line number ( $\theta + \underline{1}$ ...16)

#### Notes:

To provide customized messages for the digital input lines, see Command 091.

091: Execute Digital Input Line High or Low Macro

This command is similar to Command 090. The difference is that instead of speaking the word "high" or

"low", the high or low internal macro for that digital input line will be executed. This allows you to

program custom messages such as "door open" and "door shut". See Chapter 8 to find the macro numbers for each digital input line.

<091>11

Execute macro for one digital input line

<091>11..11

Execute macros for multiple digital input lines

#### Parameters:

- 091 is the default command name.
- Il is the digital input line number (011...16)

#### Notes:

Multiple digital input lines can be read with one call to this command by entering more than one port number here.

# 092: Enable/Disable Digital Input Line Alarm

This command allows you to turn on digital input line alarms that will occur whenever an digital input-

line

goes high or low. When the alarm occurs, it will execute the digital input line high or low macro.

Note

that these are the same macros that get executed by Command 091 whenever the digital input line-

is read.

The high and low alarms can be enabled or disabled separately.

<092>11 a c

#### Parameters:

- 092 is the default command name.
- ll is the digital input line number (011..16)
- A is 1 for the high alarm, 0 for the low alarm
- C is 1 to enable the alarm, 0 to disable it

#### Note

There is currently no command to recall whether the digital input line alarm is turned on or off.

# 093: Turn Open Collector Output Line On

This command allows you to turn an open collector output line on. The outputs are active low open

collector drivers, so on means that they apply a ground to that open collector output. Off means that the

open collector output is open, or not hooked to anything.

# <093>11

Turn a single open collector output line on

#### <093>11..11

Turn multiple open collector output lines on

#### Parameters:

- 093 is the default command name.
- Il is the open collector output line number ( $\theta + \underline{1}$ ...16)

#### Notes:

To provide customized messages when turning open collector output lines on or off, use a macro

that both executes this command and the speak voice message command (036).

# 094: Turn Open Collector Output Line Off

This command allows you to turn an open collector output line off. The outputs are active low open

collector drivers, so on means that they apply a ground to that open collector output. Off means that the

open collector output is open, or not hooked to anything.

# <094> 111

Turn a single open collector output line off

#### <094>11..11

Turn multiple open collector output lines off

#### Parameters:

- 094 is the default command name.
- Il is the open collector output line number ( $\frac{0+1}{2}$ ..16)

#### Notes:

To provide customized messages when turning open collector output lines on or off, use a macro

that both executes this command and the speak voice message command (036).

# 095: Recall Whether Open Collector Output Line is On or Off

This command allows you to recall whether the open collector output lines are turned on or off.

<095> <del>1</del>11

Check a single open collector output line

<095>11..11

Check multiple open collector output lines

#### Parameters:

- 095 is the default command name.
- Il is the open collector output line number ( $\theta + \underline{1}$ ...16)

#### Notes:

To provide a customized message when an open collector output line is turned on or off, call Commands 093 or 094 from a macro that also speaks a voice message. There is no easy way to get a

customized message to recall whether a line is on or off at the current time without turning it on or off

again. If you really need custom recall messages and you are very familiar with macro programming,-

read

\_the following, otherwise don't bother. The idea is to use a macro to call the open collector output-

line on

and off commands. Also in that on/off macro, call the program-single-command-macro-command and

\_program another macro (we will call it the recall macro) to speak the appropriate recall-message. That

\_recall macro could then be executed to find out whether the open collector output linewas turned on or

off last. In other words, we would use the on and off macros to program the recallmacro. Whichever

on/off macro was executed last would have programmed the recall macro last, making it contain the

appropriate message. If you didn't understand all of this, don't worry about it, use-this command, and

wait for a later software version that will make all of this easier.

# 100: Read Analog Input Line

This command allows you to read the analog input lines on the RLC-DSP404. The number that is read

back will depend on three other things: the precision used (set with Command 101), the conversion-

scale

(set with Command 102), and the calibration (set with Command 103). When you want to read the

analog lines as part of a custom message such as "The temperature is ??? degrees Fahrenheit" you should

use the read-analog-input special words (see words numbered 800 and higher in Appendix B). They will

allow you to read the analog input without all of the extra " Line ?" words that you won't want in your

messages.

 $<100>\frac{11}{11}$ 

Read a single analog line

<100>11..11

Read multiple analog lines

#### Parameters:

- 100 is the default command name.
- ll is the analog input line number (0+1..16)

#### Notes:

Multiple analog input lines can be read with one call to this command by entering more than one

port number here.

# Example:

Command 100 works fine, but I want a nicer message when reading wind speed. 053 erases then

starts programming a macro. 600 is the macro number. 036 is the command to speak a voice message.

The following numbers come from Appendix B and specify the words for the message. Word 838 is a

special word number that the controller automatically replaces with the current reading for analog line 3.

; Speak "The wind speed is (analog 3) miles per hour" 053 600 036 476 531 452 270 838 <del>003 -</del>317 375 249

## 101: Set Resolution For Analog Input

This command allows you to specify how many digits after the decimal point will be used when reading

each analog input line. If you want to read voltage to 1/10 of a volt, you specify one digit after the

decimal point. This decimal point is assumed in the other analog commands since there is no good way

to enter a decimal point on a DTMF pad. If you specify one decimal place with this command, the other

analog commands will assume that the numbers you enter have an assumed decimal point one digit from

the end. In other words, if you want to specify a value of 12 volts and you are using one digit after the

decimal point, you must enter 120. The descriptions of those commands will explain this in more detail.

<101>11 r

#### Parameters:

- 101 is the default command name.
- ll is the analog input line number (011..16)
- R is the number of digits after the decimal point (0..3)

#### Explanation:

This command may allow you to read an analog input with more decimal places than the controller can

accurately measure. That doesn't hurt anything, but may be misleading (such as indicating that the

temperature is 75.251 degrees when you really only know it is within about one degree of 75). \_ \_ The

analog to digital converter (ADC) in the controller accepts a voltage between 0 and 15 volts (higher

voltages may be reduced to that range with an external seriesal resistor on t). The out of range analog input.)to digital converter

and can differentiatedistinguish between 4096 (or 12-bit resolution) voltage levels within that range, providing a resolution of about 3.66mV per level.

LM335 temperature sensors output a voltage of 10mV per degree Kelvin (Celsius - 273). This corresponds to For each

<u>change in temperature of one degree Fahrenheit, the voltage will change</u> about 5mV (10mV \* 5/9) <u>per degree Fahrenheit</u>, about <u>one-half degree resolution</u>. There

is no reason to try to read

the same as the resolution of the ADC. In other words, the controller can determine what the temperature is to the nearest degree. You could tell the controller to speak the temperature with two decimal places when conversion itself doesn't have that

much resolution. Even one digitone or

<u>two digits</u> after the decimal point is pushing it - it would sound like you were getting 1/10 degree resolution even though you would really only be getting about « degree resolution.

We recommend reading, but it wouldn't give you significantly more information. It generally works best to read the temperature to the nearest degree (0 digits after the decimal point).

Another example: reading battery voltage. Since the controller requires 12 or so volts to run, the

processor's analog to digital converter reads the power supply voltage directly. So analog input line #4 is

connected to the controller's power input. To your battery probably supplies between 12 and 14 volts, less than the 15 volt maximum of the analog inputs, it can be connected directly to an analog input

<u>line (a fuse would be a good idea). It can then be read a resolution of about 3.66mV; you can choose</u>

<u>how many decimal points to</u> make the controller <del>read the power supply voltage, we</del> need to set it to convert the value read on a scale of 0..15V. This can be done by entering

```
102 08 0 0000 0 0015; read analog input 8 on 0 to 15 volt scale
101 08 0; report.
```

```
101 4 1; read analog input 84 with no1 decimal places
102 4 0 0000 0 0150; read analog input 4 on 0.0 to 15.0 volt scale
```

<u>or</u>

101 4 2; read analog input 4 with 2 decimal places
102 4 0 0000 0 1500; read analog input 4 on 0.00 to 15.00 volt scale

## 102: Set Conversion Ratio For Analog Input

This command allows you to select what scale the analog inputs are read on. This allows you to use the

analog inputs to read temperature on a scale from hundreds of degrees below zero to hundreds above:

<u>(see Appendix H)</u>, battery voltage on a scale from 0 to <u>25 volts 15V</u> or wind direction from 0 to 360 degrees. -

Anything that can

generate an analog voltage can be read on a scale appropriate to the measurement.

Unfortunately, this

flexibility brings with it a little complexity. To make it easy, we provide a chart of the common conversions you might use. If you want to use a conversion that is not listed, read the explanations after

the chart and study the examples on the chart. Once you see the pattern, the calculations are not difficult

<u>The chart below shows some commonly used conversion ratios</u>. If you have a different type of sensor

and need a different conversion ratio, there is information after the chart about how to calculate the

needed values.

Command Parameters Description Resolution

```
<102> xx ll n wwww m zzzz
General conversion form
```

<102> xx<u>||</u> 0 0000 0 1023 Default Setting 1 analog to digital converter count

<102> 08 0 0000 0 0250 Internal Battery Voltage 0.1 volts, enter "101 08 1"

<102> xx 1 0460 0 0440 1500

# Voltage from 0.00 to 15.00 (default setting) 3.66 mV

# <102> 11 1 0460 0 2240

Fahrenheit temperature 1 degree, enter "101 x 0"

<102> xx | 1 0273 0 0227 | 1227 Celsius temperature 1 degree, enter "101 x 0"

<102> xx 0 0000 0 0005 0..5 volts 1 volt, enter "101 x 0"

<102> xx 0 0000 0 0050 0..5 volts 0.1 volt, enter "101 x 1"

<102> xx 0 0000 0 0500 0..5 volts 0.01 volt, enter "101 x 2"

<102> xx 0 0000 0 0025 0..25 volts 1 volt, enter "101 x 0"

<102> xx 0 0000 0 0250 0..25 volts 0.1 volt, enter "101 x 1"

<102> xx 0 0000 0 2500 0..25 volts 0.01 volt, enter "101 x 2"

```
\frac{102 \times xx}{11} 0 0000 0 0100
0 to 100%
(of the 0..15V input range)
1 percent, enter "101 x 0"
\frac{102 \times xx}{11} 0 0000 0 0360
0 to 360 degrees
\frac{15V = 360 \text{ degrees}}{1}
1 degree, enter "101 x 0"
```

#### Notes:

-Please note that regardless of the conversion used, the voltage entering the analog inputs must be

between 0 and  $\frac{515V}{}$  volts.

-For more information about hooking up a LM335Z temperature sensor, see Appendix H.

#### Parameters:

- 102 is the default command name.
- xx1 is the analog input line number ( $\frac{01}{1}$ ..16)
- n is 1 for negative, 0 for positive for the following number
- wwww is the reading with a 0 volt input with leading 0s if necessary
- m is 1 for negative, 0 for positive for the following number
- zzzz is the reading with a 5 volt input to the processor with leading 0s if necessary.

# **Custom Analog Conversion Ratios:**

If the conversions provided in the chart are what you need, don't bother reading this section. It describes

how to come up with your own conversions.

The conversion is simply a linear ratio. You provide a reading that corresponds with 0 volts at the ADC

processor(analog-to-digital converter) and another number that corresponds with 5 volts at the processorADC, and the-

controller just does

\_a linear interpolation.

First we will describe some of the conversions in the table, then illustrate how to come up with your own:

#### 0 to 15 volt, 1 volt resolution:

This is about as straightforward as it can get. When it reads 0, it converts it to zero. When

#### the

processor reads 15 volts, it converts it to 15 volts.

#### 0 to 15 volt, 1/10 volt resolution:

When it reads 0, it converts it to zero. To get 1/10 volt resolution, we need to use one digit after

the decimal point. Because of this we have to assume one decimal point when we enter the conversion

points. When the processor reads 15 volts, we need to convert to 150, which with one assumed decimal

place, is 15.0 volts.

own:

#### 0 to 15 volt, 1/100 volt resolution:

When it reads 0, it converts it to zero. To get 1/100 volt resolution, we need to use two digits after the decimal point. When the processor reads 15 volts, we tell it to convert it to 1500, which with

onetwo assumed decimal places, is 15.00 volts.

# Temperature in Celsius, 1 degree resolution, no voltage dividers:

The key to figuring this one out is knowing how the LM335 temperature sensor works. It provides an output voltage of 10mV per degree Kelvin. It should therefore output zero volts at zero

degrees Kelvin. Zero degrees Kelvin is minus 273 degrees Celsius, so that is our first conversion point, -

273. The 15 volt conversion point would be reached at  $\frac{15V/10mV}{5V/10mV}$  per degree = 1500 degrees Kelvin, or

1227 degrees Celsius (above zero). This is our other conversion point.

# Temperature in Fahrenheit, 1 degree resolution, no voltage dividers:

This conversion is very similar to the one for Celsius temperature. 0 degrees Kelvin is -460 degrees Fahrenheit. 5001500 degrees Kelvin is 4402240 degrees Fahrenheit.

One more example will illustrate how to develop a conversion that is not listed in the chart. Let us

assume that we want to read the wind speed at our site and that we have an anemometer (wind speed

detector) that reads 10 volts at 100 MPH. Since the maximum voltage is below 15 above 5 volts no external

divider is necessarywe will need to

use a voltage divider. To avoid having to disconnect the pullup resistors on inputs 1..3 (which is necessary to use a voltage divider with them), we will use analog input #5 and make our own external

<u>voltage divider.</u> The divider will have the input voltage coming through a 40.2K resistor in series with a

10K resistor. The other end of the 10K should be hooked to ground. Analog input #5 should be connected to the point where the two resistors are joined, where the voltage should be about 1/5 what it

<u>is at the input of the voltage divider</u>. We will assume that 0 volts are produced when the wind is not-

blowing and that it

\_increases linearly from there. That sets our zero point to be zero. We must calculateour full scale

reading as if it will occur at  $15\underline{\underline{V}}$  volts, even though the sensor will never put out that much voltage. What

we need to know is how fast the wind would have to blow to give us a 15 $\underline{\underline{V}}$  volt signal. Asimple ratio will

\_give us the answer:

```
100 MPH = X MPH

10 volts 15\underline{\underline{V}} volts

Cross Multiplying: \underline{\underline{\phantom{A}}} 100 * 15\underline{\underline{V}} = 10 * X;

\underline{\underline{\phantom{A}}} 1500 = 10 * \overline{X};

\underline{\underline{\phantom{A}}} X = 150 MPH.
```

We now know that the low point is 0, the high point is 150, and that so we need to can set usep the voltage divider conversion with 102 0 0000 0 0150.

# 103: Calibrate an Analog Input

This command allows you to correct for small amounts of error in reading analog sources. It should not

be used until the resolution and conversion ratios are set (with Commands 101 and 102). It is not intended to fix readings that are way off (more that 20 percent or so). If you are getting a reading that is

a long way off, go back to Command 102 and correct the conversion ratio. This command accepts as

input the correct value for an analog input line and adds or subtracts the right amount from the reading it

is receiving to make it equal what you say it is. To get rid of <u>(zero out)</u> this correction factor, execute the-

reset

\_calibration form of this command shown in the table below.

<103> ll n wwww Calibrate an analog input

<103>11 2 Reset calibration

#### Parameters:

- 103 is the default command name.
- Il is the analog input line number ( $\theta + 1 = 1.16$ )
- N is 1 for negative, 0 for positive for the following number
- WWWW is the actual value that should be read by the sensor.

#### Notes:

The value you enter will have as many assumed decimal places as you set with Command 101.

# 104: Set an Analog Alarm

This command allows you to set an alarm that will occur when an analog reading goes below a low-

alarm

point or above a high alarm point. When the alarm occurs, it will execute an internal macro (see

# Chapter

8 for internal macro definitions). You can program this internal macro to do anything, turn open collector output lines on or off, speak a voice message, change your courtesy beep, etc. The alarm point

will be checked at intervals determined by the duration of the input alarm timer (see Command 020).

When the analog reading comes out of alarm by the "Hysteresis" amount (set with Command 105), the

analog alarm clear macro will be executed. You might want to program this macro to change an open

collector output line and/or speak an alarm clear message.

<104> ll a n wwww Set an Analog Alarm

#### Parameters:

- 104 is the default command name. —
- ll is the analog input line number (011..16)
- A is 0 for a low alarm, 1 for a high alarm
- N is 1 for negative, 0 for positive for the following number
- WWWW is the alarm point with leading 0s if necessary

#### Notes:

The value you enter will have as many assumed decimal places as you set with Command 101.

## 105: Set Analog Alarm Hysteresis

Hysteresis is a concept not everyone is familiar with, so let me illustrate it before I try to explain how to

use it. Let us suppose that you are using one of the analog lines to read the temperature inside of your

radio shack. In the winter, you want the controller to automatically turn the heater on and off to keep the

temperature above 40 degrees. To do this you decide to control the heater with a relay that you can

switch with one of the open collector output lines. Next you set a low alarm at 40 degrees and program

the low alarm macro for that analog line to turn the heater on and speak the message "low alarm". Now

you need a way to turn the heater back off. To do this you use the analog alarm to normal macro to turn

the heater off and speak the message "low alarm clear". This is where Hysteresis comes in. Do you-

want

the heater to turn off at 41 degrees? This would probably make the heater turn on and off really-often. It

might be better if it warmed up to 45 degrees before the heater turned off, so it would turn onand off less

often. The amount that it has to warm up past where the low alarm point was is the amount of

Hysteresis, in this case 5 degrees. In the case of a high alarm (such as would be used to run an air

conditioner, the amount of Hysteresis is how much the temperature would have to drop below the high

alarm point before the alarm to normal macro would be executed. The amount of Hysteresis is the same

for the high and low alarms (if this is not acceptable for your application, let us know). This command

lets you set how much Hysteresis each analog line uses when determining whether the alarm is clear yet.

<105>11 wwww

#### Parameters:

- 105 is the default command name.
- Il is the analog input line number (011..16)
- WWWW is the alarm point with leading 0s if necessary

# Notes:

The value you enter must be a positive number and will have as many assumed decimal places as you set with Command 101.

# 106: Enable/Disable an Analog Alarm

This command allows you to control whether or not the analog alarms will occur without having to mess

with the alarm points. This might be used to turn off a low temperature alarm while you are working at a

site and have the door open or to disable turning a heater on when you are running on battery power. If

an alarm is disabled, Command 107 will still tell you whether or not the line is in alarm, but the alarm

macro will never execute.

<106>11 a n

#### Parameters:

- 106 is the default command name.
- Il is the analog input line number (011...16)
- A is 0 for a low alarm, 1 for a high alarm
- N is 1 to enable the alarm, 0 to disable it

107: Recall Analog Lines in Alarm

This command lists all of the ports in high alarm, then all of the ports in low alarm. It is helpful when

trying to find out whether you have set the alarm points correctly.

<107>

#### Parameters:

- 107 is the default command name.

# 108: Recall Analog Line Configuration

This command recalls all kinds of information about an analog line's conversion, resolution, calibration,

alarm points, Hysteresis, alarm enabled/disabled status, etc. It is intended to aid in setting up the analog

subsystem, not as a user command.

<108 > 11

#### Parameters:

- 108 is the default command name.
- Il is the analog input line number (011...16)

Description of the voice response:

"analog?" - which analog input on the I/O board we are referring to (1..5)

"0 volts is?" - the lower calibration point

"5 volts is?" - the upper calibration point

"calibrate?" - how many units the calibration changes the reading

"low alarm?" - the low alarm point

"high alarm?" - the high alarm point

"h?" - the amount of Hysteresis

"low alarm?" - whether alarm is on or off

"high alarm?" - whether alarm is on or off

160: Clear Analog High/Lows

This command allows you to reset the analog high/low values. They are reset to whatever the current

value is. The readings can be read by speaking the appropriate word numbers (see Appendix B).

 $<160 > a_1 11..11$ 

# Parameters:

- 160 is the default command name
- A is 0 for the low value, 1 for the high value, 2 to clear both the low and high values
- ll..ll are the analog input lines (011..16)

161: Set Analog Smoothing Factor

This command allows you to smooth the analog readings to "average out" noise and sudden changes.

<161>11 ss

# Parameters:

- 161 is the default command name.
- Il is the analog input line (011.16)
   SS is the smoothing factor

**Smooth Factor** Average Smooth Time

50 about 9 seconds

60 about 13 seconds

70 about 18 seconds

80 about 30 seconds

90 about 50 seconds

95 about 120 seconds

97 about 220 seconds 98 about 325 seconds

99 about 11 minutes

# 109: Configure Wind Speed Reading

This command can be used to tell the controller to count the pulses coming from an anemometer (those

whirly things with three cups that spin in the wind) to determine the wind speed. It counts the number of

pulses in a default of 2.26 seconds and treats that number like a voltage that could be read by an analog

line. All of the normal analog commands will work with the resulting number: command 102 will-

control

the scaling, command 100 will provide the current reading, the analog alarms can be used tonotify you if

\_the wind exceeds a certain speed, etc.

<109>0

Don't calculate wind speed

<109> xx 11

Use input line 'xx' X' for wind speed

#### Parameters:

\*\*\*11 - the contact closure input line to use for wind speed.

Note:

The "conversion ratio" (see command 102) for the analog line corresponding to the input number

1023" where  $\frac{\mathbf{x} \mathbf{x} \mathbf{l}}{\mathbf{l}}$  is the input line number).

#### Details:

To read wind speed, hook up the anemometer so that the reed switch that closes as it rotates connects the

input line on the controller to ground. Using a voltmeter or logic probe, make sure that the line pulses

every time the anemometer goes around. The line can be connected directly to inputs 1..3, or to input 5

(on pin 4) if you use a 10K pullup resistor to 5 volts. Then use command 109 to tell the controller which

input line it is connected to. From that point on, reading the analog line of that number will give

you a

number related to the wind speed.

To make the controller read the wind speed in miles per hour, you will need to find out how fast your

anemometer pulses relative to the wind speed. One common anemometer (Davis) is rated at 26.6 pulses

per minute per mile per hour. 60/26.6 = 2.2556 seconds to get one pulse per mile per hour. The wind

speed timer is set to count the pulses in 2.26 seconds. If the analog conversion ratio is left at the default

1:1 (it can be changed with command 102), the analog line will read the speed in miles per hour. The

wind speed measurement can be adjusted by changing the timer or by changing the conversion ratio with

command 102. Using the calibrate command for wind speed is not recommended, as any calibration

offset will keep it from reading zero when it is calm. You can use command 100 or the analog special

words to make the controller speak the wind speed.

## 096: Control or Recall Extended Output Lines

"Extended" output lines provide a way to control more external devices or signals than the number of

open collector output lines built into the controller (or option boards). By connecting external shift

registers such as are used on many BCD boards to three of the controller's open collector output lines,

you can control up to 64 "extended" output lines. Whenever command 096 is executed to set or recall

the state of an extended output line, the controller shifts out 64 bits of information representing the state

of each of the outputs. Extended output line 64 is shifted out first, line 1 last. The data is also shifted-

out

when the controller is reset and the extended outputs are enabled (you should not enable the extended

output lines if you are not using them, or output lines 5, 6 and 7 will get messed up every timethe

\_controller resets).

< 096 > 0

Disable the extended output lines (the default)

< 096 > 1

Enable the extended output lines

<096> xx

Recall the state of extended output line "xx"

<0.96> xx.1

Turn extended output line "xx" on

<096> xx 0

Turn extended output line "xx" off

#### Parameters:

XX - the extended output line number (two digits, 01..64)

## Details:

Most standard shift registers should be compatible with this command. Up to eight 8-bit shift registers

can be chained together, each one providing eight more extended outputs. If the shift registers have

separate output registers (like the 74HC595 or 4094), the latch line can be used to keep the outputs from

rippling each time new data is shifted in.

Open Collector Output Line Number Description

5 Latch - Optional, but will prevent the lines from "rippling" as data is shifted if used

6 Clock - pulses 64 times to shift data out

7
Data - goes high or low for each clock pulse.
If using the RBI-1 or RLC-ICM, this line will be shared. Both should work normally.

# Chapter 13: Autopatch Routines

## Configuring the Autopatch:

Command 110 is used to enable and configure the autopatch. The autopatch uses port 4 when installed.

It allows you to specify which radio port

the autopatch is plugged in to and whether or not you want the autopatch to speak the number it is about-

to dial

using the synthesized voice. If you select to have the number read back, you can choose whether

it

should read it back "politely" (so it can be interrupted by kerchunking) or "impolitely" (so it always-

reads

\_back the whole number). See command 044 in Ch 6 for DTMF regenerate parameters.

# Autopatch Up Commands:

There are three<u>several</u> different commands that can be used to access<u>place a call using</u> the autopatch. All of them-

connect the

\_port that the command was entered from (and any ports connected to it) to the autopatch. These

commands should not normally be executed from from the serial port or by the scheduler (how do you

because there

<u>is no way to connect an autopatchthe audio</u> to <u>a scheduler?them</u>). They are:

-Manual Off Hook: Command 111. This command connects the radio port to the phone line without dialing any numbers. You can dial phone numbers without DTMF regeneration by executing this command, waiting for dial tone, and entering the number on your DTMF pad. Since the tones are not captured and regenerated but go out directly onto the phone line, there

is

no long distance checking, etc.

-Normal Forward Dial: Command 112. This command is the one you would usually make available to users. Three digit numbers will access autodial slots, 4 through 11 digit numbers will

will be checked against the dialing tables (explained later), then regenerated over the phone line. H

If you have specified pre-dial digits (such as a '9' to get out of a local PBX) with Command 116,

they will be dialed first.

-Special Forward Dial: Command 113. This command is similar to the normal forward dial but it

bypasses the dialing table checks. It is the most convenient way to bypass all of the long distance

checking. It will dial any predial digits that you have programmed with Command 116.

-Two-Stage Patch: Macro 552. The user can execute this macro, unkey and hear dial tone, then

key up again to enter a phone number. The phone number will be processed by command 112,

which will check it against the long-distance dialing tables and regenerate the DTMF digits. For

users that aren't used to entering the patch up code (often '\*') and phone number all at once before

unkeying, this macro may reduce confusion.

Using '\*' for the Autopatch Up Command:

You can use the '\*' digit to execute any of the above autopatch commands. Simply rename your autopatch command to a '\*' using Command 010 ( "010 112 \*" for example). This will allow you to use

the patch by simply keying up, pressing '\*', then and the phone number you wish to dial then unkeying.

Macro 552 and command 112 can both be named the same thing (such as '\*') without causing problems.

The controller knows that command 112 requires more digits to be entered at the same time as the

DTMF command name and that macro 552 does not, so it will execute the appropriate command automatically.

# Hanging Up:

No matter which command was used to bring up the autopatch, Command 114 will hang it up. If you

want to have more than one hang up command, just make several different macros call Command 114.

You can rename command 114 to '#' by entering "010 114 #" unkey, 'D' or <Enter>.

Command 115 can also be used to hang up the patch. It differs from command 114 in that it will not

hang up the patch from a radio port that is not part of a call in progress. For example: port 1 and port 2

are running independent repeaters (they aren't connected), and port 1 makes an autopatch call. Port 2

continues to operate normally, unaware that the autopatch is in use. Then someone on port 2 decides to

make a call on the patch and gets the autopatch busy message. Rather than waiting for the user on port 1

to finish their call, the person trying to make a call on port 2 decides to hang up the patch so he can make

his own call. If he uses command 115, the controller will not hang up the patch because port 2 is not

connected to the autopatch. If he uses command 114, it will. Either command will work to hang up the

patch if they are entered from port 1, the port that made the call. Often command 115 is used as the

primary hang up command and command 114 is reserved as a control operator command, to be used-

only

when an emergency mandates hanging up someone else's call. Resetting the controller with-command

\_035 also hangs up the patch and can be executed from any radio port.

#### Connected Ports:

Any ports that are connected to the port you make the <u>If an</u> autopatch call from will also be included in the

autopatch call. Any ports being monitored by the port you make the is placed from a port that is in a group (connected to other ports), the autopatch will

also be placed in that group for the duration of the call so that all of the connected ports will be able to

hear the conversation. If an autopatch call from will be

monitored by the patch. For example, if you have connected repeaters and someone wants to make a call

from one of them, you can bring the patch up for them from the other one. (This is done internally by

disconnecting all ports from the patch, then "smart connecting" it to the port that is placing the call in the

same way that command 008 works is placed from a port that is not in a group, by default the controller will put both that port and the autopatch port into group 3 (to connect them together). You

<u>can change which group is used for that purpose by editing the before-patch-off-hook macro (see</u> Chapter 8).

# Predial Digits:

Autopatches that are on a PBX often have to dial a '9' or some other combination of digits to reach the

outside world. The RLC-DSP404 has the ability to dial these digits for you. You can tell it what

digits

to dial and how long of delays to use before and after these "predial digits" with Command 116. These

digits will be dialed before every number that is dialed with the forward dial commands. You can-

choose

whether or not they should be dialed before each autodial number. This allows you to dialnumbers that

\_do not require the predial digits by putting them in an autodial slot.

## The Autodialer:

There are 501 autodial slots that can each hold up to an eighteen digit phone number. They are numbered 0 through 500. They can be accessed by executing either of the forward dial commands with

the number of the autodial slot you want to dial. They can be programmed with Command 124.

can

\_find out what number is in an autodial slot with Command 125. You can select whether or not the

predial digits (set with Command 116) get sent before the autodial number with Command 126. This is

useful for those using a PBX because it allows them to have some autodial slots go to internal numbers

and some to dial the predial digits to get to the outside world. Command 127 allows you to enable or

disable the use of an autodial slot. This allows you to keep an autodial number from being dialed

## without

erasing the slot and having to re-program it later.

# Limiting Call Duration:

The time out timer for the autopatch port limits the total duration of the call. If the timer expires, it will

execute the autopatch port's time out macro (see Chapter 8) and hang the autopatch up. If you would

like a message to be spoken when this happens, put the commands to speak that message in the time out

macro. If you do not want the autopatch to time out, set the timer's duration to 9999 with Command

020. You will probably want to erase the contents of the time out clear macro for the autopatch port

with Command 055.

You will be warned before the patch times out. Thirty seconds before timeout, three beeps will be sent

out of the radio port and down the phone line (so both sides of the conversation know it). Two beeps are

sent twenty seconds before, and one ten seconds before. The CW characters 'S', 'I', and 'E' are used for

these warning beeps by default, but you can change them (or eliminate them altogether) using the event

triggers (see Chapter 20).

To reset the patch time out timer during a call, use Command 022 to reset timer  $124\underline{99}$  (see Chapter 4 for

more information about timers) by entering "022 1<del>24</del><u>99</u>" and unkeying. You could make macro 600 extend

the patch timer using the code \*\*3 as follows:

```
053 600 030 18 D or unkey; send CW 'I' as a beep-beep response 056 600 038 D or unkey; be silent for rest of macro 056 600 022 12499 D or unkey; reset patch time out timer 010 600 **3 D or unkey; rename macro 600 to '**3'
```

How the Dialing Tables Work:

The dialing tables are used to control which long distance numbers can be dialed with Command 112-

and

which cannot. They do not affect autodial numbers or numbers dialed with Command 113. If you

attempt to dial a number with Command 112 that is not allowed you will get an error 212 (you can

disable or change this error message by editing macro 212 - see Chapter 8). By default all but 7 digit

numbers are blocked (see command 119). Before a number is dialed using Command 112, it must pass

the following tests:

-<u>u</u> All digits in the phone number must be decimal digits. A, B, C, and D are not allowed; if you

need to dial these digits, put them in as predial digits, use an autodial slot or use Command 113.

-<u>u</u> If the number is one, two or three digits and is 500 or less, it will be treated as an autodial number. The autodial number will be looked up, and if it has been programmed, it will be accepted without checking to see if it is long distance or not. It is assumed that whoever programs the autodial slots will decide whether to allow long distance numbers in autodial

slots<del>or</del> or not.

-<u>u</u> If the number matches any entry in the allowed number table, it may be allowed (see the rule below); otherwise it is blocked. In other words, if you don't specifically allow that type of number, command 112 won't allow it to be dialed. By default, allowed number slot 000 is programmed to allow all seven digit numbers (it is programmed to "###", which means, "allow

any three digits followed by any four digits" - see command 119 for more information).

- ig If a number matches an entry in the allowed number table as described above, it is checked against
- the nuisance number table. If it matches one of the entries in the nuisance number table, it is blocked (even though the rule above allowed it). For example, the nuisance number table can be

<u>can be</u> used to keep some seven digits numbers from being dialed even though all other seven digit

digit numbers are allowed.

If the number passes all of the above tests and is accepted, it will be read back (if you turn number

readback on with Command 110) and then dialed.

Both the allowed numbers table and the nuisance number table store each type of number in a separate

"slot". Each slot affects only one length of number, so allowing all seven digit numbers will not affect-

six

or eight digit numbers. You should keep track of what you put in each slot as you program them, so-

that

\_you can easily change them later.

The allowed numbers table has 500 slots, numbered 000..499. Each slot can hold one type of number

that you want to allow. For example, you might want to program slot 0 to allow seven digit numbers-

that

\_begin with the prefix 245, such as 245-5002 and slot 1 to allow eleven digit numbers that begin with

1800. To do this, you could enter Command 119 000 245 D or unkey (where Command 119 is the name

of the command that programs the allowed numbers table, 0 is the slot to store this type of number in.

and 245 is the number we want to allow, ignoring the last four digits). If you instead wanted to

allow all

seven digit numbers, not just 245 numbers, we could enter Command 119 000 ### D or unkey instead.

The # symbol is a wildcard digit that represents any decimal digit. To allow 1800 numbers (using slot 1

so we don't mess up the seven digit numbers we allowed in slot 0), we would enter Command 119 001

1800### D or unkey.

The nuisance number table allows you to block numbers that would otherwise be allowed. It has 100

slots, numbered 000..099. You may not need to use the nuisance number table. It is usually used to

block prank calls. For example, we allowed all seven digit numbers in the allow table example above.

If

someone was calling our fax number (245-4889) with the autopatch as a prank, we could block that

number by entering Command 121 000 2454889 D or unkey. Note that the nuisance number table is

independent from the allowed number table; slot 000 in one table does not interfere with slot 000 in the

other table. The nuisance number table requires that you enter all of the digits of the phone number; it

does not ignore the last four digits like the allowed number table does. The nuisance number table

accepts wildcards. Even if we had allowed all seven digit numbers in the allow table as in the examples

above, we could block seven digit numbers beginning with 554 by entering Command 121 001 554####

D or unkey.

You can check the operation of the dialing tables at any time by either trying to dial a number with the

forward dial command, or just pretending to dial it with Command 123. This command will tell you

whether a number would be blocked by the dialing table or would be dialed, without actually using the

autopatch. Command 123 will work even if you don't have an autopatch.

Other Commands that Affect the Autopatch:

Command 007 (see Chapter 3) allows you to turn the DTMF mute on or off for the autopatch port.

While this does not affect the DTMF digits that are actually generated when the autopatch is

dialing, it

does have several other effects. See the note on command 007 for more information. During anautopatch

- <u>call</u> it is possible to connect and disconnect radio ports from the autopatch port, including or excluding
- them from the remainder of the call. Note that any ports that are included or excluded from the call
- should also be connected or disconnected from the ports that were already a part of the call, so-they can
- hear both sides of the conversation.

# Half-Duplex Links and the Autopatch:

<u>In most cases autopatch calls are placed by users of a repeater.</u> Once a call is connected, the repeater

<u>transmitter typically stays keyed continuously for the duration of the call. When no radios are</u> keyed, the

repeater transmits audio from the autopatch (whatever the person on the phone is saying). When a radio

is keyed, the repeater "repeats" their audio (and typically mutes the audio from the phone, see command

<u>128 for more info</u>). When the call is terminated, the repeater returns to normal operation and <u>transmits</u>

only when someone keys their radio or to send ID, courtesy beeps, hang time, etc.

If the repeater port on the controller is "connected to" (in a group with) other ports (repeater or link

ports) when a call is placed, those other ports will normally also be connected to the autopatch port.

<u>That potentially allows everyone that could communicate using the connected repeaters and links</u> before

the call was placed to continue to talk with each other and with the person on the phone during the call.

Note that the radios connected to those other ports on the controller (not the end-users' radios) will

<u>transmit continuously during the call, just as the repeater does, sending audio from the phone and other</u>

<u>connected radios</u>. This works fine for repeaters and full-duplex link radios, but causes problems for

half-duplex link radios. Those half-duplex link radios will transmit all of the audio as described above.

but because they are continuously transmitting during the call, anyone at the other end of that link will be

<u>unable to respond and be heard. This is not a fault of the autopatch, but a side effect caused by the patch</u>

receiving audio all of the time and the half-duplex link not being able to receive while transmitting.

The RLC-DSP404 deals with this potential problem by providing a way to automatically disconnect any

half-duplex link ports before connecting an autopatch call. The same method could be used, if desired,

to disconnect full-duplex links or cross-band repeaters if desired. Before connecting the autopatch port

to the port that enters the command to complete the call, it calls the "Before patch off hook" event trigger

(???); see Chapter 20 for a list of event triggers. You can use command "157 ??? mmm" to call a macro

when that event trigger is fired. The macro can then be programmed to disconnect any ports that you do

not want included in the call. This can be done by using command 017 to take them out of the talk

group.

# Port Connections During A Call:

<u>This section addresses the same subject as the section "Connected Ports" earlier in this chapter but</u>

provides more details.

The "Half-Duplex Links and the Autopatch" section above mentions that the controller automatically

connects ports to the autopatch. This section provides more details about how that is done by default

and how you can customize it. As described in Chapter 2, ports are "connected" by putting them into the

same "talk group". Naturally, to "connect" the autopatch port to another port, they should be put into the

same group. The question is, "which group?"

If the port that enters the command to complete the autopatch call (typically the repeater port, and referred to as such hereafter) is already in a group, the autopatch port is simply added to that group. It

then automatically becomes connected to all of the ports that were previously in that group (unless they

<u>are removed by a macro called from the "Before patch off hook" event trigger as described above).</u>

If the repeater port is not already in a group but the autopatch port is in a group (typically by itself), the

repeater port will be put into the same group as the autopatch. To ensure that the autopatch port is

always in a group, command 110 automatically programs the "Before patch off hook" event to call a

macro that puts the autopatch port into group 3. That macro can be changed to use a different group if

<u>desired</u>; it should generally be a group that is not used for any other purpose (to avoid accidentally

connecting ports to the patch during a call). If the macro is changed so it does not put the patch

<u>into a</u>

group (not recommended) and the repeater port is not in a group, the patch commands may fail and generate error message 313.

# 110: Configure the Autopatch

This command allows you to enable or disablesets which port the autopatch and allows interface is hooked to and allows you to choose whether and how

the number is read back before it is dialed.

<110> pp s

#### Parameters:

-110 is the default command name.

ppp is the radio port that the autopatch enable/disable control. 0 - Disable the autopatch. 1 - Enable the autopatch.

—is hooked to (01..12). Enter 00 to specify that no ports are

autopatches. If the DSP404 does not have any expansion boards installed (if it has only four radio ports) and the autopatch is connected to the controller with a ribbon cable, the port number

must be entered as 04 and a radio must not be connected to the port 4 DB-9 connector (the autopatch ribbon cable connector and port 4's DB-9 share circuits).

s is the readback style, described below. Modes 2 and 3 watch to see if you force the command

to be executed by pressing the force-execution digit (defaults to 'D', see command 078) or kerchunk before, during, or shortly after the number is read back; if you do they will \_\_\_\_ immediately

— quit reading the number back and either dial the number (mode 2) or abort dialing

\_\_ (mode 3). Also

— see the notes for more options.

S - Readback Style Reads Number Back If Kerchunked or Force Execution

0 Never No Effect

1 Always No Effect 2 Politely Makes it Dial

3 Politely Makes it Abort Dialing

4
Politely
No Effect (dials either way)

Default: The autopatch system is enabled. Readback style is type '1' (read back before dialing).

## Notes:

-disabled.

# Notes:

If you change the autopatch port with this command, you will need to set up the reverse patch again with Command 133.

You can adjust messages and the duration of the delays before and after the phone number is read

back by editing macros 540..544 and 551, after you execute this command to set them up.

- <u>u</u> If this command is executed while the patch is in use, it will hang the patch up.
- $-\underline{\underline{\dot{u}}}$  This command automatically turns on timed execution and makes  $\underline{\underline{\#}}\underline{\underline{\#}}$  be the force-execution digit

for the autopatch port, to make entering commands from the reverse patch easier (see command

133). These changes can be reversed/modified with command 078.

- <u>ù</u> This command also sets up an event trigger to put the autopatch port into group 3 when a call <u>is</u>
- completed See the section "Port Connections During a Call" above for more info about that.

  ù The DSP404's autopatch connects to the controller through a ribbon cable inside the cabinet.

  It is
- also possible to use a different autopatch board (such as the one designed for the RLC-3 and RLC-4) on any port using that port's DB-9 connector; this might be useful if you want to locate
- the autopatch board a distance from the controller, such as at the other end of a full-duplex radio
  - link.

## 111: Manual Off Hook

This command connects the port from which the command is executed to the autopatch without dialing

any numbers. Touch tones from your radio can be used to dial numbers without DTMF regeneration.

This is usually used only for testing, because it doesn't regenerate your DTMF digits, it doesn't allow you

to block long distance numbers, and it usually causes an error message when you dial a number. The

error message may be generated because the controller can't tell whether you are entering a command

(such as to hang up the patch) or dialing a number, so it treats the number as a (usually invalid) command; you can just ignore the error message. Command 114 can be used to hang up the patch.

<111>

## Parameters:

- 111 is the default command name.

## 112: Normal Forward Dial

This is the normal autopatch up command you would make available to your users if you want an open autopatch. If the number you enter is 3 digits or less, it dials that autodial number. If it is longer, it checks it against the dialing tables described at the beginning of this autopatch section and if it

passes, dials that number.. Command 114 can be used to hang up the patch.

<112> sss

Autopatch using an autodial memory slot

<112> d..d

Autopatch using user entered number

## Parameters:

- 112 is the default command name.
- SSS is the autodial slot number (1..3 digits)
- D..D is the phone number you want to dial

#### Notes:

-The longest number that can be dialed with the command is eleven digits, because that is the longest number that can be specified in the allowed number table. If you need to dial longer numbers, use Command 113.

# 113: Forward Dial with no Long Distance Checking

This is the autopatch up command you would use if you wanted to dial a number without worrying about

whether or not it is allowed by the dialing tables. You would not normally make this command available

to the average user, because it would allow them to dial any number, including long distance numbers.

<113> sss

Autopatch using an autodial memory slot

<113> d..d

Autopatch using user entered number

## Parameters:

- 113 is the default command name.
- SSS is the autodial slot number (1..3 digits)
- D..D is the phone number you want to dial

## Notes:

You can call this from a macro to dial numbers too long to fit in an autodial slot.

## Example:

Have macro 600 dial the number 012345678901234567890

<053>600 113 012345678901234567890 D or unkey or <Enter>

The user will program macro 600 to bring up the patch and dial the number 012345678901234567890.

137: Autodial Only

This is the same as the other dialing commands except it will only let you dial autodial numbers.

< 137 > sss

## Parameters:

- 137 is the default command name.
- SSS is the autodial slot number 0..500 (1..3 digits)

129: Repeat Dial (or recall last number dialed)

This command allows you to easily redial the last number you called or to find out the last number

someone else called. You can make it "forget" the last number dialed.

<129>

Redial the last number dialed

<129> pp

Recall (speak, do not dial) the last number dialed from port 'pp' pp'

<129> pp-

Forget the last number dialed from port 'pp'

## Notes:

-The controller keeps track of the last number dialed separately for each port that can use the autopatch, so if you make a call from port 1 and get a busy signal, then someone on port 2 makes

a call (which you might not even know about), then you attempt a redial from port 1, it will redial

the number you called, not the number that was called from port 2.

-This command works for numbers that are dialed directly or using an autodial slot, but it does

remember numbers that are dialed while using command 111 (manual off hook).

-If you try to use the redial feature after the number has been "forgotten", the controller will speak

"Repeat Dial Clear" (it does that by calling an event trigger, see Chapter 20 if you wish to

# change

that message).

-If you want to allow users to dial the last number dialed but not to use the recall or forget features, make a macro that calls this command and only give users access to that macro. For example:

010 600 ABC; name macro "ABC"

053 600 129; program macro to execute command 129

# 114: Hang up the Autopatch

This is the command to use to hang up the autopatch, no matter which of the three autopatch up commands you used to take it off-hook.

<114>

#### Parameters:

- 114 is the default command name.

#### Note:

 $\underline{\dot{}}$  The autopatch is also hung up whenever the controller is reset.

# Example:

I want my autopatch hang-up code to be '#'

<010> 114 # D or unkey or <Enter>

Now the users will enter '#' to hang-up the autopatch.

# 115: Possibly Hang up the Autopatch

This command normally works exactly like command 114, but it won't allow you to hang up the patch if

someone else on another radio port is using it and you aren't. Command 114 will hang up the patch if it

is in use by any port; that is you can hang it up even if someone else on another port of the controller

that is using it. It is important to be able to do that if there is an emergency and you need to cut them off.

On the other hand, if someone tries to use the patch and gets the "autopatch busy" message, they

may not

realize (or care) that someone else is using the patch even though they can't hear it, and they may hang it

up. Giving the users access to command 115 rather than 114 will solve that problem, as only the port(s)

that can hear the autopatch call will be allowed to hang it up. <u>If they try to hang it up with this</u> command

while someone else is using it, you may want to speak a message that indicates that they aren't allowed

to do that. Event trigger 332 "Hang Up Command 115 Blocked" (see Chapter 20) will let you do that.

<115>

# 116: Set / Recall the Predial Digits and Timing

When either of the forward dial commands are used, several things must take place before the number is actually dialed:

- -If number readback is turned on, speak the number.
- -Take the phone line off-hook. This is the same as you picking up your phone at home.
- -Since the controller can not listen to see if it gets dial tone from the phone line, it just delays for a
- \_\_\_ little
- bit and assumes that dial tone is there. We will call this delay the "initial delay".
- -If you must dial '9' or some other digits to get out of a local switchboard or PBX, those digits should be

<u>be</u> dialed here. We will call those "predial digits". You can also use these predial digits to dial-special

<u>special</u> codes to turn on or off call waiting, caller ID, and other special features that your phone

- \_\_ company may
- offer. They can be omitted if you are not on a PBX.
- -After dialing the predial digits, you may need to delay again while the PBX hooks you up to an
- outside
- telephone line. We will call this delay the "after-predial delay". This delay can be set to zero if you are
- not using predial digits.
  - -Now we can dial the actual number.

This command lets you set the initial delay, predial digits (if any), and after-predial delay.

# **Recall Settings**

<116>0

# **Change Settings**

<116> iii aaa d..d

## Parameters:

116 is the default command name.

-<u>u</u> III is the duration of the initial delay in 10mS increments (001..250). Default is 100. Do not set to

\_\_ 0.

AAA the duration of the after-predial delay in 10mS increments (001..250). Default is 100. Do not set

set to 0.

D..D are the predial digits. They can be omitted. The maximum number of predial digits is 10. Any

<u>Any</u> of the 16 DTMF digits can be used, although you might have to temporarily change your force-

execution digit to use it (see command 078).

## Defaults:

Initial delay = 100 (1 second) After-predial delay = 100 (1 second) Predial digits = none

#### Note:

Do not use a delay time of 0, or will lock the TX on the air sending the dialing cover tone until the

controller is reset.

## 119: Set Allowed Numbers Table Slot

This command allows you to set one of the slots in the allowed numbers table. For a description of this

table and how to use it, see the explanation of the dialing tables before Command 110.

<119> sss

Clear slot sss

<119> sss d..d Program slot sss

#### Parameters:

- 119 is the default command name.
- SSS is the slot number (000..499)
- D..D is the area code/prefix (do not include the last four digits of the phone number). The '#' digit is a wildcard that matches any digit.

## Defaults:

- Slot 000 is programmed to "###", which allows all seven digit numbers.

# Example:

<119> 001 1800 ### D or unkey or <Enter>

- This will allow all 1-800 numbers

# 120: Recall Allowed Numbers Table Slot

This command allows you to recall the contents of one of the slots in the allowed numbers table. For a

description of this table and how to use it, see the explanation of the dialing tables before Command-

110.

<120> sss

# Parameters:

- 120 is the default command name.
- SSS is the slot number (000..499)

## 121: Set Nuisance Numbers Table Slot

This command allows you to set one of the slots in the nuisance number table. For a description of this

table and how to use it, see the explanation of the dialing tables before Command 110.

<121> sss

Clear slot sss

<121> sss d..d

Program Slot sss

#### Parameters:

- 121 is the default command name.
- SSS is the slot number (000..099)
- D..D is the whole number to be blocked (do include the last four digits of the phone number). The '#' digit is a wildcard that matches any digit.

# Defaults:

- No slots are programmed, so any numbers allowed by command 119 can be dialed with command 112.

## Example:

- "121 000 245 5002" will program slot 000 to block 245-5002 even though it is allowed by default (along with all other seven digit numbers) by command 119.

# 122: Recall Nuisance Numbers Table Slot

This command allows you to recall the contents of one of the slots in the nuisance number table. For a

description of this table and how to use it, see the explanation of the dialing tables before Command-

110.

<122> sss

# Parameters:

- 122 is the default command name.
- SSS is the slot number (000..099)
- D..D is the whole number to be blocked (do include the last four digits of the phone number). The '#' digit is a wildcard that matches any digit.

# 123: Test Dialing Tables

This command allows you to test the dialing tables. It takes the telephone number you enter and

tests it

in the exact same way the normal forward dial Command 112 does, but instead of dialing the number, it

just tells you whether or not the number is rejected by the dialing tables. This comes in very handy when

setting up the dialing tables, because you don't have to actually dial and hang up numbers to see if they

are blocked or not. This command also works from the serial port, allowing you to check the dialing

table from a terminal or computer. You do not have to have an autopatch installed to use this command.

<123> d..d

#### Parameters:

- 123 is the default command name.
- D..D is the number you wish to test with the dialing tables

# 124: Set Autodial Slot

This command allows you to set one of the autodial slots. For a description of the autodial slots and-

how

\_to use them, see the autopatch section before Command 110.

<124> sss d..d

#### Parameters:

- 124 is the default command name.
- SSS is the slot number (0..500)
- D..D is the whole number to be dialed (up to 18 digits), not including any predial digits (they

must be set with Command 116 - you can keep them from being sent for an autodial slot with Command 126).

## Notes:

- -You can clear the data out of a slot by entering Command 124 SSS D or unkey
- -You can disable a slot without erasing it with Command 127.
- -After you program an autodial memory, the predial information for that slot is enabled
- -Autodial numbers are not checked by the long distance dialing tables

## 125: Recall Autodial Slot

This command allows you to recall the contents of one of the autodial slots.

<125> sss

## Parameters:

- 125 is the default command name.
- SSS is the slot number (0..500)

# 126: Send Predial Digits / Callsign for Autodial Slot?

This command allows you to control whether or not the predial digits will be sent before an autodial

number. The default is to send them. By telling the controller not to send them, you can dial extensions

on the PBX you are on (numbers that don't need the predial digits) with an autodial slot. The initial-

delay

\_and after-predial delay (see Command 116) are sent in either case.

It also allows you to control whether or not any call signs you may have programmed for your users will

be spoken when dialing their autodial slot. You may also want to assign autodial slots for emergency

numbers and program their "callsign" to be something like "police". See command 191 for information

about programming call signs.

Set Predial Sending

<126> sss p

Set Callsign Sending

<126> sss p c

## Parameters:

ù 126 is the default command name.

 $\underline{\underline{\dot{\mathbf{u}}}}$  SSS is the slot number (0..500)

'p' is 1 to send the predial digits (the default), 0 to not send them.

-<u>u</u> 'c' (optional, no change if omitted) is 1 to send the callsign for that autodial slot if it is programmed (the default), 0 is to just use the number of the autodial slot. The default call signs

are the number of the slot, spoken as separate digits like "two three zero". If you set 'c' to 0,

will speak the number of the slot as a number, like "two hundred thirty".

# Notes:

it

This command must be executed after you program an autodial position. The default setting for

this command is predial enabled. If you have a predial number programmed, and you do not want the

controller to add a predial your autodial slot number, then you must execute this command and disable

the predial setting for that specific autodial number.

# 127: Enable/Disable an Autodial Slot

This command allows you to disable an autodial slot without erasing its contents so you can enable it

later without having to re-enter the number.

<127> sss c

## Parameters:

- 127 is the default command name.
- SSS is the slot number (0..500)
- C is 1 to enable the slot (also done automatically when you program it), 0 to disable it

# 128: Set/Recall Patch Audio Options for a TX

Talking to someone using the autopatch is different in several ways from talking to someone on a repeater. One difference is that when you are talking on a repeater, everyone has to wait until you unkey

before they can talk (unless they have a stronger signal than you do and can capture the repeater receiver); a person talking on a phone during an autopatch call can talk at the same time that you are

talking on the radio. If you are using a typical transceiver (HT or mobile) that is half-duplex (cannot

transmit and receive at the same time), you can't talk and listen at the same time. If the autopatch is set

up to work full-duplex and the person on the phone talks at the same time you do, you will not be able to

hear what they are saying, but anyone else listening to the repeater will be able to hear both you and

them. To avoid this problem, the autopatch can be set to work in half-duplex mode. Half-duplex mode

causes the audio from the phone to be muted whenever you are talking; if someone starts to say something that shouldn't be transmitted, all you have to do is key up and they will get muted. This is the

default mode. In some situations, such as when you have two radios (one to talk on and the other to

listen with) or a radio that can transmit and receive at the same time (possibly on different bands), you

may want to change the autopatch to work in duplex mode. You can change the mode in the middle of a

call, and can select the mode for each transmitter separately.

Another difference between talking to someone on a repeater versus an autopatch is that the person using

the phone through the autopatch doesn't care if your audio gets transmitted out the repeater or not; he is

listening to the phone. If you don't want everyone else that is monitoring the repeater to hear the things

you say while you are talking on the autopatch, you can tell the controller to mute your audio at those

times. That is known as "semi-private" mode. Anyone that is listening to the repeater while you use the

autopatch in semi-private mode will only hear one side of the conversation, what the person on the-

phone

says. You can turn on a cover tone to be sent while the person on the radio is talking, or just let it-

be

```
silent.
<128> pp
Recall half-duplex and semi-private settings for a port
<128> pp h
```

Set autopatch half-duplex mode for a port

<128> pp h s

<128> pp 0 0

<128> pp 1 0

<128> pp 1 1

<128> pp 1 2

Set autopatch half-duplex and semi-private modes for a port

Full duplex mode, not semi-private

Half duplex, not semi-private

Half duplex, semi-private with no cover tone

Half duplex, semi-private with cover tone

## Parameters:

- 128 is the default command name.
- pp is the port (01..12) that the autopatch call is made or answered from, not the autopatch port

(3).

- H is the Half-Duplex on/off setting, 1 for half duplex (the default), 0 for full duplex

#### Notes:

The half/full duplex mode and semi-private mode settings are independent, but the semi-private

feature doesn't work well in duplex mode because the autopatch hybrid is not (and can not be)

perfect. For this reason, only the combinations shown in the chart above are useful in most situations.

This command allows you to control whether the audio from the autopatch gets muted when one

of the receivers that can send audio to the patch is active. When the controller receives a command to bring up the patch, it connects that port and any ports that are monitoring or connected to that port to the patch, so they can all take part in the call. Each of those ports' transmitters will stay up for the duration of the call. Each transmitter that is set for

full-duplex

mode with this command will transmit the audio from the autopatch for the entire duration

of the

call; if it also transmits the audio from a receiver, it will mix it with the autopatch audio. Each

transmitter that is set up for half-duplex mode (the default) with this command will mute the audio

<u>audio</u> from the autopatch whenever someone keys up their radio to talk to the person on the <u>phone.</u>

<u>phone.</u> This allows the control op to mute anything that the person on the phone may say by <u>simply</u>

<u>simply</u> keying up, rather than having to hang up the patch.

# 133: Set up Reverse Patch

This command allows you to set up the reverse autopatch. You must set up the forward patch functions

with Command 110 before you use this command. If you want to change how the reverse patch works,

just execute this command again with the new information.

<133>

Recall reverse patch settings

<133>0

Disable reverse autopatch

<133> 1 xx <del>y pp</del>..<del>y qq</del>

Configure for over-air ringing

<133>2 xx

Configure for control mode with no password

<133> 2 xx n..n

Configure for control mode with password n..n

# Parameters:

- 133 is the default command name.
- There are three reverse patch "modes".

Mode 0 disables the reverse patch. Forward patch will still work normally.

Mode 1 is the ring over air mode

XX - Number of rings the controller waits before ringing over the air.

Ypp..Yqq - What ports the ringing will be routed to

Mode 2 is the control mode

XX - Number of rings the controller waits before answering the phone.

N..N - Access code required when in mode 2 access

# Note about Ring Detection:

This command automatically enables the keyup delay filter (see the description for the keyup delay-

timers in

Chapter 4 for more information) for the autopatch port (port 4). This helps prevent transients on the phone line

from fooling the controller into thinking the phone is ringing when it is not. If the phone line going to the controller

rings in very short bursts, you may have to disable or shorten the-

keyup delay timer after executing this command

\_to get the controller to answer.

# Note on Mode 2:

After XX rings, the controller will answer the phone and give you about 29 seconds to enter the access-

code N..N,

or it will hang up on you. If you enter the code N..N correctly the controller will speak-

"Control" and let you enter

\_commands by DTMF just as you would from a radio port. Since you can't-

unkey to tell the controller to execute

\_the commands, you will have to either use timed execution or-

change your force-execution digit for the autopatch

from 'D' to '#' (both of those things are done-

automatically by command 110, see command 078 for more details).

Note that you will have to have to-

rename any commands you wish to execute from the telephone to not contain the

\_digits 'A', 'B', 'C' or 'D',-

as those digits can't be entered from most telephones.

After entering the access code, you can go out over radio ports or just monitor them by executing-Commands 000

and 001. For example, if your autopatch is on port 12 and you wish to monitor therepeater on port 1, execute

Command 001 121 D or wait if in timed execution mode. This will make the autopatch (port 12) monitor the

repeater (port 1).

## 134: Access Reverse Patch Control Mode

You do not need to know about this command - it is for the controller's internal use when using reverse patch mode 2 (control mode), so you can quit reading now if you want. When the controller

answers the phone in mode 2, the only commands you can execute are the pre-access macros for the

autopatch port, because the controller turns preaccess on when you set up the patch. When you specify

the reverse patch access code with Command 133, it renames one of the pre-access macros for that port

to the access code and programs that macro to call this command when executed. This command allows

you to access all of the commands until the patch is hung up, resets the patch time out timer, and stops

the pre-access timer, among other things. If you are accessing the reverse patch in mode 2 and the time

out timer is about to expire, you can execute this command to keep the patch from timing out.

<134>

## Parameters:

- 134 is the default command name.

## 135: Answer Reverse Patch

This command is used to answer a reverse patch call that is ringing out over the air (Autopatch needs to

be configured as mode 1 with command 133 or mode 2 if command 132 is also used). It will only work

when the reverse patch is ringing - it is not a substitute for the manual off-hook command. The patch is

hung up the same way as for forward patch, with Command 114.

<135>

## Parameters:

- 135 is the default command name.

Notes:

- $-\underline{\underline{\mathring{u}}}$  The controller will speak "Connect" out both the radio and the autopatch when this command is
  - executed successfully.
- $-\underline{\underline{\dot{u}}}$  If you try to execute this command and the reverse autopatch has not been ringing, you will get an
  - an autopatch error (See System wide errors at the front of the manual)

#### 132: Start Reverse Patch Call-Out

There are several different ways to use the reverse autopatch. Command 133 allows you to select what

the controller should do when it detects that the phone line is ringing (when someone is calling the

controller). It can ignore the ringing (mode 0), generate a ring tone over the air without answering the

phone (mode 1), or answer the phone after a few rings (mode 2). This command is only useful when

command 133 is set for mode 2.

After the controller answers the phone, it may require you to enter a password (see command 133 for

details). After the password has been entered, it will say "control", unless you have changed that message to something else. At that point, the controller will wait for you to enter a command. You

could enter any command, such as 026 to recall the time or 187 to log on so you can do password-

protected commands. By using this command, you can make the controller do a general call-out or

directed call-out.

<132>

Start general call-out

<132> x

<132> xx

<132> xxx

Start directed call-out to

user xxx

If you start a general call-out, the controller will generate a ring-tone over the air. Anyone listening can

answer the call-out by entering the reverse patch answer command (135, or whatever you have renamed

it to). If no one answers the call-out, the controller will generate the ring tone a certain number of times.

then give up and say "No answer" to the person on the phone. The number of times it will ring before

giving up can be changed with command 136; it defaults to 5 rings for a general call-out. The ring tone

will normally be transmitted on port 1, but that can be changed with command 192.

If you start a directed call-out and someone is talking on one of the ports that the call-out is going to, the

controller will generate a ring tone until they unkey. Then it will speak their callsign, "Call for" and-

their

\_callsign again, send the ring tone three times, and speak "<callsign> call for <callsign>" again. - Finally, it

will ring a few more times, then give up and tell the person on the phone "No answer". The call-out can

be answered at any time with command 135 or stopped with the hang up command (114 or 115). The

callsign for each user can be set with command 191. Normally the call-out will be done on the

transmitter connected to port 1, but that can be changed (or directed call-out can be disabled) foreach

user with command 192. Command 192 can also be used to change how many times the controller-

will

generate the ring tone before giving up (the default is three). The person listening to the phone will-

hear

\_a DTMF '\'\_\_' rather than a standard telephone ring tone.

If you wish to stop either a general or directed call-out before anyone answers it, enter the hang up code

(the name of command 114 or 115). This will stop the call-out but will not cause the controller to hang

up. You can then execute command 132 to try again, or any other command. If you wish to hang up,

enter the hang up code again.

# 136: Set up Reverse Autopatch Ring

This command allows the user to set up the over the air ringing tone and duration.

<136>

Recall ring duration and frequencies

<136> gg dd Set number of rings before give up when using command 132

<136> xxx yyyy zzzz Set ring duration and frequencies

# Parameters:

- 136 is the default command name.
- GG is the maximum number of times the controller will generate a ring tone when  $\frac{132}{132}$ 
  - <u>132</u> is used to do a general call-out. Default is 5 rings.
- DD is the maximum number of times the controller will generate a ring tone at the end of the

directed reverse patch call-out sequence. See command 132 for more details. The default is 3 rings.

- XXX is the duration of the ring tone
- YYYY is the Frequency of the first ring tone
- ZZZZ (optional) is the Frequency of the second ring tone

## Defaults:

Ring tone duration defaults to 2 Second Ring tone frequencies default to 0440 Hz and 0480 Hz.

# Example:

To set the ring back to the default: 136 200 0440 0480

## Notes:

You should not make the duration of the ring tone too long. The controller will stack up tone

requests and could still be ringing over the air after the phone has answered if the duration of the

tone is longer than the delay between rings from your phone company.

When using command 132 for either a general or directed call-out, the person on the phone

will

hear a DTMF  $+ \frac{1}{2}$  rather than the tone frequencies specified with this command (that the person

listening to the radio will hear). That is because the RLC-DSP404 does not have the hardware

needed to send a normal ring tone to the autopatch.

# 192: Set/Recall Call-Out Options

The command allows you to set and recall several options that affect how the reverse patch call-out

command (132) works. The default is to allow the general call-out and directed call-out for all users. If

you disable the directed call-out for a user and someone attempts to do a directed call-out to them using

command 132, they will hear the message "No P A G E R". Each user's callsign can be set with command 191 (in Chapter 18).

<192> 0 000

Recall general call-out settings

<192> 0 000 0

Disable general call-out

<192> 0 000 1 xxpp..xxqq

Enable general call-out to transmitters <a href="xxx">xxx</a>...xxx</a>

<192> 0 uuu

Recall directed call-out settings for user uuu

<192> 0 uuu 0

Disable directed call-out to user uuu

<192> 0 uuu 1 xxpp..xxqq

Enable directed call-out to user uuu on

transmitters xxx..xxx

<192> 1 uuu vvv

Recall settings for range of users from uuu to vvv

<192> 1 uuu vvv 0

Disable directed call-out for users uuu..vvv

<192> 1 uuu vvv 1 xxpp..xxqq Enable directed call-out for users uuu..vvv on transmitters xxx..xxx

# Parameters:

- uuu is the user number
- vvv is the last user number in a range from user uuu to user vvv
- $-\frac{xx}{pp}..xx\underline{qq}$  is a list of the ports that the call-out will be transmitted on. The default for everything is

transmitter 1.

# Chapter 14: Doug Hall RBI-1 and RLC-ICM Routines

## What the RBI-1 is:

Doug Hall Electronics' Remote Base Interface (RBI-1) allows the RLC-DSP404 to control the Kenwood

series TM-X21 and TM-X31 mobile radios. The RBI-1 converts the data output by the RLC-DSP404

into a format that the radios can use. Up to four bands can be supported by one RBI-1 interface, with

one band active at a time. PL (CTCSS) encode and decode is handled by the radios. The RBI-1 plugs

into one of the RLC-DSP404's radio ports and uses three of the open collector output lines . The audio,

COR and PTT interface is made through the RLC-DSP404's radio port and the signals that control the

RBI-1 and ultimately the radio come from the open collector output lines. More information about the

RBI-1, including the address and phone number for Doug Hall Electronics, is included on the following

pages. Link Communications does not sell the RBI-1 interface.

# What the RLC-ICM is:

The RLC-ICM is a remote base interface for IC-900 and IC-901 band modules. The RLC-ICM uses the

same data stream from the repeater controller as the RBI-1, except for the special setup codes sent with

command 139. Up to four bands can be supported by one RLC-ICM interface. Unlike the RBI-1, more

than one band can be active at the same time; up to all four bands can transmit or receive at the same

time. The RLC-ICM also supports a Communications Specialists' TS-64 PL board for each band-module.

\_Each band that has a TS-64 can encode and decode PL. Different bands can use different PL-frequencies.

The RLC-ICM plugs into one of the RLC-DSP 404's radio ports and uses two of the open-collector output

\_lines on the Club Deluxe module. The audio, COR and PTT interface is made throughthe

RLC-DSP404's radio port and the signals that control the RLC-ICM and ultimately the radio come-

from

\_the open collector output lines. More information about the RLC-ICM can be found at http://www.link-comm.com/rlcicm.html.

## Interfacing and Setup:

It is very easy to interface the RBI-1or RLC-ICM to the RLC-DSP404. Directions for building the

needed cable is provided on one of the following pages. You can build it yourself or order one from-

Link

Communications, Inc.. The RBI-1 is connected to the radio's microphone connectors with cables

supplied with the RBI-1. The RLC-ICM includes cables and small interface boards to connect to the IC-

900/901 band modules. The only other connections are power, ground and antenna to the radios. The

RBI-1 gets its power from the radio; the RLC-ICM has its own power plug.

If you are using the RLC-ICM, you will need to set it up with command 139. After that, all of the

commands to set frequency, bands, etc should work.

Using the RBI-1 or the RLC-ICM:

Using the RBI-1 or the RLC-ICM (after it is set up) is very straightforward. There are separate commands to do each of the following tasks:

<u>ù</u> 139: Setup RLC-ICM Interface

141: Control/Recall RBI-1 Output Lines

142: Set Frequency and Optional Offset for RBI-1 or RLC-ICM

143: Set Offset for RBI-1 or RLC-ICM

144: Set Offset Format for RBI-1 or RLC-ICM

145: Set Power Level for RBI-1

-<u>u</u> 146: Set PL Frequency for RBI-1 or RLC-ICM

147: Turn PL Encode Off/On for RBI-1 or RLC-ICM

148: Turn PL Decode Off/On for RBI-1 or RLC-ICM

149: Recall Band, Frequency and Offset for RBI-1 or RLC-ICM

150: Recall All RBI-1 or RLC-ICM Settings

151: Turn Radio Power On or Off for RBI-1

152: Goto Radio Memory for RBI-1

If there are combinations of settings that you use often, you can program them into the memories on the

Kenwood radios (if you are using the RBI-1) or you can program user macros to select those settings,

making the controller's macro work like a memory.

Doug Hall Electronics 815 E. Hudson St. Columbus, Ohio 43211 (614)261-8871 FAX 261-8805

#### INTRODUCTION

The DHE Remote Base Interface (RBI-1) Adapts the Kenwood series TM-X21 and TM-X31 mobile radios to

several brands of Repeater Controllers. The RBI model 1 converts the serial data stream from the Controller

and Directly controls the Kenwood Mobile radio. All connections to the Kenwood radio are made thru the

microphone jack. In the maximum configuration using a Kenwood TM-701 Dual Band Mobile you can

\_control-

Frequency, CTCSS encode On/Off, RF power level, Offset, Power On/Off, and Band. This is all accomplished thru the microphone jack.

The controller can modify the following functions (on at least some radios, see below):

- -Full frequency control, 4 ports/radios, and 4 bands.
- -Transmitter power HI/MED/LOW
- -CTCSS Frequency select, Encode on/off, Decode on/off.
- -20 and -12 MHz offsets on 1200.

The Supported Kenwood Mobile Radios are as follows:

140 220 440 1200 **Dual Band** TM-221 TM-321 TM-621+ TM-721+ TM-421 TM-521 TM-231 TM-331 TM-431 TM-531 TM-631+ TM-731+ TM-241 TM-441 TM-541 TM-701++ Dual Banders

## SUPPORT CROSS REFERENCE

# CTCSS CTCSS MULTI RF PWR

**FUNCTION ENCODE** SELECT DECODE BAND POWER **GENERIC Y** Y Y Y Y N N TM-X21 Y N TM-X31 Y Y Y Y TM-X41 Y Y Y Y TM-621/721 Y N N Y N

TM-631/731 Y N N Y N TM-701 Y Y Y Y Y

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## **SPECIFICATIONS**

Microprocessor: INTEL 87C51 Series 12MHz

Connections:

Power: RCA Phono + center pin.
Controller: 9 Pin female "D" Connector
Expansion: 9 Pin male "D" connector.

Radios: 4 8 Pin Modular Compatible with Kenwood PG-4H cable.

1 PG-4H provided. Additional cables available from Kenwood or DHE.

Adjustments: "T" (VR1) Radio transmit audio level adjust.

"R" (VR2) Radio receive audio level adjust.

Audio: Radio Transmit 0.050V to 2.5V Input. (response controlled by capacitor

removal)

Impedance 15K.

Radio Receive 0.020V to 2.5V Output. (response controlled by capacitor

removal)

Impedance 5K.

"S" Meter output: 0 to +5V 0V = no signal, 5V = > "S" 9.

Output impedance approx 5K.

Expansion output: 8 outputs, ground active, Sink 500mA each, 1A maximum total.

Power Requirements: +10 to +14 Vdc @ 23mA.

Size: 1.5" X 5.1" X 5.5"

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#### Installation

Place or mount the RBI-1 in close proximity to the Kenwood mobile radio to be used. Connect the-

RBI-1

with the provided PG-4H Cable from the 8 pin modular jack marked "RADIO" to the Kenwood Microphone jack. Only Port 1 (140/DUAL) will support a Dual Band radio. Port 1 is the only Port the

140 MHz radio can be connected to.

The RBI will support all 4 bands (140/220/440/1200) as follows:

If Port one (on the RBI-1, not the controller) is filled, Port 2 is for 220 only, Port 3 is for 440 only, Port 4

4-is for 1200 only. Basically, if the selected band is unavailable on Port 1 it will go to the port assigned to that band.

Installation instructions are included with the RLC-ICM for connecting it to the IC-900/901 modules.

Building the RBI-1/RLC-ICM Cable

It is important to keep your interface cable as short as possible. The cable should never be more than 6

feet in length; shorter is better.

RBI-1 Connector J2 RLC-DSP404 Connections

Pin# - Line Name Pin# - Line Name

... I/OConnections to I/O DB-25

1 - RBI-1 RESET ...... Pin 24 (output 4)

3 - Data ...... Pin 10 (output 7)

4 - Clock/Strobe ..... Pin 22 (output 8)

9 - Ground ...... Ground, Pin 1

- This pin is required for noise suppression

2 - "S" Meter output .... Analog Input on DSP4 (optional)

- Pin 2,3,4,5,14,15,16 or 17.

Connections to the radio port

5 - Kenwood TX Audio (T Pot) . 4 - RLC-DSP404 audio out

6 - Kenwood RX Audio Pot).. 5 - RLC-DSP404 audio in

8 - PTT to Kenwood TX. . . . . 3 - RLC-DSP404 PTT output

7 - COS from Kenwood RX ... 7 - RLC-DSP404 COR input (Active high)

- 9 Ground . . . . . . . . 1 RLC-DSP404 ground connection
  2 RLC-ICM (not RBI-1) PL
  - Detect Out. . . . . . 2 RLC-DSP404 PL detect input (optional)

In case it wasn't clear, there is only one connector on the RBI-1 that goes to the RLC-DSP404. It is

connected to two different connectors on the RLC-DSP404. The audio connector goes to one of the

radio ports, the RLC-Club RLC-DSP412's open collector output lines provide the serial control signals.

# Setup and Adjustment

The RBI-1 COR signal is active high. The RLC-ICM COR signal is active low. Set the COR polarity to active high with command 013.

Audio receive level from the Kenwood to the Controller is controlled by VR2 ). The audio level from

the Controller to the Kenwood is adjusted by VR1 (T). Refer to the manual for additional adjustments in

the controller.

Capacitor C5 (10uF) Inside the RBI-1 Interface must be removed and replaced with a 1uF/25V Tantalum

Capacitor for the Audio to sound correct. Remove capacitors C16 and C17 to keep the audio from

sounding too 'Bassy'.

## Kenwood Radio Setup

The Kenwood radios need certain parameters set up before they can be controlled from the RBI-1, such

as STEP. To make sure everything is set properly for use with the RBI-1, you should reset the radio to

make sure all of the settings are set to the factory defaults. Instructions about how to do this can be

found in your Kenwood operating guide or in the list below. This will erase the memories you have

stored in the radio - you can enter them in again afterward.

TM-701 Hold the MR key down during power on to reset.

TM-X21 Hold the VFO/M and M.IN keys down during power on to reset.

TM-621/721 Hold the F key down during power on to reset.

TM-631/731 Hold the MR key down during power on to reset.

TM-X31 Hold the MR key down during power on to reset.

TM-X41 Hold the VFO key down during power on to reset.

Set the step size to 5KHz. (25KHz on 1200 MHz units)

Set dual band radio to single band.

Set power to desired setting. Remember, remote base transmitters can have a high duty cycle because it

will be transmitting during all activity on the Repeater side. The mobile radios used in a remote base

configuration should be set to low power in most cases.

Set VFO/MEM to VFO for external frequency input.

Set CTCSS for desired frequencies. When using TM-X31/X41 series it will be set by the controller and

will override your initial setting.

Set CTCSS Decode to off.

Set ABC and AL to off on models that support it.

Turn off Repeat functions.

Once these have been set, connect the Mike jack to the RBI. Reset the RBI to initialize the radio to the

controller and get them in sync.

Any time there are manual changes from the radio front panel, the RBI and the Radio can get out of-

sync.

\_This will require a RBI reset to correct. We recommend hooking the reset line from the RBI to an-

oner

collector output from the controller. To reset the RBI-1, turn the open collector output line on

and-

back

off. If you do not turn the line back off, the reset line will be held low, disabling the RBI-1. Amacro can

\_be used to let you toggle the open collector output line with a single command.

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# 139: Set Up the RLC-ICM Interface

The RLC-ICM interface allows the RLC-DSP404 to control IC-900/901 band modules using the same

commands as are used for the Doug Hall RBI-1. This command tells the controller which interface you

are using (default is the RBI-1) and allows you to set up the RLC-ICM interface. This setup procedure is

not necessary for the RBI-1, since it will only support one band module being on at a time.

Once you have set up the RLC-ICM with this command, you can use most of the RBI-1 commands

(Commands 141..150) as described.

You may want to check the test points/LEDs (see page following command 139) to make sure that these

commands are being correctly received by the RLC-ICM. If they are not, you will have to enter them

again, as they are not stored by the controller.

<139>000

Set the controller for RBI-1 (the default)

<139> c ss

Set the controller for RLC-ICM

## Parameters:

- 139 is the default command name.
- C is the connector number on the RLC-ICM that the module you are setting up is plugged into (1..4).
- SS is the setup code described below

## Procedure:

-<u>u</u> First tell the RLC-ICM which band module is plugged into each of its connectors. The setup codes are listed in the chart below. You will need to execute command C139 once for each setup

code you wish to enter.

SS (the setup code)

Description

28 MHz Module

05

50 MHz Module

10

140..160 MHz Module

15

220 MHz Module

20

430..440 MHz Module

25

1200 MHz Module (not currently active)

The default setup for the RLC-ICM is to have connector 1 plugged into the 140..160 MHz module, connector 2 plugged into the 220 MHz module and connector 3 plugged into the 430..440 MHz module. As an example, the following commands will enter those settings again:

Command 139 110 D or unkey or <Enter>
Command 139 215 D or unkey or <Enter>
Command 139 320 D or unkey or <Enter>

-<u>u</u> Second, you must tell each band module what size of offset to use when you select a plus or minus offset with Commands 142 or 143. The setup codes follow:

SS (the setup code)
Description

30

100 KHz Offset

# Example:

20 MHz Offset

70

To select a 100 KHz offset for the 140..160 MHz module that is plugged into connector 1, enter

Command 139 130 D or unkey.

- -<u>u</u> Setup codes 75 and 80 are reserved for special offset memories, which are not yet supported.
- <u>u</u> You should normally use Commands 000, 001 and 002 to control turning the remote base on and

off and monitoring it. Those commands treat the whole RLC-ICM interface as one unit, connecting to and disconnecting from it the same way they would a link port. In addition to these

commands, you can tell the RLC-ICM interface to enable transceive, enable receive only, or

disable individual modules using the following codes:

SS (the setup code)

Description

85

**Enable Transceive** 

90

Enable Receive Only (Transmit Disabled)

95

Disable Module Completely

If you have properly entered the above commands, the RLC-ICM is set up and ready to use. To enter

frequencies, turn PL on and off, etc., use the RBI-1 commands in this section of the manual (commands

142..150).

## **RLC-ICM Firmware Versions:**

V1.23 and later versions of the RLC-ICM (not RLC-DSP404) firmware work slightly differently than

earlier versions. The changes include:

- -When you switch from one frequency band to another by entering a new frequency with \_ command
- 142, version 1.23 and later automatically disable the other frequency bands (as if you  $\underline{\phantom{a}}$  entered
- setup code 95). You can re-enable the other bands using setup code 85 or 95. Earlier
   versions
- left the other bands enabled until you specifically disabled them.
- -When you change frequency with command 142 (or use some of the other commands), version 1.23 and later do not automatically switch to receive only mode (as if you did setup code 90)

like

earlier versions did.

Because of these differences, the example below has a separate version for each version of RLC-ICM

firmware.

Example:

If you wanted to monitor the 140..160 MHz module and the 220 module, but only transmit on 140, you

could enter Command 139 2 90 D or unkey to disable transmitting on the 220 module on connector 2-

and

Command 139 1 85 D or unkey to enable transceive on 140..160 MHz (connector 1). If you then-

used

Command 000 to connect the repeater port you were using to the port that the RLC-ICM is on, you

would be able to transmit on and receive from the 140..160 MHz module but only receive from the 220

MHz module.

If you are using RLC-ICM firmware version 1.22 or earlier, you may want to write macros to enable

transceive after changing frequencies. The following commands will program macro 600 to enable

transceive on the 140..160 MHz module on connector 1 and name that macro to 12:

Command 053 600 038 D or unkey ; be silent for the rest of the macro

Command 056 600 139 185 D or unkey ; enable transceive Command 010 600 12 D or unkey ; rename macro 600 to 12

## **RLC-ICM Internal Operation Test Points**

The RLC-ICM controller for Icom IC900\901 modules supports on-board function test points (LEDs in

later versions). These test points are supported in the software release V1.14 and later. The test points

are located towards the center of the interface. Test points are located on connector J10 which is a 5 pin

male header connector (or just LEDs).

The following signals are present on J10.

- Pin 1 Transfer complete (Data received without errors)
- Pin 2 Configuration data received (Set-up data received without errors)
- Pin 3 Error detected in transfer (Errors were encountered on the RLC-ICM)
- Pin 4 1 second pulse output (Indicates program is running)
- Pin 5 Ground reference

When any data is sent to the RLC-ICM one of the above pins will change state. The active state is  $\pm 5v$ 

(high) or the LED being lit. More than one state may be present at a time and the states will be active for

10 seconds (Except the 1 second pulse output).

## Controller interfacing:

The most common use for these signals is to read them with a voltmeter when troubleshootingthe

\_RLC-ICM. They could also be connected to digital input lines on the controller to provide remote

feedback that commands were or were not transferred correctly, although this should not be necessary

once the RLC-ICM has been interfaced and tested.

When a frequency is selected on the interface, and the data was received without errors, pin #1 will go from the low (0v) state to the high (5V) state. When connected to an digital input line the controller can respond (Remote Base OK) for example. If an error is received during transfer pin #3 will

go from the low (0v) state to the high (5V) state. When connected to an digital input line the controller

can respond (Remote Base Error) for example. These lines simply tell the user that the data was received.

These lines can not directly interface to LED's, relays or any current "hungry" device. They are only designed for correct\error detection.

## 142: Set Frequency (and Offset) for RBI-1 or RLC-ICM

This command allows you to change the frequency of the radios connected to the Doug Hall RBI-1 or-

the

RLC-ICM. After entering the command name (default is 142), you can just enter the frequency the-

way

\_you would say it (ignoring the decimal point). To go to 147.38MHz, you could just enter "142-14738"

and unkey. You do not need to enter 0's at the end unless you want to change the offset, inwhich case

\_you have to enter three digits after the assumed decimal point before the digit that specifiesthe offset.

For example, "142 1473801" would select a positive offset (using format 0, see command-144). The

controller will determine what band the frequency is in and send the information to theremote base

\_interface. The remote base interface figures out which radio handles that band's informationand sends

\_the frequency to that radio.

<142> 29xxf o 10 meter

<142> 5xxf o 50 MHz

<142> 14xxxf o 144 MHz

<142> 22xxxf o 220 MHz

<142> 43xxxf o 430 MHz

<142> 44xxxf o 440 MHz <142> 124xxxf o 1240 MHz

<142> 125xxxf o 1250 MHz

<142> 126xxxf o 1260 MHz

<142> 127xxxf o 1270 MHz

<142> 128xxxf o 1280 MHz

<142> 129xxxf o 1290 MHz

#### Parameters:

- 142 is the default command name.
- XXX is the new frequency (MHz, 100KHz, 10KHz)
- F (optional) is the 5 KHz entry
- O (optional) is the new offset (see Command 143 for the format)

## Notes:

- -<u>u</u> If you do not want to change the current offset, you can leave off the last few digits of the command as shown in the chart above.
- You can keep the controller from speaking the frequency by either entering or not entering a

as a "megahertz point", like "142 147\*38". See command 144 for more information.

## 143: Set Offset for RBI-1 or RLC-ICM

This command allows you to change the offset on the radio connected to the Doug Hall RBI-1 or the

RLC-ICM. The offset is always specified as one digit, 0 to 3. There are two different common definitions of what digit corresponds with what offset. They are shown in the table below. The RLC-DSP404 supports both. You can select which format you want to use with Command 144.

```
<143>0
```

## Parameters:

- 143 is the default command name.
- O is the new offset

```
Offset
Format 1
Format 2

0
Minus
Minus 20 (1200 only)

1
Plus
Minus

2
Simplex
Simplex
Simplex
```

Minus 20 (1200 only)

## Note:

Plus

3

You can recall the current band unit, frequency, and offset with Command 149.

## 144: Set Offset and Frequency Readback Styles

This command allows you to change the way you enter the offset with Commands 142 and 143. The

offset is always specified as one digit, 0 to 3. There are two different common definitions of what digit

corresponds with what offset. They are shown in the table below. As an example, if you enter "142

147380 1" you will get a positive offset if you are using format 0 and a minus offset if you are using

format 1.

This command also allows you to control under what conditions the controller will speak the frequency

when you use commands 142 and 146 (PL frequency). By default, if the frequency is entered without a

("142 14738" for example), the controller will speak the frequency ("one hundred forty seven point

three eight") to confirm that it made the change. In some cases, such as when someone is jamming the

remote base, you might not want the frequency to be spoken. In those cases, you can insert a \*' for a

"megahertz point" while entering the frequency, like "142 147\*38", and the controller will just say the

word "Frequency" rather than telling you what the frequency is. If you want to reverse this logic, so the

controller normally speaks the word "Frequency" and you have to enter a \*\* to make the controller

speak what the frequency is, use the last format in the table below.

```
<144> x
Select offset format x, don't change ** readback setting

<144> x 0
Select offset format x, ** disables frequency readback

<144> x 1
Select offset format x, ** enables frequency readback
```

#### Parameters:

- 144 is the default command name.

- X is the new offset format. Used in conjunction with Command 143

```
Offset
X = 0
X = 1
0
Minus
Minus 20 (1200 only)
1
Plus
Minus
2
Simplex
Simplex
Minus 20 (1200 only)
Plus
Defaults:
 - the default format is X=0 and ** makes it say the word "Frequency".
Note:
 There is no command to recall which format you are using. If you are unsure, execute
 143 1 D or unkey. If it says "plus", you are using format 0. If it says "minus", you are using
```

format 1.

# 145: Set Power Level for RBI-1

This command allows you to change the power of the radio connected to the Doug Hall RBI-1. The

power level for the RLC-ICM is set with a jumper on the RLC-ICM and cannot be changed remotely

without special wiring (connecting the control line to a open collector output on the controller).

<145>0

Low Power

<145>1

Medium Power

<145> 2

High Power

## Parameters:

- 145 is the default command name.

## Default:

- the default is low power

## 146: Set PL Frequency for RBI-1 or RLC-ICM

This command allows you to change the PL (CTCSS) frequency of the radio connected to the Doug Hall

RBI-1 or the RLC-ICM. The frequency you set will apply to both received and transmitted PL. See

Commands 147 and 148 to turn the PL encoder and decoder on and off.

<146> x..x

#### Parameters:

- 146 is the default command name.
- X..X is the PL frequency in Hz. Valid frequencies are listed below. Default is 67.0 Hz.

#### Notes:

The RLC-DSP404 makes selecting PL frequencies easy by allowing you to enter approximate values for the PL frequencies. For example, you can select a PL of 71.9 Hz by entering any of the

the following values for X..X in the command above: 71, 72, 710, 719, 7100, and 7190. The RLC-DSP404 takes the number that you enter and finds the closest match among the valid PL frequencies. When the synthesized voice responds to this command, it tells you the actual frequency selected, even if the value you entered was approximate.

-<u>u</u> A \*\* is never required as a decimal point, but can be used ("146 127\*3") to tell the controller

whether to speak the new PL frequency or whether to just say "PL". See command 144 for more

information.

Valid RBI-1 PL Frequencies (see next page for RLC-ICM PL frequencies)

67.0 Hz

71.9 Hz

74.4 Hz

77.0 Hz

79.7 Hz

82.5 Hz

85.4 Hz

88.5 Hz

91.5 Hz

94.8 Hz

97.4 Hz

100.0 Hz

103.5 Hz

107.2 Hz

110.9 Hz

114.8 Hz

118.8 Hz

123.0 Hz

127.3 Hz

131.8 Hz

136.5 Hz

141.3 Hz

146.2 Hz

151.4 Hz

156.7 Hz

162.2 Hz

167.9 Hz

173.8 Hz

179.9 Hz

186.2 Hz

192.8 Hz

203.5 Hz

210.7 Hz

218.1 Hz

225.7 Hz

233.6 Hz

241.8 Hz 250.3 Hz

# Valid RLC-ICM PL Frequencies

- 33.0 Hz
- 35.4 Hz
- 36.6 Hz
- 37.9 Hz
- 39.6 Hz
- 44.4 Hz
- 47.5 Hz
- 49.2 Hz
- 51.2 Hz
- 53.0 Hz

54.9 Hz

56.8 Hz

58.8 Hz

63.0 Hz

67.0 Hz

69.4 Hz

71.9 Hz

74.4 Hz

77.0 Hz

79.7 Hz

82.5 Hz

85.4 Hz

88.5 Hz

91.5 Hz

94.8 Hz

97.4 Hz

100.0 Hz

103.5 Hz

107.2 Hz

110.9 Hz

114.8 Hz

118.8 Hz

123.0 Hz

127.3 Hz

131.8 Hz

136.5 Hz

141.3 Hz

146.2 Hz

151.4 Hz

156.7 Hz

159.8 Hz

162.2 Hz

165.5 Hz

167.9 Hz

171.3 Hz

173.8 Hz

177.3 Hz

179.9 Hz

183.5 Hz

186.2 Hz

189.9 Hz

192.8 Hz

196.6 Hz

199.5 Hz

203.5 Hz

206.5 Hz

210.7 Hz

218.1 Hz

225.7 Hz

229.1 Hz

233.6 Hz

241.8 Hz

250.3 Hz

254.1 Hz

# 147: Turn PL Encode Off/On for RBI-1 or RLC-ICM

This command allows you to turn the PL (CTCSS) encoder of the radio connected to the Doug Hall

RBI-1 or the RLC-ICM off or on.

<147>0

PL Encode Off

<147> 1

PL Encode On

# Parameters:

- 147 is the default command name.

## Default:

- the default PL encode off

# 148: Turn PL Decode Off/On for RBI-1 or RLC-ICM

This command allows you to turn the PL (CTCSS) decoder of the radio connected to the Doug Hall

RBI-1 or the RLC-ICM off or on.

<148>0

PL Decode Off

<148> 1

PL Decode On

## Parameters:

- 148 is the default command name.

# Default:

- the default PL decode off

# 149: Recall Frequency and Offset for RBI-1 or RLC-ICM

This command allows you to recall the current band, frequency and offset settings of the radio connected

to the Doug Hall RBI-1 or the RLC-ICM. The format of the voice response is given below. If you want

information about power, PL, etc., see the next command: Command 150.

<149>

#### Parameters:

- 149 is the default command name.

# Voice Response:

XXX.YYY The frequency in MHz.

O The offset as indicated below:

"minus" minus offset

"s" simplex

"plus" plus offset

"minus 20" minus 20 MHz offset (1200 radios only)

# 150: Recall All RBI-1 or RLC-ICM Settings

This command allows you to recall all of the current settings for the RBI-1 or the RLC-ICM. The format

of the voice response is given below. When this command is used with the RLC-ICM, it recalls the

settings of the last band for which a command is issued (the other band's information cannot be recalled).

<150>

#### Parameters:

- 150 is the default command name.

# Voice Response:

XXX.YYY The frequency in MHz.

O The offset as indicated below:

"minus" minus offset

"s" simplex

```
"plus" plus offset
"minus 20" minus 20 MHz offset (1200 radios only)
```

"power XXXX" power setting is low/moderate/high"
"PL XX.X Hertz" PL (CTCSS) frequency is XX.X hertz

"PL TX On/Off" PL encoder is on/off, "PL RX On/Off", PL decoder is on/off

## 151: Turn Radio Power On or Off for RBI-1

This command allows you to use the Doug Hall RBI-1 to turn the radio's power off, if the radio supports

it. This feature is not supported by the RLC-ICM.

<151>0

Radio Power Off

<151>1

Radio Power On

## Parameters:

- 151 is the default command name.

# Example:

I want to turn off the power on my 2 meter radio

<151>0

Voice Response:

"Radio Power < ON/OFF>"

# 152: Goto Radio Memory Channel for the RBI-1

This command allows you to go to one of the memory channels that is stored on the radio. It is not

supported by the RLC-ICM. These memories must be set up ahead of time, since there is no way to

program them using the RBI-1. The controller doesn't know what frequency (or any of the other settings) the memory has in it - that is determined totally by the radio. Only some radios support this

feature. The most common use for memories is to go to frequencies that you can't get to otherwise, such

as NOAA weather frequency. If you have more than one radio connected to the RBI-1, the memory

recall command always goes to the last radio you sent a frequency to. So if you are on two meters and

you want to recall a memory on the 220 radio, you need to enter a 220 frequency first to select that radio,

then use this command to go to the memory. The number of memories available is determined by the

radio. This command does not work on the RLC-ICM, as those band modules to not have internal

memories. It is possible to program macros on the controller that go to a specific frequency, offset, etc

and use them like memories.

<152> x..x

## Parameters:

- 152 is the default command name.
- x..x is the memory to go to (1..20, or as supported by the radio)

#### Notes:

When you recall a memory and follow that with a 'Recall all RBI-1 or RLC-ICM settings (Command 150)' only the radio power and memory information will be recalled. Because the memory

contents are not known by the controller, the frequency readback can not be used. It is a good idea to

have the frequencies noted for future use.

## Example:

I want to recall the NOAA weather channel which is in memory channel 15.

Voice Response: "Look Up <x..x>"

# 141: Control/Recall RBI-1 Output Lines

The Doug Hall RBI-1 has eight open collector output lines that can be used to control other hardware,

such as antenna switches. This feature is not supported by the RLC-ICM. Those output lines can be

controlled with this command. See the RBI-1 manual for more information about their current sink-

limits

and other specifications.

<141>X

Recall State of Output 'X' X'

<141> X 1

Turn Output 'X' X' On

<141> X 0

Turn Output 'X' X' Off

#### Note:

When an output line is turned on or off using this command, there will be a slight delay (about a

second) before the change will actually take place. Because of the delay, this command cannot be

<u>be</u> used to quickly pulse an output line. See commands 093 and 094 which use the output lines on

on the Deluxe board if you need pulses.

# Chapter 15: Serial Controlled (HF) Radio Support

<u>This section describes the controller's interface for serial controlled radios. Most such radios are for the</u>

<u>HF bands, but some such as the FT-736 handle the VHF and UHF bands. The controller's</u> software will

handle frequencies through the 1.2GHz band for radios that support them. When "HF radios" are referred to in this chapter, other serial controlled radios are also included.

# **HF Radio Interfacing**

The audio in, audio out and PTT connections to the serial controlled radio should be made just like for a

repeater or any other radio, as described in Chapter 1. If the serial controlled radio has a COR output

(from an all-mode squelch), it can be connected normally as well. If the radio does not have a COR

<u>output</u>, set the COR polarity for that radio port to active high, so the internal pullup will make it <u>always</u>

active (or leave it active low and tie the COR input to ground). This is necessary because the controller

<u>normally mutes incoming audio unless the COR line is active (see command 005 for more information).</u>

Note that having the COR line always active will make the HF receiver time out, so you might want to

<u>disable the time out timer for that radio port by setting it to zero (with command 020). If it does</u> time

out, you can reset the time out timer by resetting the controller with command 035 (you will have to exit

HF mode to do that).

<u>In addition to the audio in, audio out, COR and PTT signals, you will need to connect the controller to</u>

the radio's serial port, so you can control the frequency and other settings. Most serial controlled radios

<u>use TTL level signals, rather than the RS-232 signals that computers, mice, modems, and the</u> controller's

main serial port all use. RS-232 signals switch between +12 and -12 volts, while TTL signals change

from 0 to 5 volts. A few radios use RS-232 level signals. Do not connect an RS-232 serial port to a

TTL serial port without an adapter! Adapters to convert TTL signals to RS-232 signals can be purchased from the radio manufacturers or built from scratch. Some of these adapters may invert the

data (the Kenwood TS-870 for example), just to make it more confusing. We have schematics

for the

<u>level converters for some radios; check our web page or call us for more information. Once you have</u>

connected an adapter to the radio, you can simply connect the RS-232 serial port on the adapter to main

<u>serial port on the RLC-DSP404.</u> This is the same serial port you can use to connect the RLC-DSP404 to

a computer, so you can only use one at a time: either the HF radio or the computer for control.

<u>If you are using a Kenwood level translator, you may have to connect pins 4 and 5 together on</u> the DB-25

connector that plugs into the level translator. This connects the RTS and CTS handshaking lines.

If you want to use TTL level output, take a 16 pin socket and solder a jumper wire between pins 11 and

14 on the top of the socket. Remove the Max232 and plug in the socket instead (don't plug the Max232

<u>into the socket</u>). It will hook the processor's TTL output up to the data out line on the DB-9 without

<u>doing a level conversion like the Max232 does. Please note that hooking up the TTL output directly</u>

<u>bypasses the protection of the Max232 and exposes the processor to the outside world.</u> Shorting out the

<u>TTL output line or hitting it with static may damage the processor, requiring that it be sent back</u> to Link

<u>Communications for repair (the processors are not easy to replace in the field, and if you damage the</u>

socket trying, there are 132 little pins to try to decoder to replace it). Use the TTL output at your own

risk; getting a level translator from the radio manufacturer is much safer.

#### HF Radio Control:

There are several commands that are used to set up the HF radio interface. They tell the controller what

radio is installed and a few other things. After the radio is set up and you are ready to change frequencies, scan, etc., you can go into a special "HF control mode". When you are in this mode, all of

the normal commands are disabled and a separate set of HF control commands are used instead.

This

makes it possible to control the HF radio with short command codes without having to worry about what

other commands might get executed accidently. These commands are organized by mapping the

# **DTMF**

<u>keypad in a logical way that makes the various commands easy to remember. When you are done using</u>

the HF radio, there is a command code that takes you back to the normal mode where you can execute

the normal commands. It is possible to execute HF commands from normal mode using command 199.

This is usually used in a macro. There is also a way to execute normal commands while you are in HF

mode (see keypad code 4). And finally, there are event triggers (see command 157) that are called when

the different HF commands are entered that can be used to customize how the HF commands work (not

<u>finished yet</u>). While in HF mode, the '#' key is used as the force-execution digit to make it easier to

control the HF remote from the reverse autopatch.

# Virtual Radio Features:

Although the RLC-DSP404's HF remote base interface is loaded with features, it uses only the most

<u>basic features on the HF radio itself: receive frequency, transmit frequency, vfo, split, and mode.</u>

<u>The</u>

rest of the features are provided by the RLC-DSP404 itself. This allows the RLC-DSP404 to provide all

of those features even on radios that don't have built-in support for them. Scanning is performed by

sending a change of frequency several times a second, so the controller always knows what frequency

the radio is on and so it can handle scan edges even if the radio doesn't support them directly.

Memories

are stored on the controller, so radios without built-in memories can support them with the RLC-DSP404. Even VFO A and VFO B are simulated by the controller; they work like you would

expect but both use VFO A on the radio (the radio's VFO B is used to handle offsets with some radios).

You could call all of these features that are handled by the controller "virtual" features, since they may or

may not exist on the radio but the controller makes it work like they do. The only reason you need to

know about which features are virtual and which ones actually use the features of the radio is so you can

<u>understand why the display on the radio doesn't always reflect the commands you enter.</u>
Watching the

display on the radio may be more confusing than just using the frequency recall command

(keypad

command '8') while you are in HF mode.

# **Default Values:**

The first time the HF remote is turned on (or after it has been reinitialized), it will go to 14.25 MHz,

<u>USB.</u> All of the virtual memories also default to 14.25 MHz, USB. Of course you can change them to

any other frequency you may choose.

# Example:

<u>I want to control a Kenwood TS-870S. I want my command prefix digit to be '1', so I enter "195 11". I</u>

then enter "196 02 2 0" to set the radio type and tell the controller that it will be connected to port two.

<u>The audio cable is built just like the one for my repeater was. Since the TS-870S already has a RS-232</u>

<u>serial port, I don't need a level converter, but I do need a null modem adapter in the serial cable between</u>

it and the controller to connect the data out line on each end to the data in line on the other. At <u>least for</u>

now, I don't care about transmit or scan band edges, so I am going to skip command 197. Entering "198"

<u>from the repeater on port 1 turns on HF mode and sets the frequency to 14.25 MHz. "179" starts it</u>

scanning up fast. Kerchunking it stops the scan. "13" will turn of HF mode.

195.	Confi	gure l	HF	Mod	e
1/2.	Comm	Sui C		11100	$\sim$

<u>This command configures the HF control mode and assigns the HF command prefix digit. It also tells</u>

the RLC-DSP404 that the serial port will be used for HF control rather than for programming the controller. You must disable HF control before the serial port will work for programming again.

Sign of the second representation of the s

# Parameters:

<u>p</u> = the HF command prefix digit. This is the digit that must be pressed before any command is

entered in HF mode. It is commonly set to '1'. If you prefer not to use a prefix digit, just enter "195 1".

#### Notes:

<u>ù When you disable HF with "195 0", the HF remote will be turned off if it is in use and it will be</u>

disabled so it cannot be turned back on until it is enabled with this command.

<u>way</u> Normally the HF remote will be turned off from the port that is using it, by entering the HF command prefix digit followed by a '3' (the exit command - see the HF commands on the following pages). If you need to turn the HF remote off from another port (one that is not currently controlling the HF remote), you can enter "195 2".

# Voice Response:

"HF on/off, key x" where "on/off" indicates whether HF is enabled or disabled (not whether HF mode is turned on or not) and "x" is the HF command prefix digit. "x" will be "clear" if no prefix digit is

used.

# Example:

I want the remote base turned on and I want my HF command prefix digit to be a '1'.

# <u>195 1 1</u>

# 196: Configure HF Radio

This command tells the controller which radio port the HF radio is interfaced to and which type of radio

it is. The controller uses this information to automatically set the baud rate (4800 for Kenwood or

Yaesu, 1200 for Icom) and to send the proper command codes for your radio.

<196>0

Recall HF Radio Configuration

<196> pp 2 0

<u>Kenwood TS-450, TS-570, TS-690, TS-850, TS-870, TS-950</u> and other recent radios

<196> pp 2 1

Kenwood TS-50, TS-140S, TS-440, TS-440S, TS-680, TS-711,

TS-790A, TS-811, TS-940, R-5000 and other early radios

<196> pp 3 0

Yaesu FT-736

<196> pp 3 1

Yaesu FT-757 (no control of modes), FT757GXII

<196> pp 3 2

Yaesu FT-767

<196> pp 3 3

Yaesu FT-747GX, FT-890, FT-900, FT-990, FT-1000

Not Supported

FT-727R, FRG-8800

<196> pp 1 xx

<u>Icom.</u> See table on next page or check your radio manual to find 'xx' (the address) for your radio

# Parameters:

pp = the radio port that the HF radio is connected to.

xx = radio address (Icom only)

Normally if you are transmitting on the HF radio and you enter a command that causes serial data

to be sent to the radio, such as changing a frequency, the controller will automatically drop the PTT to the HF radio while the serial data is sent. Some radios like the Yaesu FT-736 and the Kenwood TS-711 require this. Even radios that don't require it seem to have less problems with

getting incorrect commands if they are not transmitting while they receive data, probably due to RF getting into the serial cable. If you want the controller to keep transmitting while it sends serial data, append a '1' to the end of the appropriate command above. For example: "196 02 2

1" would select port 02, Kenwood, type 1, leave PTT on when sending serial. "196 02 2 1" would make the PTT drop while sending serial.

# Voice Response:

<u>"HF on <port>, <I/K/Y><type> On/Off" where <port> is the radio port on the controller that</u> the

HF radio is connected to, <I/K/Y> signifies the brand of the radio (Icom, Kenwood or Yaesu, respectively), and <type> signifies the radio type. On/Off indicates whether the PTT will be left on

while serial data is being sent (default is off).

#### Icom Notes:

<u>ù Because the Icom radios can co-exist on a common serial bus (CI-V), a radio address is needed to </u>

select what radio gets the serial data. The list below shows the addresses of some Icom radios. If

you don't find your radio listed, check your radio's owner's manual.

<u>ù Some Icom radios will let you change their addresses. This should not cause any problems as long as you don't change the address of an IC-735 to anything but 04 and you don't change the address of any other radio to 04. The IC-735 uses a slightly different format to set the frequency</u>

and the controller software uses this format whenever the radio address is set to 04.

#### Example 1:

I want to tell the controller that there is an Icom IC-725 on radio port 02.

# Example 2:

<u>I have a Kenwood TS-440 radio on port 02.</u>

<u>196 02 2 2</u>

# Icom Radio Addresses

Controller

Setting

(Decimal)

Radio

Setting

(HEX)

Radio Type

Controller

Setting

(Decimal)

Radio

Setting

(HEX)

Radio Type

04 04 IC-735 36 24 IC-1271 A/E

08 08 IC-R7000

38 26 IC-781

16 10 IC-275 A/E/H 40 28 IC-725

18 12 IC-375 A 42 2A IC-R9000

20 14 IC-475 A/E/H 44 2C IC-765

22 16 IC-575 A/H 46 2E IC-970 A/E/H

24 18 IC-1275 A/E 48 30 IC-726

26 1A IC-R71 A/E/D 50 32

# <u>IC-R72</u>

28 1C IC-751 A 52 34 IC-R7100

<u>IC-IC/100</u>

30 1E IC-761 72 48 IC-706

32 20 IC-271 A/E/H 78 4E IC-706 MK2

34 22 IC-471 A/E/H 86 56 IC-746

# 197: Set/Recall Transmit/Scan Band Edges

<u>This command allows you to set and recall the edges of the frequency ranges that you are allowed to</u>

transmit in and within which the scanning function will loop. These two features are completely separate: they are stored separately and they operate independently, although the frequency ranges for

both are set with this command.

<u>Transmit Edges: The controller will let you receive on any frequency, but only transmit within</u> the

transmit edges that you set up with this command. This protects you from accidently transmitting on a

frequency you shouldn't.

<u>Scan Edges: The controller will let you start scanning from any frequency. Since you will often want to</u>

<u>focus on a small frequency range, it will also allow you to set a more limited range to scan within. This</u>

is the purpose of the scan band edges. Even if you started scanning from a frequency that was not within

any of the scan bands, if you are scanning up and reach the top edge of a scan band, it will automatically

<u>loop to the bottom edge and continue scanning.</u> If it reaches the bottom edge of a scan band, it will

automatically loop to the top edge. It will speak the current frequency immediately before and after

looping.

197 e

Recall Edges for all Bands

197 e c

Set Edges for all Bands for a Class (novice..amateur extra)

197 e bb

Recall Edges for one Band

197 e bb c

Set Edges for one Band for a Class

197 e bb u f..f\*f..f Set Upper or Lower Edge for one Band to a Specific Frequency Parameters: e = 0 to set a transmit band edge(s), 1 for a scan band edge(s) c = Class to set edge(s) to. You can find out what the edges are for each class by setting them then recalling them with this command. Novice Technician / Tech Plus <u>2</u> <u>General</u> Advanced Amateur Extra bb = 0..15 which band. See the table below. You don't have to leave the bands as they default you want to re-assign them some other way. If two bands overlap, the first one found that contains the current frequency will be used. u = 0 for lower edge, 1 for upper edge. If you try to set the upper edge to a lower frequency than the lower edge, the lower edge will be set to match it. If you try to set the lower edge to a higher frequency than the upper edge, the upper edge will be set to match it. f..f\*f..f = the new frequency. The '\*' should go between the 1MHz digit and the 100KHz digit

the frequency. Example "14\*25" for 14.25MHz. Frequencies over 2GHz have not

## **Defaults:**

been tested.

The following table shows the defaults for both the transmit and scan edges (they can be set separately). These are the edges of the voice bands for the amateur extra class. Note that voice is not

<u>allowed on 30 meters.</u> There is also a user defined band at the end that you can set for any other frequency range.

# Band

<u>bb</u>

Lower Edge

Upper Edge

# 160 meters

00

1.8 MHz

2.0 MHz

# 80 meters

<u>01</u>

3.75 MHz

4.0 MHz

# 40 meters

<u>02</u>

7.15 MHz

7.3 MHz

# 30 meters

03

<u>0.0 MHz</u>

0.0 MHz

# 20 meters

04

14.15 MHz

14.35 MHz

# 17 meters

<u>05</u>

# <u>18.11 MHz</u> 18.168 MHz

15 meters

<u>06</u>

21.2 MHz 21.45 MHz

12 meters

<u>07</u>

24.93 MHz

24.99 MHz

# 10 meters

08

28.3 MHz

28.999999 MHz

# 10 meters

09 29.0 MHz 29.7 MHz

# 6 meters

<u>10</u>

50.1 MHz

54.0 MHz

# 2 meters

11

144.1 MHz

148 MHz

# <u>1.25 meters</u>

12 222.0 MHz 225.0 MHz

70 cm 13 420.0 MHz 450.0 MHz
33 cm 14 902.0 MHz 928.0 MHz
23 cm 15 1240.0 MHz 1300.0 MHz
<u>user defined</u> <u>16</u> <u>0.0 MHz</u> <u>0.0 MHz</u>
198: HF Mode Enable
This command enables the HF remote base mode. This mode re-defines the DTMF keyboard
<u>into a</u>
<u>quick HF remote access pad.</u> When this mode is enabled, only HF commands can be entered (see the
following pages). In order to execute any system wide commands the user must get out of the
<u>HF mode</u> with keypad command '3' or use keypad command '4'.
<198>
Parameters: There are no parameters for this command
Defaults: HF mode is disabled

Response:

<u>ù</u> "HF Remote On <frequency>" if successful.

<u>ù</u> "HF is off" if need to enable HF control with command 195.

<u>ù</u> "HF busy X" if another port is in HF control mode. X is the number of the port this is currently

using the HF remote. If they just forgot to exit HF mode, you can turn them off with "195 2", then enter "198" again to enable control from the port you are using.

<u>ù</u> "Error 217" if you are already in HF mode.

# **HF Prefix:**

The HF prefix is a single digit that is configured with Command 195. This digit is always the first digit entered when executing a command while in HF mode. The reason for the prefix digit is to

keep single digit entries from accidentally being entered.

Example: I am in HF mode and need to start the scan function for fast up scanning

Enter: 1 79 unkey or '#' Response: "Scan up fast"

Example: I am in HF mode and need to enter a frequency

Enter: 1 29\*600 unkey or '#' Response: '2 9 point 6 0 0 0 0'

Example: I am in HF mode and need to recall memory 15

Enter: 1 515 unkey or '#' Response: <frequency>

In all these examples the format for data entry was:

<HF Prefix> <Command> <Additional Data if Needed> <unkey or '#'>

# **HF Remote Base Keypad Definition:**

1: RX Only

1x: HF Mode...

1 - USB

2 - LSB

3 - AM

4 - FM

5 - CW

2: RX and TX

21: Toggle PL RX

22: Toggle PL TX

23: PL Off

28: Recall PL

2<Hz>: Set PL Freq

3: Exit HF Mode,

Return to

Normal

Command

# Mode A: Bump Up 20Hz 4: Bump Down

- 100Hz
- 4<name>: Execute
- Command by
- Name
- 5: Select VFO A
- 5xx: Recall Memory
  - 0..99
- 6: Bump Up
  - 100Hz
- B: Bump Down
- 20Hz
- 7: Bump Down
- 500 Hz
- 7x: Start Scan...
  - 1 Down Slow
  - 3 Up Slow
  - 4 Down Med.
  - 6 Up Medium
- 7 Down Fast
  - 9 Up Fast
- 8: Recall Current
  - VFO Settings
- 80: Offset Off
- 81: Offset On
- 811: Minus Offset
- 810: Plus Offset
- 81xy: Set size of
- offset for this
- band
- 9: Bump Up
- 500Hz
- C: Not Defined
- \* Use as
  - Frequency
- <Point> Key
- 0: Select VFO B

0xx: Write Memory
Channel 0..99
#: ForceExecution
Digit, Like an
Enter Key

D: Not Defined

# **Explanation of Keypad Commands:**

Remember that before pressing the digit shown on the keypad map above, you must enter the HF

prefix digit you set with command 195. The prefix digit is shown as a 'p' in the descriptions below; it

defaults to '1'.

# Digit 1:

<u>ù "p 1": Selects receive only mode. Keying the repeater will not cause the HF radio to transmit while in receive only mode. You can also go to any frequency the radio supports while in this mode, while the allowed frequency ranges may be restricted when transmit is enabled. Voice response: "HF Receive". This does the same thing as command 001 does when you are not in HF mode.</u>

<u>ù "p 1 x": Select radio mode. "x" is from the table below. If your radio supports wide and narrow</u>

versions of a mode, the wide version will be used.

Definition

Selects USB Mode

<u>2</u> <u>Selects LSB Mode</u>

<u>3</u> Selects AM Mode

<u>4</u> <u>Selects FM Mode</u>

# <u>5</u> Selects CW Mode

# Digit 2:

- <u>ù "p 2"</u>: Select transceive mode. Keying the repeater will cause the HF radio to transmit while in
- this mode. You can only go to frequencies that are within the transmit band edges while in this mode. If you try to go to a disallowed frequency, or if you try to enable this mode while on a disallowed frequency, the controller will generate the HF error (the default is for it to speak "error 217) and will not do it. If this command is successful, you should hear the voice response:
- "HF Transmit". This does the same thing as command 000 does when you are not in HF mode.

  ù "p 2 1": Toggle PL receive requirement. Normally off. If turned on, receiver squelch will not open unless the correct PL frequency is detected. Not supported by all radios. On the Yaesu

  FT-
- 736, PL receive only works when PL transmit is enabled.
- <u>ù "p 2 2": Toggle PL transmit setting. Normally off. If turned on, will transmit the current PL frequency. Not supported by all radios.</u>
- ù "p 2 3": Turn PL receive and transmit off.
- <u>ù</u> "p 2 8": Recall PL receive and transmit settings and frequency.
- <u>ù "p 2 <Hz>":</u> Set the current PL frequency to <Hz>. Do not use the '\*' as a decimal point. You can enter the frequency to the nearest Hz, and the controller will look it up the nearest exact match for you.

# Digit 3:

ù "p 3": Exit HF mode and return to normal command mode. Voice response is "HF Off".

## Digit 4:

- <u>ù "p 4": Bump down 100 Hz. If you are in transceive mode, you may get an error if the new frequency would be disallowed by the transmit edges. Voice response is "Down 100".</u>
- <u>ù "p 4 <command name>": Execute command <command name>. For example: "p 4 026" would recall the time from HF mode, just as "026" would from normal command mode.</u>

## Digit 5:

- <u>ù "p 5": Selects virtual VFO A. Has no effect if you are already using virtual VFO A. Restores</u> the receive frequency, transmit frequency offset and mode to whatever they were when you last used virtual VFO A.
- <u>u</u> "p 5 x" or "p 5 xx": Recalls the contents of virtual memory "xx" into the current virtual VFO.
   <u>This includes the receive frequency, transmit frequency offset and mode. Once a memory has been recalled, you can bump up or down, scan, or do anything else you would do with a frequency you entered directly into the VFO. Since the memories are virtual, that is they are stored in the controller's memory rather than in the radio, all 100 memories will work regardless
  </u>

of whether your HF radio has built-in memories or not.

Digit 6:

<u>ù "p 6": Bump up 100 Hz. If you are in transceive mode, you may get an error if the new frequency would be disallowed by the transmit edges. Voice response is "Up 100".</u>

Digit 7:

<u>ù</u> "p 7": Bump down 500 Hz. If you are in transceive mode, you may get an error if the new frequency would be disallowed by the transmit edges. Voice response is "Down 500".
 <u>ù</u> "p 7 x": Start scan type "x" (see table below). Scanning is normally stopped by keying up. If you are using command 199 to control the HF radio, you may find it useful to enter a value for

"x" that is not in the table below to stop scanning.

"x" Definition

<u>I</u> <u>Scan Down Slow</u>

<u>3</u> <u>Scan Up Slow</u>

4 Scan Down Medium

<u>6</u> <u>Scan Up Medium</u>

<u>Z</u> <u>Scan Down Fast</u>

<u>9</u> <u>Scan Up Fast</u>

Digit 8:

<u>ù</u> "p 8": Recalls the current frequency, offset (if not zero) and virtual VFO (if it is VFO B). <u>ù</u> "p 8 0": Turn transmitter frequency offset off (set it to 0). Voice response is "Off". <u>ù</u> "p 8 1": Turn transmitter frequency offset on (set it to whatever offset was last used on this band). Voice response is "<offset frequency> MHz". The controller will not bother to tell the radio to go into split mode unless you have transmit enabled (keypad command 2).
 <u>ù</u> "p 8 1 x": Turn offset on and make it negative if "x" is 1, positive if x is 0 or 2.
 <u>ù</u> "p 8 1 x y": Turn offset on and make it negative if "x" is 1, positive if x is 0 or 2. Set offset size

"y" from the table below.

# Offset Code Offset size

 $\frac{\underline{0}}{\underline{0}}$ 

<u>1</u> 100 KHz

 $\underline{\underline{\underline{2}}}\\\underline{\underline{500~\text{KHz}}}$ 

 $\underline{\underline{\underline{3}}}\underline{\underline{600~\text{KHz}}}$ 

 $\underline{\underline{\underline{4}}} \\ \underline{\underline{1 \ MHz}}$ 

<u><u>5</u> <u>1.6 MHz</u></u>

<u>6</u> <u>1.7 MHz</u>

<u>7</u> <u>5 MHz</u> <u>8</u> 12 <u>MHz</u>

<u>9</u> 20 MHz

Note: Only some Icom radios support controlling the split function from the serial port. Those that do

include the IC-725, IC-726, IC-765, IC-781, and IC-970. The IC-R71, IC-R72, IC-271, IC-275, IC-375A, IC-475, IC-735, IC-471, IC-575, IC-751, IC-751A, IC-761, IC-1271, IC-1275, IC-R7000,

IC-R7100, and IC-R9000 do not support turning split on and off from their CI-V interfaces. If you

attempt to turn split mode on for a radio that doesn't support it, the controller will send the command and

respond as if it worked, but the radio will not change. If you want to control split mode remotely, you

<u>can wire one of the controller's open collector output lines to the split button on the radio. Then</u> you will

be able to "push" the split button by turning the open collector output line on and off.

## Digit 9:

<u>ù</u> "p 9": Bump up 500 Hz. If you are in transceive mode, you may get an error if the new frequency would be disallowed by the transmit edges. Voice response is "Up 500".

#### Digit 0:

<u>ù "p 0": Selects virtual VFO B. Has no effect if you are already using virtual VFO B. Restores</u>
the receive frequency, transmit frequency offset and mode to whatever they were when you last
used virtual VFO B. VFO B is called a "virtual VFO" because the controller keeps track of it
separately from virtual VFO A so it will work as you would expect, but both will usually use
VFO A on the radio. In other words, if you look at the radio, it will probably show VFO A
even

when you select virtual VFO B.

<u>ù "p 0 x" or "p 0 xx": Writes the contents of the current virtual VFO into virtual memory "xx".</u>

<u>This includes the receive frequency, transmit frequency offset and mode. Since the memories are</u>

virtual, that is they are stored in the controller's memory rather than in the radio, all 100 memories will work regardless of whether your HF radio has built-in memories or not. Voice response is "Write xx".

# Digit A:

<u>ù "p A": Bump up 20 Hz. If you are in transceive mode, you may get an error if the new before</u> the 100 KHz digit. Voice response is "Up 20".

# Digit B:

<u>ù</u> "p B": Bump down 20 Hz. If you are in transceive mode, you may get an error if the new before

the 100 KHz digit. Voice response is "Down 20".

# Digit C and D: Not used.

<u>Digit \*: Used only when entering frequencies.</u> See the instructions for "HF Frequency Entry:" below.

<u>Digit #": Used to make a command execute right away, without waiting for you to unkey.</u>
<u>Similar to</u>

the forced execution digit of 'D' that is used when not in HF mode. If you press '#' after entering

a command, you may not be able to hear part of the voice response to that command. Simply unkeying will avoid this problem.

# **Scanning:**

Although your HF radio may have a scan feature built in, it is not used when scanning with the controller (see the "Virtual Radio Features" section at the beginning of this chapter). Instead, the controller sends a new frequency to the radio several times a second. Each time a new frequency is sent,

<u>it is 20, 100 or 500Hz different than the previous frequency, depending on whether you have selected</u>

slow, medium or fast scanning. A new frequency is sent just as often when scanning slowly as when

scanning fast, but because the frequency is changed by a different amount, the resulting scan rate is

different. You can change how often a new frequency is sent to the radio by adjusting a timer.

Changing that timer will affect all three scan rates. See command 020 in Chapter 4 for information

about changing the HF scan timer value.

When the controller reaches the top or bottom of a scan band (see command 197), it will speak the current frequency, wrap around to the other edge of that band, speak the frequency again, and continue scanning. It will also speak the frequency every 10 KHz when scanning slow or medium or

every 25 KHz when scanning fast.

# **HF Frequency Entry:**

To enter a new frequency, press the HF prefix digit (default is '1') followed by the frequency.

Put

<u>a '\*' after the 1 MHz digit. For example, to go to 14.25 MHz, enter "1 14\*25" and unkey or press '#'.</u>

Leading and trailing zeros are optional. The '\*' must be entered, as that is the only thing the controller

uses to tell whether you are entering a frequency or another command.

# **Automatic Mode Selection:**

When frequencies below 10 MHz are entered, LSB mode is automatically selected. When frequencies between 10 MHz and 29 MHz are entered, USB mode is automatically selected. When

<u>frequencies above 29 MHz are entered, FM mode is automatically selected. Of course you can</u> always

<u>override the default mode (using keypad command 1). When memories are recalled, they retain</u> <u>the</u>

mode they were stored with, rather than using the automatic mode selection feature.

# Typical HF remote base session:

HF Prefix is '1'

1) 198 D or unkey; Enable HF remote mode

2) 1 29\*68 # or unkey; Move the HF remote to 29.680 MHz, VFO 'A'

3) 1 0 # or unkey ; Select VFO 'B'

4) 1 29\*58 # or unkey ; Move the HF remote to 29.580 MHz, VFO 'B'

5) 1 5 # or unkey ; Select VFO 'A'

6) 1 8 1 # or unkey ; Select Split (Repeater Mode)

7) 1 2 # or unkey ; Go into transmit and receive mode

...

1 3 # or unkey; Cancel HF mode after communications are complete

# 199: Enter HF Command (w/o being in HF mode)

This command allows you to control an HF radio without switching into HF mode with command 198.

This may be useful when you just want to change just one thing or if you want to write a macro that will

<u>do a lot of things at once.</u> After entering the command name, you should enter your HF prefix <u>digit (if</u>

<u>you have one, see command 195, then any other digits you would enter if you were in HF mode</u>
(1 for

receive, 14\*25 to change frequency, etc).

199 p h..h

# Parameters:

- p = your HF command prefix digit if you have one (see command 195)
- h..h is a command you would normally enter while in HF mode (they are described after command 198)

# Notes:

<u>ù It is possible to write a macro that uses command 199 to do several things, then execute that macro from HF mode using the keypad digit 4.</u>

# Chapter 16: Special Audio Routing Commands

See Appendix A for more information about audio routing.

# 037: Set Audio Routing Variable for Commands In a Macro

This command allows you to override the default message routing variable within a macro. It only

remains in effect until the end of the macro or until 037 or 038 are executed, whichever comes first.

Appendix A has more information about controlling where messages are sent. The most common use of

this command is to send the audio generated by commands in a macro to a different combination of ports

than it is normally sent to. An example of this is provided below.

< 037>-

pp..qq

#### Parameters:

- 037 is the default command name.
- pp..qq is the list of ports the message is to be routed to (use '0\*' for the current port, see Appendix L)

#### Note:

The changes made to the audio routing variable by this command affect all commands (including

other macros) executed until the end of the macro containing this command, or until command 037 or

038 are executed again, whichever occurs first.

## Example:

You have repeaters on ports 1 and 2. You want to make a recall time command that will speak the time out both repeaters whenever it is executed. Since command responses normally only go out of

the port that entered the DTMF command (but see command 050), we need to use a macro and manually

change the audio routing variable (with 037). We will use the command to recall the time in the male

voice (026) for this example. You could use any of the user macros (600..999), but we will use 600 for

this example.

-First we will recall macro 600 to make sure that there is nothing stored in it that we want to keep: 054

600 D or unkey or <Enter>

- -If it has something in it, we can erase it with 055 600 D or unkey, or choose a different macro.
- -Now we can append the commands we want to the macro. The first command we want the macro to

execute will set the audio routing variable to ports 1 and 2. This command is 037 124 D or unkey. To append it onto the end of the macro we enter 056 600 037 01 02 D or unkey.

-We then want the macro to recall the time (command 026). To append this onto the end of the macro

we enter 056 600 026 D or unkey.

- -Now we can cause the time to be recalled out ports 01 and 02 by executing the macro 600.
- -If you want to rename this macro to "567", for example, do the following: 010 600 567 D or unkey.

Now entering 567 and unkeying will execute the macro and cause the time to be spoken out ports

01 and 02.

# 038: Execute the Rest Of This Macro Silently

This command kills all voice/CW responses beyond this point. This command is designed for use-

within a

macro. When multiple commands are executed inside a macro, the commands that are executed-contain

their own message responses. To keep from hearing all of the responses when the macro is executed,

simply execute command 038 first, then all messages following that command are canceled. If you wants

a message response to occur from within a macro, speak the response before you execute 038.

< 038>

#### Parameters:

- 038 is the default command name.

## Notes:

The changes made to the audio routing variable by this command affect all commands (including

other macros) executed until the end of the macro containing this command, or until command 037 or

038 are executed again, whichever occurs first.

#### Example:

Want to change the access mode of port 1 and speak a message indicating what you did.

- 1) Use a multiple command macro for this purpose Macro 600 will be used to execute this sequence.
- 2) 005 is the Access mode change command
  Want to change the mode to COR and PL Access
  005 01 3 "Port 1 COR and PL"
- 3) 036 is the Voice message speak command Want to speak "Repeater on PL"
- 4) Macro programming:

```
055 600; erase the macro
```

056 600 036 411 358 046 042; speak "Repeater on PL"

056 600 038; be quiet for rest of macro

056 600 005 01 3; set to COR and PL access mode

5) The macro will speak the message "Repeater On P L" and not the mode change message "1 CAP"

### 065: Restore Audio Routing Variable (Undo 037 and 038)

This command allows you to restore the audio routing within a macro to whatever it was at thebeginning

of the macro. In other words, if commands 037 or 038 have been executed earlier in themacro, their

effects will be negated. It has no effect if used outside of a macro.

< 065>

### Example:

I want to make a macro to connect ports 1 and 2 and speak "Link Up" to whichever port entered the

command (which is the default, see command 050). This can be done without using command 065 as

follows:

ossis of the ossis

056 600 036 292 507; speak "link up"

056 600 038; be quiet for the rest of this macro 056 600 000 0102; connect ports 01 and 02

The above method may seem backwards, as the command to send the "link up" response comes before

the ports are actually connected. When the controller executes the macro, it puts the words "link up" in a

buffer to be spoken when the voice synthesizer has time and immediately goes ahead and finishes the

macro, connecting the ports. Assuming that the voice synthesizer is not busy speaking something else, it

will speak "link up" soon afterward.

The following macro does the exact same thing, and will sound exactly the same to the person that enters

it:

ossis of the ossis

056 600 038; be quiet for the rest of this macro, unless

command 037 or 065 are executed

056 600 000 0102; connect ports 1 and 2

ose the audio routing back to what it was at the

beginning of this macro

056 600 036 292 507; speak "link up"

Note that the ports are connected first, then the audio routing is restored and the message is sent. It

\_takes-

one more command in the macro (065) to put things in this order, but if it makes more sense to you

\_do-

program your macros this way, there is no harm in doing it. Note that in both macros, command 038

\_is-

needed to keep the default response of command 000 from being spoken: "one connect two".

## 039: Recall the Ports in the Current Audio Routing Variable

This command allows you to determine what ports audio is being sent out of without having a radio

tuned to each of the transmitters. It speaks a list of numbers which represent the ports that are included

in the audio routing variable at the time it is executed (see Appendix A for more information about audio

routing variables).

< 039>

## Example:

You want to know what transmitters are hearing the courtesy beep that is generated when port 2's

receiver unkeys. Solution: append this command to the end of the courtesy beep macro (257) for port 2

so it will speak the number of the ports that just heard the courtesy beep:

<056> 257 039 D or unkey or <Enter>

#### Note:

To erase command 039 from the courtesy beep macro when you are tired of hearing it, use command 058 and you will not have to erase the whole macro and program it again.

# 050: Set Up or Recall Default Audio Routing Variables

This command allows you to configure which transmitters send different voice messages and tones. -

Each

\_time a command is executed that generates a message to tell you what it did or an event occurs that

triggers a message, the controller figures out what transmitters should send that message and stores it in

an "audio routing variable" until it is actually sent. Normally if you enter a command using DTMF on a

repeater, the response message will be sent out that repeater so you can hear it. The same goes for a link.

But in some cases, you might want the response messages to commands entered from a link to be sent

out both the link and a repeater, so you can keep track of what is going on. This command allows you to

do that. It allows you to control where response messages will be sent for commands that are entered

from each receiver or the serial port. It also allows you to control where messages that are generated by

the scheduler, I/O alarms and event triggers will be sent.

Please note that when a macro is executed, it may override these default settings by using commands 037

and 038 (they only work inside of a macro). This command sets the default routing; commands 037 and

038 override it and change it to something else. If it has been changed using commands 037 or 038 in a

macro, command 065 will restore it to the default setting for the remainder of the macro.

Recall Default <050> SS

Set Default to pp..qq <050> SS pp..qq

Clear Default <050> SS 0

Parameters:

- 050 is the default command name.
- SS specifies which default audio routing variable to change
  - 01 commands entered from receiver 1
  - 02 commands entered from receiver 2
  - 03 commands entered from receiver 3
  - 04 commands entered from receiver 4
  - 05 commands entered from receiver 5
  - 06 commands entered from receiver 6
  - 07 commands entered from receiver 7
  - 08 commands entered from receiver 8
  - 09 commands entered from receiver 9
  - 10 commands entered from receiver 10
  - 11 commands entered from receiver 11
  - 12 commands entered from receiver 12
  - 13 commands entered from the serial portnot used
  - 14 commands executed from Tclient (serial, telnet-server, SSH, etc) connection 1
  - 15 commands executed from Tclient (serial, telnet-server, SSH, etc) connection 2
  - 16 commands executed from <del>Tclient</del> (serial, telnet<del>-server</del>, SSH, etc) connection 3
  - 17 commands executed from Tclient (serial, telnet-server, SSH, etc) connection 4
  - 18 commands executed from Web server

### through web interface

- 19 commands executed by an event trigger or automatic macro
- 20 commands executed by the scheduler
  - 21 commands executed by an I/O alarm
  - 22 commands executed by the internal firmware logic
- 23 commands executed by interactive HF radio controls
  - 24 do not use
  - 25 commands executed using RCI's send page feature
- pp..qq is a list of the ports that the audio will be sent out of. Enter a '0' if you do not want the audio to be sent anywhere.

#### Default:

Commands entered from a receiver are sent to whichever port entered the command. All others—default to sending messages out transmitter 1.

#### Notes:

-<u>u</u> When you enter a command on the serial port to change the audio routing variable for commands

entered from the serial port, the routing is changed before the response to this command is generated. For example, if you turn the responses off by entering "050 09 0", you won't get a voice response. If you enter "050 09 01" to turn them back on for port 01 (the default), you will

get a voice response out port 01.

-<u>u</u> Command 114 (the autopatch hangup command) can not be controlled with this command, as it

sets its own audio routing to speak the hang up message to all of the ports that are listening to the

patch, not just to the one that hung it up.

-<u>u</u> See Appendix A for more information about audio routing variables in general, commands 037,

038 and 065 for information about routing audio within a macro.

## Chapter 17: Special Control Commands

### 035: Remotely Reset the Controller

This command allows you to remotely reset the RLC-DSP404 controller. This does exactly the same

thing as turning the power off and back on or pressing the reset switch on the board. It will not cause

you to lose any of your programming - that is only possible by being at the site of the controller and

following one of the initialization procedures described in Appendix D.

< 035>

#### Parameters:

- 035 is the default command name.

207: PersistSave Settings to Flash or Undo Changes

The RLC-DSP404 does not save most settings as soon as you change them (as earlier RLC controllers

did). It works more like a computer that loads a file into memory, works on it, then saves it again. If you

lose power without saving, the changes will be lost. To save the changes, you can either reset the controller (with command 035), or enter "207 1" at any time. You can also save settings from RCI using

the File > Save Settings (on controller) menu option.

When the DSP404 start up, it loads the last saved settings into memory. It is also possible to use this

command to re-load those settings at a later time. This will effectively undo any changes you have made

# since you last saved.

<207> 1

Update persistent data: Save settings to flash memory

<u><207> 2</u>
<u>Undo changes since last save</u>
<u>(load settings from flash memory)</u>

## 078: Set Command Entry Options for a Port

This command allows you to specify several options concerning how the controller will process

characters you enter.

<0.78> pp**Recall Options** 

<0.78> pp c Set Chaining

<0.78> pp c t Set Chaining and Timed Execution

<078> pp c t e Set All Options

<078> pp 0 0 D Set for Normal Operation

### Parameters:

- 078 is the default command name.
- pp is the port for which to change the options
- 1..12 indicate the corresponding port
- 13 indicates the serial port
- C is the chaining control. This variable allows your commands to be chained together. Must

entered but is ignored for the serial port.

- 1 Enables command chaining
- 0 Disables command chaining (the default)
- T is the timed execution. This variable allows timed execution of commands entered. Must be
- = entered but is ignored for the serial port.
  - 1 Enables timed execution
  - 0 Disables timed execution (the default)
  - E (optional) is the new force-execution digit (default is 'D' for radio ports, '!' for the serial

port).

#### Defaults:

2. Chaining and timed execution should normally be turned off and the force execution digit set to

\_ 'D' for

all radio ports. Port 1 defaults with timed execution enabled to make it easier to change the COR polarity

\_if necessary when first setting up. After getting it set up correctly, timed

\_ execution should normally be

\_turned off by entering "078 1 0 0".

### Command Chaining:

Normally the controller considers everything you enter before unkeying or pressing 'D' or the enter key-

to

be one command. If there are more characters that it knows what to do with, it generates an error

message and discards the command. The chaining option lets you enter more than one command at a

time, executing all of them at once when you unkey. This can cause problems when it is ambiguous

where one command ends and the next begins, but may be useful in some cases. With the chaining-

option

turned on, the controller will let you chain on another command without unkeying after any-command

that always takes the same number of digits. This includes all of the macros and a lot of the commands

numbered 000 to 199 (those which never take any digits after the command name). Of theremaining

commands numbered between 000 and 199, you can find out which commands can have another

command come immediately after them by looking them up with command 011; if it does not say

\_"variable", you can enter another command after it. If command 011 does say "variable", that-command

must be the only command entered or the last command in a chain of commands. It is recommended

that you leave this option turned off unless you have a specific reason to turn it on. Thisoption is not

\_available (the setting is ignored) for commands entered from the serial port.

#### Timed Execution:

Normally when you enter a DTMF command, you unkey to tell the controller it is time to execute the

command. If you enter a command and wait longer than a few seconds (see the DTMF interdigit timer -

command 020) the controller assumes that you didn't want to do that command and it throws it away.

This keeps a digit accidently entered from messing up a command you might enter 30 seconds later (if

you didn't unkey in the meantime). It also reduces the likelihood of DTMF voice falsing (see-introduction

to Chapter 3) causing a command to be executed accidently; if your voice falses the decoder and you

\_don't unkey for a few seconds, the controller will just discard that falsed digit. Thereare times, however,

when it isn't possible to unkey and it would be handy to have another way to tell thecontroller to

execute. If your repeater squelch gets stuck open or someone sits on their mike, the controller won't be

\_able to tell if you unkey. In this situation, you can enter a command and then force itto execute with the

\_force-execution digit (normally 'D', but can be changed with this command). If your radio doesn't have

\_'D' on the DTMF keypad, you won't be able to do this. Another situation is when you call in on the

reverse autopatch; you can't unkey and most phones don't have the 'D' key. In either ofthose cases, you

might want to turn on timed execution. When timed execution is turned on, instead of throwing a

command away if you pause for a few seconds, the controller executes it. This is thepreferred method of

entering commands on the reverse autopatch. If you use it, you will probably want-to shorten the DTMF

interdigit timer (see command 020) to 2 or 3 seconds. This option is typically onlyused on radio ports if

\_you are controlling from a radio that doesn't have 'D' on its DTMF keypad. Thisoption is not available

(the setting is ignored) for commands entered from the serial port.

### The Force-Execution Digit:

As mentioned previously, the force-execution digit tells the controller to immediately execute any

command that may have been entered, without waiting for you to unkey. It is recommended that you

leave this digit set to 'D' in most cases, but if you need to change it, 'A', 'B', 'C' and '\*' are other-acceptable

choices ('\*' and '#' #' work pretty well from the reverse autopatch if you don't want to use timed execution). Please note that you will not be able to use any commands that have the force-execution-

digit

in their names, so avoid that digit when setting up command names. If you use '\*' as the force-execution

force-

<u>execution</u> digit for your repeater port, you will not be able to use '\*' as your autopatch up code. If you-

use the

\_DTMF mute bypass feature (see introduction to Chapter 3), your choice of force-execution digit-will

\_affect that as well.

#### Advanced Note:

If you are trying to change the force-execution digit for one port (call it 'A') by entering this command-

on

another port (call it 'B'), you will be unable to change A's force-execution digit to be the same as B's-

in

the normal way. This is because when port B sees that digit, it can't tell whether you want it to execute

immediately or whether that is what you are trying to change A's force-execution digit to. The easy

solution is to enter this command from the port that you are trying to change. If you must enter it from

another port, specify the new force execution-digit to be a '9' 9' (or any other decimal digit). The controller

will consider this to be a special case (since changing the force-execution digit to a '9' 9' would normally-

be

a very bad idea) and will instead change it to be the same as it is for the source that entered the command.

If you didn't understand this paragraph, just ignore it.

### 079: Seed Command Buffer

This command allows you to seed the command buffer with a command and any necessary data digits.

The next time digits are entered from the corresponding source, they will be appended to the seeded

values.

```
<079> ssss 0
Clear
<079> ssss ccc d..d
Seed Command Buffer
```

#### Parameters:

- 079 is the default command name.
- ssS is the source that commands will be executed from
- 01..12 indicates a radio <u>or autopatch port Note that at least through firmware</u> <u>version 4.10, this command uses only one digit for "s", so the serial port option below will not work.</u>

This command will eventually be changed so "s" is two digits.

- 13 indicates the serial port
- 0\*# indicates current port
- ccc is the command number
- d..d is the data digits for ccc, if necessary

### Example:

```
-Can be used with a macro to make '*' up patch with dial tone and long distance checking:

110 11 ; enable the patch

010 600 * ; name patch up macro '*'

056 600 051 ; start dial tone

056 600 038 ; mute following voice responses

056 600 022 125211 3000 ; reset dial tone timer for 30 seconds

056 600 079 0*# 112____ ; on next keyup, feed data to command 112
```

## 080: Execute Command by Number

This command executes other commands without regard to what their names are. In other words, if you

know the number of the command as shown in the manual, you can execute it without knowing its name

by using this command. It is automatically named "N" rather than "080" as you would normally expect,

which means it can only be executed from the serial port unless you rename it (since DTMF pads don't

have the letter "N"). The purpose of this command is explained in the notes below.

<080> XXX D..D

#### Parameters:

<080> is the name of this command, normally "N". See notes below.

XXX is the number of the command you wish to execute

D..D is the data required by command XXX, if any

#### Notes:

Since this command makes it easy to execute commands without considering if their names have been

changed, renaming commands does not provide much security from someone trying to mess up the

programming from the serial port. If access to the serial port can not be controlled (if you have a modem

connected to it, for example), you should use the password system to secure the controller. This command does not bypass the password system; if a password is necessary to execute a command

directly, the password will still be required if you use this command.

The purpose of this command is to make it easier to program the controller from a computer. One of the

best ways to program the controller is to use a text editor ("Notepad" works well in Microsoft Windows) to create a file that contains all of the commands needed to set up the controller. Such a-

file

can be "uploaded" to the controller using a communications program. A small example of such a-

file is

shown below (note that everything following a 'z;' (semicolon) until the end of the line is acomment):

; Setup file for repeater controller
007 011; turn on DTMF mute for port 1
000 0101; \_\_\_\_make port 1 a repeater
010 000 A12; rename command 000 to "A12"

After uploading a file like the one above, you might notice an error in the file or decide to add something

else to the file. After making the changes with the editor, you can upload the file again. During this

second upload, the line "000 011" will cause a "Command name not found" error because command 000

was renamed during the previous upload. To avoid this problem, you can either reinitialize thecontroller

\_before each upload (see Appendix D) or you can modify the file as shown below:

; Setup file for rep	peater controller
N007 011;	turn on DTMF mute for port 1
N000 0101;	make port 1 a repeater
N010 000 A12;	rename command 000 to "A12"

By inserting an "N"(the name of this command, 080) at the beginning of each line, the controller will

ignore any name changes and will allow you to upload the file multiple times without errors.

#### 164: Recall Software Version

This command allows you to recall the software version that the controller is running, which might be

useful when calling for technical support. Do not be concerned if the controller software version is later

than your manual version, as many of the changes between software versions do not require manual

changes.

<164>

#### Parameters:

- 164 is the default command name

165: Reset COP Watchdog Timer

This command allows you to reset the COP watchdog timer from within a macro. The only time this

should be needed is if you are executing an extremely long macro sequence (many macros calling each

other). If such a macro sequence takes too long to execute, it will cause the controller to reset, because

the controller thinks that something is wrong. Executing this command in the middle of such a long

macro sequence will tell the controller that everything is ok; it is just taking a long time.

<165>

#### Parameters:

- 165 is the default command name

### Advanced Information:

The COP timer is actually a hardware timer (in the DS1232 chip) that automatically resets the controller if the controller gets stuck in a loop. To keep it from resetting the controller, the software

must pulse a pin on the chip at least every second or so to tell the chip that the Computer is Operating

Properly (hence the name COP timer). On our controllers, that pin is pulsed in the main loop, from

which all of the procedures and functions are called. If there is a bug in any of those procedures or

functions that makes it take longer than a second or so (a long time for a computer) to return to the main

loop, the COP timer resets the controller. It is possible to write enough long macros that call other long

macros so that when the controller executes them it takes longer than a second and thereby fools the

COP timer into thinking that there is a problem and causes the controller to reset. If that happens, you

can call command 165 in the middle of those long macros to manually tickle the COP and keep it from

resetting the controller. That is the only use for this command.

### \_167: Do Nothing

This command does nothing. After executing, it returns an OK error code like most other commands

do. It is used as the default command to execute for commands like Command 157.

# Parameters:

- 167 is the default command name

### Chapter 18: 500 User Structure

### The Password System

The RLC-DSP404 provides several features that allow you to protect it from unwanted access. They

range from very simple to extremely secure. Of course the more secure methods are also more complicated. If you don't need a lot of security, don't worry about the advanced password features. This

section discusses just the password structure. Other ways of adding security are changing command

names (see commands 010, 011, 012 and 062) and blocking access to commands from certain ports (see

commands 130 and 131). The password system is disabled when the controller is shipped and after you

re-initialize it (which sets everything back to defaults), so you don't have to worry about entering passwords until you are ready for it.

The password system allows you to require that users "log in" to the controller before they will be able to

execute some or all of the commands. You can even allow some users, such as control operators, more

access than others. This is accomplished by assigning each user a "user level" which determines how

much they are allowed to do. User levels can range from 0 to 7. Typically, the owner of the system

would be level 7, control operators level 6..3 (more on that later), and other Club members level 2..1.

Level 7 users always have access to every command in the controller. A good rule is to assign lower

levels to commands that are less important. For example, lower level users can not access higher level

commands, but higher level users can access lower level commands.

When the password system is enabled, the RLC-DSP404 requires a certain user level to execute each

command. The commands default to suggested levels, but you can change them if you wish.

someone logs into the controller and tries to execute a command, their user level must be equal to or

greater than the level required by that command, or the RLC-DSP404 will not let them execute the

requested command. The command for setting up passwords is a level 4 command, so only users that-

are

\_level 4,5,6 or 7 can set passwords. The command to change which ports are connected together is-

level

\_4, so user levels 4, 5, 6 and 7 can bring up links, set up crossband repeaters, etc. Commands that

are

\_assigned level 0 can always be executed by anyone, even if they do not log into the controller first.

Recalling the time is an example of a level 0 command.

You will need to tell the controller what each user's level is, and assign them a password, callsign,

autodial number and other information for each user. To keep track of this information, you will need to

assign each user a number between 001 and 500. We will call this their "user number". It will also be

their autodial slot number, their paging slot number, etc. They will have to tell the controller what their

user number is, along with their password, to log in. For the purpose of examples in the manual, we will

consider the owner to be user 001, the control operators to be 002 through 009, and the rest of the Club

members 010 through 500, although it doesn't really matter whether you are user 003 or 300.

When someone tries to execute a command without logging onto the controller, the controller doesn't

know who they are, so it considers them to be user 000. If they try to execute a command without

logging onto the controller, the controller will compare the user level required to execute that command

with the user level for user 000. If user 000 is set to be level 7, they will be able to execute any-command

in the controller without logging on. This is how the password system is disabled when the controller is

shipped or after you re-initialize. If user 000 is set to level 0, they will only be able to execute level 0

commands (like recalling the time) without logging on. If user 000 is set to level 2, theywill be able to

\_use the autopatch without logging on.

If you decide you want to enable the password system, you should first set up a password for yourself

and assign yourself a user level (see command 186):

#### Example:

```
186 001 1 7 0 1234 ; user 001, enabled, level 7, fixed password 1234
```

Now you can try logging in. First check and see if anyone else is logged in by entering Command 188

and unkeying. Now log in by entering Command "187 001 1234", where 187 is the login command, 001

is your user number and 1234 is your password. The controller should respond and tell you that it

accepted the command. Now enter Command 188 and note that you are logged in. Now logout by

entering Command 189 and unkeying. Command 188 will confirm that you are no longer logged in. -

You

will also be logged out automatically if you do not enter a valid command for 60 seconds (you can-

change

the automatic logout timer with Command 020).

### Example:

Set up user 002 as a control operator (or yourself for now). Assign them a different password.

```
186 002 1 6 0 4321 —; user 002, enabled, level 6, fixed password 4321
```

Try logging in as user 002. It is important to set up and test two different users before continuing to

enable the password system, to prevent you from accidently locking yourself out of the controller.

```
187 002 4321 ; log in as user 002
189 ; log out
```

Remember that when no one is logged in, the controller considers you to be user 000. Up to this point,

user 000 has been a level 7 user and could execute any command. Now we will change user 000 to a

level 0 user, so that only level 0 commands like reading the time can be executed without logging on.

Make sure you have followed the example up to this point and can log on as a level 6 or 7 user, or

this-

will lock you out of the controller.

```
186 000 1 0; — enable the password system
```

To disable the password system (you may have to log on first):

## 186 000 1 7; disable the password system

Note that there is no reason to program a password for user 000, since everyone is user 000 until they log

in. Now enter Command 009 to try and recall the crosspoint settings. If you are not logged in, the

controller won't let you (that is a level 4 command). Log in as user 001 or 002 as described above and

try Command 009 again. You can check to see if you are logged in by entering Command 188.

If you want your Club members to be able to use the autopatch and remote base and do other common

things without logging on, but you still want your control operators to have to log on to change how the

controller is programmed, log on, enter the command sequence for Command 186 000 1 2. This sets

user 000 to level 2. If you do this, everyone will be able to execute level 0, 1 and 2 commands without

logging in.

If you want to turn the password system off, log on and enter the command sequence for Command 186

000 1 7. This sets user 000 to level 7. If you do this, the controller will allow all commands to be

executed without logging on.

Before setting up the rest of the users, you should consider how secure you want your system to be and

choose from the following methods of logging into the controller. Before experimenting with these

methods, make sure that you are able to log on as at least TWO different users, both level 7. Otherwise if you mess up, you might not be able to log in. A secure system can lock you out too!

### Method #1 - No Passwords:

To log on with this method, you have to tell the controller your user number, but you don't have to enter

a password. This is useful when you want to require people to log on to execute commands so you know

who they are, but it doesn't provide much security. It is easy to log on as someone else, because you

don't have to know their password. To set up user 001 with no password, enter Command 186 001 17.

User 001 can log on with Command 187 001.

#### Method #2 - Fixed Passwords:

We have already used this method in the examples above. With fixed passwords, you log onto the

controller by entering Command 187 followed by your user number and your password, for example-

"187

\_001 1234". You can make your password up to eight digits long. For example, using Command

186 001

1 7 0 12345678, user 001 is assigned a fixed password of 12345678. Longer passwords are obviously

\_harder to guess, but if someone is decoding your DTMF tones, they will probably be able to-figure out

\_your password no matter how long it is. Even so, fixed passwords are probably secure enoughfor most

\_Club members, and possibly secure enough for even the owner and control operators.

### Method #3 - Challenge Passwords:

When a user with a challenge password logs in, it takes two steps. First you enter the logon command

(Command 187) followed by their user number excluding the password information. The controller-

looks

up the user number, finds out that the user is configured for a challenge password entry, and issues

the

challenge by requesting the user to enter certain randomly selected digits of his password. The user-

then

re-executes Command 187 followed by those digits of the users password that the controller asked-

for.

An example will probably make this a lot more clear. You will have to logon before trying this example,

\_since command 186 is a level 6 command.

#### Example:

```
186 003 1 6 3 ABCABC ; user 003, enabled, level 3, password ABCABC

187 003 ; request to login

; controller responds with "Please enter 2, 6, 3"

187 B C C ; enter 2nd, 6th, and 3rd digit of password

; controller responds with logon message
```

Command 186 told the controller that user 003 wanted a 3 digit challenge password of ABCABC.

"Command 187 003" told the controller that user 003 was trying to login. The controller knew

(because

of command 186) that user 003 needed a three digit challenge. It randomly chose to ask for the 2nd, 6th,

and 3rd digit of the password. After the controller issues such a challenge, the next time command 187-

is

\_executed, it should be the answer to the challenge. In this case, user 003 entered the three digits that-

the

\_challenge asked for, as you can see below:

### Requested digits:

1

2

3

4

5

6

## Password digits:

A

В

C

A

B C

The 2nd, 6th and 3rd digit of the password are "B C C".

The challenge password method is more secure than the fixed password method, because if someone

decodes your DTMF digits as you enter your password, they don't learn your entire password, but only

those digits that you enter. If they try to logon using your password, the challenge will likely ask for

digits they don't know.

The challenge will never ask for the same digit twice, so the challenge can't ask for more digits than the

length of your password. For the most security, it is recommended that you use at least six and preferably eight digits (the maximum length) for your password and have the challenge ask for three or

four digits.

Method #4 - Challenge Passwords with Decoy Digits:

While the method #3 is very secure, if someone decodes your DTMF digits as you log on many times,

they will eventually learn all of the digits of your password. Using "decoy digits" makes it much more

difficult to figure out a password by decoding the digits.

The controller doesn't require you to enter decoy digits, but it allows it if you have a challenge password.

Consider the challenge password that was set up for user 003 in the example for method #3.

```
187 003 ; request to login ; controller responds with "Please enter 2, 6, 3"
```

Now instead of entering: "187 B C C" like with method #3, enter"187 5 3 A B C C B". Note that "B C

C" still appears in the digits entered. The other digits ("5 3 A" and the final "B") are not needed; they are just "decoy" digits and are ignored by the controller. But someone decoding your

DTMF tones doesn't know which digits are the decoy digits and which ones are digits 2, 6 and 3 of your

password. So even if they decode your DTMF digits as you log on dozens of times, they probably won't

be able to figure out your password.

All you have to do to use method #4 is request to log in ("187 003" for example), figure out what digits

the controller is asking for, then enter 187, some decoy digits, the digits the controller asked for, and

some more decoy digits. You should randomly choose from all of the DTMF digits (except the force-

execution digit which defaults to 'D') for your decoy digits. You can use from 0 up to 8 or so decoy

digits before and again after the digits the controller asks for.

Remember that the whole purpose of the decoy digits is to keep someone that is listening and decoding

your tones from figuring out which of the digits you enter are the decoy digits and which ones are the

answer to the challenge. Use different decoy digits each time. Try to enter the decoy digits at the same

rate that you do the other digits.

If all of this password stuff sounds too complicated, remember that using a challenge password with

decoy digits is only needed to deal with extreme security problems. You will probably be just fine with

no passwords and just changing a few of the important command names or with Method #1 fixed passwords.

## 186: Set up User Password

This command allows the system manager to set-up a user's password. Once the password is set, the

user must then enter the correct sequence to access commands higher than level 0.

<186> uuu

Recall a user's password information

<186> uuu e

Enable/Disable a selected user

<186> uuu e 1

Enable/Disable a selected user and set the user level

<186> uuu e <u>H1</u> t p..p

All of the above plus enter password information

#### Parameters:

UUU - user number (001..500)

E - 1 enable / 0 disable

L - user level

T - password type (0 =fixed. 1 or more is number of challenge digits)

P..P - your password (8 digits max)

#### Notes:

- Can enable or disable a user by only entering through E.
- If choose a password type of 0 but don't enter a password, you will be able to  $\log$  in by just entering the

name of command 187 followed by your user number (password method #1).

## 187: User Log-on

This command is the actual command the user uses when accessing high level commands. Because of-

the

importance of this command it can never be assigned an access level higher than '0'. By correctly-

entering

\_password information, the user can log-on to the controller and have access to all commandsthat are

\_assigned a level equal or less than their level.

<187> uuu p..p

Fixed password where p..p is the length of 'uuu' password

or...

<187> uuu <unkey> <voice prompt speaks the users required entries> then <keyup> and p..p Challenged password where p..p are the digits from 'uuu' password table.

### Parameters:

-187 is the default command name UUU is the user number (001..500) P..P is the password data

## Notes:

If a password is challenged the user must unkey and allow the controller to prompt them with the

digits to enter from their custom password table.

## 188: Recall Who Is Logged In

This command tells you who, if anyone, is logged in. If someone is causing problems, you can find out

who they are (or at least who they are logged in as) with this command. If you have not been monitoring

and you want to log on to the repeater, you should use this command first to find out if someone is

already logged in.

If no one is logged in when you execute this command, it will speak "clear".

<188>

#### Parameters:

-188 is the default command name

189: User Log-off

Once a user has completed their needs on the system, they should log-off. Once off the system they must

again log-on in order to execute any system commands assigned a level higher than '0'.

<189>

### Parameters:

-189 is the default command name

### Notes:

If the controller should lose power while you are logged on, it will automatically log you offwhen

\_power is restored so no one else can control without logging on. Actually, everyone isautomatically

logged off whenever the controller is reset for any reason.

### 190: Assign a User Level to a Command

This command assigns a user level to a command name, or a range of command names. The commands

default to reasonable levels, but you can change them to anything you wish.

<190> ccc

Recall level of a single command

<190> ccc 1

Set the level for a single command

<190> ccc eee

Recall the level for a range of commands

<190> ccc eee 1

Set the level for a range of commands

#### Parameters:

CCC is the command number from 000..999

L is the level assigned

- 0 is the lowest level with no log on required
- 7 is the highest level of log on

EEE is the ending command number for entries that require this data

## Notes:

-The controller will not let you use a larger value for  $\frac{1}{2}$  than your user level. This is to keep you

from locking yourself out of the controller.

-If a command currently has a level higher than your user level, you will not be able to change it.

This is too keep lower level users from gaining unauthorized access.

-You cannot change the level of the logon command; it is always 0. This is necessary to avoid locking yourself out of the controller.

### 191: Assign a Callsign to a User

This command assigns a callsign to a user number. User 14 might be KC7HXB for example.

callsign is used when the controller speaks messages about logging on and off and in several other-

places.

It is possible to use a different name for a user instead of their callsign. The default "call signs"are just

the user number; user 14 is "zero one four". The "callsign" can consist of any words listed in-Appendix

B. This includes all of the numbers and letters and the special words like the current time.

<191> uuu Recall user callsign

<191> uuu www..www Set the user callsign

### Parameters:

- 191 is the default command name
- UUU is the user number (001..500)
- www..www is a list of word numbers from Appendix B. There is a limit of 8 words per user number.

### Notes:

- -ù When you program a callsign for a user, the controller will automatically begin using it for the voice readback of the autodial slot with the same number. You can keep the call signs from = being - used for the autodials with command 126.

# Chapter 19: The Beaconing System

The beaconing system was designed to alert you when something at the site needs your attention. It can

be set up to announce a message over the radio and/or call you using the autopatch. It can beacon a

limited number of times, or indefinitely until you cancel the beacon.

### Note:

If you have two beacons in a row set up to go to the autopatch, and the patch never hangs up between

them, you may need to shorten the hang timer for the autopatch port to less than a second.

### 045: Setup Beacon Table

This command allows you to set up the beacon table. It is this table that controls what happens when a

beacon is started. The different slots in the table can be used to alert you of different things, or they can

be used together (when N is set to 01..50) to alert you in several different ways, such as by radio and by telephone.

<045> SS Recall slot SS

<045> SS MMM XX TTTT NN T D..D Set slot SS

#### Parameters:

045 is the default command name.

SS = beaconing table slot number to set up/recall: 01..50. If this is the last parameter entered, will

will recall the current settings of the slot in the table.

MMM = macro/command number to do

XX = number of times to do it

TTTT = time to wait between in seconds between calls to MMM. If the message spoken in command/macro MMM uses the controller's synthesized voice or DVR and it takes longer than this timer is set for, the controller will wait until the message is done. This timer should be set fairly short (less than 5 seconds) when T=1 (autopatch), so when when you answer the phone you won't have to wait a long time before you hear the message.

NN = next beaconing table slot to do (01..50), or

00 = stop after done with this slot

T =type of beacon to do

0 = beacon out radio port(s)

D..D = list of radio ports, audio routing

1 = beacon out of autopatch

D..D = phone number to dial

#### 046: Start Beacon

This command starts a beacon using the table you set up with command 045. You can start with any of

the beacon table slots, so different conditions can start different messages.

<046> SS

### Parameters:

046 is the default command name.

SS = beaconing table slot number to start with (01..50)

047: Cancel Beacon

This command allows you cancel a beacon after it has been started. Since only one beacon can be active

at a time, you don't have to specify which one you want to cancel.

< 047>

#### Parameters:

047 is the default command name.

048: Start Beacon Using English Words

This command allows you to start a beacon from the serial port that will speak the message you specify

using English words. It automatically programs macro 343 (and possibly 344) to speak the message you

specify (see command 066 for more details) and starts beaconing using the beacon table slot you specify

(which should be set up ahead of time to call macro 343). This command is most useful for alerting you

of errors that occur in another system that can output a serial error message and execute this command.

Any word that is not in the controller's voice library (see Appendix B) will be spelled out.

<048> SS Error message in English words

# Parameters:

048 is the default command name.

SS is the beacon slot number to use (often is 01)

Error\_message\_in\_English\_words is the message to be spoken, with the words separated by underscore digits.

# Example:

048 01 This\_is\_a\_test\_error\_message

## Chapter 20: Event Triggers

The controller does a lot of things totally under the control of the built-in firmware which you as the user

can't change, such as turning on a PTT when a receiver goes active and hanging up the phone when it

times out. Other things are done by calling automatic macros (see Chapter 8), such as sending IDs and

courtesy beeps. Although you can't control when the automatic macros get called, you can control what

they do. Event triggers give you even more flexibility. They allow you to execute any of the built in

commands or any of the macros whenever certain things happen. All you have to do is tell the controller

what command you want to do when each event occurs with command 157. If you only want it to

happen some of the time, you can just disable the event trigger with command 159. If you tell the event

trigger to execute a macro, you may need to program the macro to do something (see Chapter 8).

should keep track of what command you assign each event trigger to execute, as you may need to know

later.

If you want to execute more than one command from an event trigger, make the event trigger call a

macro, then program the macro to execute each of the commands in turn. That way the event trigger

calls only a single macro and the macro takes care of calling multiple other commands.

## 157: Set/Recall Event Trigger

This command allows the user to assign a macro or command call when an event occurs in order to get

response or action to occur. These are useful for alarming, and interrogating events that occur.

<157> eee Recall event trigger 'eee' eee'

<157> eee ccc

Set event trigger 'cee' eee' to execute command 'cee' ccc'

#### Defaults:

- All events are enabled and most are set to call command 158 (the exceptions are noted in the event trigger listing later in this chapter)

#### Notes:

- When this command is used to set an event trigger, it automatically enables the event trigger.

## 158: Default Event Trigger Action

This command is very unusual. It should only be called from an event trigger, never directly or as part-

of

a macro. In other words, the only use for this command is as the parameter 'ccc' in command 157.

Whenever this command is executed, it looks to see which event trigger called it, and does something

different for each one. The controller uses this method to reset timers, send messages and do a lot of

other things that need to work "out of the box," but which you might want to override and make do

something different. To change what one of the event triggers does, use command 157 to make that

event trigger call a macro rather than this command. Then program the macro to do something different

than this command did for that event trigger. The things that this command will do when called from

each event trigger may be noted in the event trigger listing later in this chapter.

<158>

Do the default action for the event trigger this was called from

#### 159: Enable/Disable Event Trigger

This command can be used to enable or disable one of the event triggers. If an event trigger is disabled,-

it

will not do anything. When it is re-enabled, it will do whatever command it was previously set to do.

#### Enable event trigger 'cee' eee'

#### <159> eee 0

Disable event trigger 'eee' eee'

#### **Event Table**

- 000 COR Active, Port 1
- 001 COR Active, Port 2
- 002 COR Active, Port 3
- 003 COR Active, Port 4
- 004 COR Active, Port 5
- 005 COR Active, Port 6
- 006 COR Active, Port 7
- 007 COR Active, Port 8
- 008 COR Active, Port 9
- 009 COR Active, Port 10
- 010 COR Active, Port 11
- 011 COR Active, Port 12
- 011 COR Active, 1 011 12
- 012 COR Inactive, Port 1
- 013 COR Inactive, Port 2
- 014 COR Inactive, Port 3
- 015 COR Inactive, Port 4
- 016 COR Inactive, Port 5
- 017 COR Inactive, Port 6
- 018 COR Inactive, Port 7
- 019 COR Inactive, Port 8
- 020 COR Inactive, Port 9
- 021 COR Inactive, Port 10
- 022 COR Inactive, Port 11
- 023 COR Inactive, Port 12
- 024 PL Active, Port 1
- 025 PL Active, Port 2
- 026 PL Active, Port 3
- 027 PL Active, Port 4
- 028 PL Active, Port 5
- 029 PL Active, Port 6
- 030 PL Active, Port 7
- 031 PL Active, Port 8
- 032 PL Active, Port 9
- 033 PL Active, Port 10

- 034 PL Active, Port 11
- 035 PL Active, Port 12
- 036 PL Inactive, Port 1
- 037 PL Inactive, Port 2
- 038 PL Inactive, Port 3
- 039 PL Inactive, Port 4
- 040 PL Inactive, Port 5
- 041 PL Inactive, Port 6
- 042 PL Inactive, Port 7
- 043 PL Inactive, Port 8
- 044 PL Inactive, Port 9
- 045 PL Inactive, Port 10
- 046 PL Inactive, Port 11
- 047 PL Inactive, Port 12
- 048 Port Active, Port 1
- 049 Port Active, Port 2
- 050 Port Active, Port 3
- 051 Port Active, Port 4
- 052 Port Active, Port 5
- 053 Port Active, Port 6
- 054 Port Active, Port 7
- 055 Port Active, Port 8
- 056 Port Active, Port 9
- 057 Port Active, Port 10
- 058 Port Active, Port 11
- 059 Port Active, Port 12
- 060 Port Inactive, Port 1
- 061 Port Inactive, Port 2
- 062 Port Inactive, Port 3
- 063 Port Inactive, Port 4
- 064 Port Inactive, Port 5
- 065 Port Inactive, Port 6
- 066 Port Inactive, Port 7
- 067 Port Inactive, Port 8
- 068 Port Inactive, Port 9
- 069 Port Inactive, Port 10
- 070 Port Inactive, Port 11
- 071 Port Inactive, Port 12
- 072 Any Connected RX Active, Port 1
- 073 Any Connected RX Active, Port 2
- 074 Any Connected RX Active, Port 3
- 075 Any Connected RX Active, Port 4
- 076 Any Connected RX Active, Port 5
- 077 Any Connected RX Active, Port 6
- 078 Any Connected RX Active, Port 7

- 079 Any Connected RX Active, Port 8
- 080 Any Connected RX Active, Port 9
- 081 Any Connected RX Active, Port 10
- 082 Any Connected RX Active, Port 11
- 083 Any Connected RX Active, Port 12
- 084 All Connected RX Inactive, Port 1
- 085 All Connected RX Inactive, Port 2
- 086 All Connected RX Inactive, Port 3
- 087 All Connected RX Inactive, Port 4
- 088 All Connected RX Inactive, Port 5
- 089 All Connected RX Inactive, Port 6
- 090 All Connected RX Inactive, Port 7
- 091 All Connected RX Inactive, Port 8
- 092 All Connected RX Inactive, Port 9
- 093 All Connected RX Inactive, Port 10
- 094 All Connected RX Inactive, Port 11
- 095 All Connected RX Inactive, Port 12
- 096 Any DTMF Active, Port 1
- 097 Any DTMF Active, Port 2
- 098 Any DTMF Active, Port 3
- 099 Any DTMF Active, Port 4
- 100 Any DTMF Active, Port 5
- 101 Any DTMF Active, Port 6
- 102 Any DTMF Active, Port 7
- 103 Any DTMF Active, Port 8
- 104 Any DTMF Active, Port 9
- 105 Any DTMF Active, Port 10
- 106 Any DTMF Active, Port 11
- 100 Ally DTMI Active, Fort II
- 107 Any DTMF Active, Port 12
- 108 Any DTMF Inactive, Port 1 109 - Any DTMF Inactive, Port 2
- 110 Any DTMF Inactive, Port 3
- 110 Any Dilvir mactive, Port 3
- 111 Any DTMF Inactive, Port 4
- 112 Any DTMF Inactive, Port 5
- 113 Any DTMF Inactive, Port 6
- 114 Any DTMF Inactive, Port 7
- 115 Any DTMF Inactive, Port 8
- 116 Any DTMF Inactive, Port 9
- 117 Any DTMF Inactive, Port 10
- 118 Any DTMF Inactive, Port 11
- 119 Any DTMF Inactive, Port 12
- 120 Port 1 DTMF Active 0
- 121 Port 1 DTMF Active 1
- 122 Port 1 DTMF Active 2
- 123 Port 1 DTMF Active 3

- 124 Port 1 DTMF Active 4
- 125 Port 1 DTMF Active 5
- 126 Port 1 DTMF Active 6
- 127 Port 1 DTMF Active 7
- 128 Port 1 DTMF Active 8
- 129 Port 1 DTMF Active 9
- 130 Port 1 DTMF Active A
- 131 Port 1 DTMF Active B
- 132 Port 1 DTMF Active C
- 133 Port 1 DTMF Active D
- 134 Port 1 DTMF Active \*
- 135 Port 1 DTMF Active #
- 136 Port 2 DTMF Active 0
- 137 Port 2 DTMF Active 1
- 138 Port 2 DTMF Active 2
- 139 Port 2 DTMF Active 3
- 140 Port 2 DTMF Active 4
- 141 Port 2 DTMF Active 5
- 142 Port 2 DTMF Active 6
- 143 Port 2 DTMF Active 7
- 144 Port 2 DTMF Active 8
- 145 Port 2 DTMF Active 9
- 146 P + 2 DTMF A + :
- 146 Port 2 DTMF Active A
- 147 Port 2 DTMF Active B
- 148 Port 2 DTMF Active C
- 149 Port 2 DTMF Active D
- 150 Port 2 DTMF Active \*
- 151 Port 2 DTMF Active #
- 152 Port 3 DTMF Active 0
- 153 Port 3 DTMF Active 1
- 154 Port 3 DTMF Active 2
- 155 Port 3 DTMF Active 3
- 156 Port 3 DTMF Active 4
- 157 Port 3 DTMF Active 5
- 158 Port 3 DTMF Active 6
- 159 Port 3 DTMF Active 7
- 160 Port 3 DTMF Active 8
- 161 Port 3 DTMF Active 9
- 101 Tott 3 D I WI Therive 3
- 162 Port 3 DTMF Active A
- 163 Port 3 DTMF Active B
- 164 Port 3 DTMF Active C
- 165 Port 3 DTMF Active D
- 166 Port 3 DTMF Active \*
- 167 Port 3 DTMF Active #
- 168 Port 4 DTMF Active 0

- 169 Port 4 DTMF Active 1
- 170 Port 4 DTMF Active 2
- 171 Port 4 DTMF Active 3
- 172 Port 4 DTMF Active 4
- 173 Port 4 DTMF Active 5
- 174 Port 4 DTMF Active 6
- 175 Port 4 DTMF Active 7
- 176 Port 4 DTMF Active 8
- 177 Port 4 DTMF Active 9
- 178 Port 4 DTMF Active A
- 179 Port 4 DTMF Active B
- 180 Port 4 DTMF Active C
- 181 Port 4 DTMF Active D
- 182 Port 4 DTMF Active \*
- 183 Port 4 DTMF Active #
- 184 Port 5 DTMF Active 0
- 185 Port 5 DTMF Active 1
- 186 Port 5 DTMF Active 2
- 187 Port 5 DTMF Active 3
- 188 Port 5 DTMF Active 4
- 100 P 45 DTME A 4' 5
- 189 Port 5 DTMF Active 5
- 190 Port 5 DTMF Active 6
- 191 Port 5 DTMF Active 7
- 192 Port 5 DTMF Active 8
- 193 Port 5 DTMF Active 9
- 194 Port 5 DTMF Active A
- 195 Port 5 DTMF Active B
- 196 Port 5 DTMF Active C
- 197 Port 5 DTMF Active D
- 198 Port 5 DTMF Active \*
- 199 Port 5 DTMF Active #
- 200 Port 6 DTMF Active 0
- 201 Port 6 DTMF Active 1
- 202 Port 6 DTMF Active 2
- 203 Port 6 DTMF Active 3
- 204 Port 6 DTMF Active 4
- 205 Port 6 DTMF Active 5
- 206 Port 6 DTMF Active 6
- 207 Port 6 DTMF Active 7
- 208 Port 6 DTMF Active 8
- 209 Port 6 DTMF Active 9
- 210 Port 6 DTMF Active A
- 211 Port 6 DTMF Active B
- 212 Port 6 DTMF Active C
- 213 Port 6 DTMF Active D

- 214 Port 6 DTMF Active \*
- 215 Port 6 DTMF Active #
- 216 Port 7 DTMF Active 0
- 217 Port 7 DTMF Active 1
- 218 Port 7 DTMF Active 2
- 219 Port 7 DTMF Active 3
- 220 Port 7 DTMF Active 4
- 221 Port 7 DTMF Active 5
- 222 Port 7 DTMF Active 6
- 223 Port 7 DTMF Active 7
- 224 Port 7 DTMF Active 8
- 225 Port 7 DTMF Active 9
- 226 Port 7 DTMF Active A
- 227 Port 7 DTMF Active B
- 228 Port 7 DTMF Active C
- 229 Port 7 DTMF Active D
- 230 Port 7 DTMF Active \*
- 230 Polt / DTMF Active
- 231 Port 7 DTMF Active #
- 232 Port 8 DTMF Active 0
- 233 Port 8 DTMF Active 1
- 234 Port 8 DTMF Active 2
- 235 Port 8 DTMF Active 3
- 236 Port 8 DTMF Active 4
- 237 Port 8 DTMF Active 5
- 238 Port 8 DTMF Active 6
- 239 Port 8 DTMF Active 7
- 240 Port 8 DTMF Active 8
- 241 Port 8 DTMF Active 9
- 242 Port 8 DTMF Active A
- 243 Port 8 DTMF Active B
- 244 Port 8 DTMF Active C
- 245 Port 8 DTMF Active D
- 246 Port 8 DTMF Active \*
- 247 Port 8 DTMF Active #
- 248 Port 9 DTMF Active 0
- 249 Port 9 DTMF Active 1
- 250 Port 9 DTMF Active 2
- 251 Port 9 DTMF Active 3
- 252 Port 9 DTMF Active 4
- 253 Port 9 DTMF Active 5
- 254 Dort O DEME Actions
- 254 Port 9 DTMF Active 6
- 255 Port 9 DTMF Active 7 256 - Port 9 DTMF Active 8
- 257 Port 9 DTMF Active 9
- 258 Port 9 DTMF Active A

- 259 Port 9 DTMF Active B
- 260 Port 9 DTMF Active C
- 261 Port 9 DTMF Active D
- 262 Port 9 DTMF Active \*
- 263 Port 9 DTMF Active #
- 264 Port 10 DTMF Active 0
- 265 Port 10 DTMF Active 1
- 266 Port 10 DTMF Active 2
- 267 Port 10 DTMF Active 3
- 268 Port 10 DTMF Active 4
- 269 Port 10 DTMF Active 5
- 270 Port 10 DTMF Active 6
- 271 Port 10 DTMF Active 7
- 272 Port 10 DTMF Active 8
- 273 Port 10 DTMF Active 9
- 274 Port 10 DTMF Active A
- 275 P 10 DTMT Active 1
- 275 Port 10 DTMF Active B
- 276 Port 10 DTMF Active C
- 277 Port 10 DTMF Active D
- 278 Port 10 DTMF Active \*
- 279 Port 10 DTMF Active #
- 280 Port 11 DTMF Active 0
- 281 Port 11 DTMF Active 1
- 282 Port 11 DTMF Active 2
- 283 Port 11 DTMF Active 3
- 284 Port 11 DTMF Active 4
- 285 Port 11 DTMF Active 5
- 286 Port 11 DTMF Active 6
- 287 Port 11 DTMF Active 7
- 288 Port 11 DTMF Active 8
- 289 Port 11 DTMF Active 9
- 290 Port 11 DTMF Active A
- 291 Port 11 DTMF Active B
- 292 Port 11 DTMF Active C
- 292 POIL II DIMF ACTIVE C
- 293 Port 11 DTMF Active D
- 294 Port 11 DTMF Active \*
- 295 Port 11 DTMF Active #
- 296 Port 12 DTMF Active 0
- 297 Port 12 DTMF Active 1
- 298 Port 12 DTMF Active 2
- 299 Port 12 DTMF Active 3
- 300 Port 12 DTMF Active 4
- 301 Port 12 DTMF Active 5
- 302 Port 12 DTMF Active 6
- 303 Port 12 DTMF Active 7

- 304 Port 12 DTMF Active 8
- 305 Port 12 DTMF Active 9
- 306 Port 12 DTMF Active A
- 307 Port 12 DTMF Active B
- 308 Port 12 DTMF Active C
- 309 Port 12 DTMF Active D
- 310 Port 12 DTMF Active \*
- 311 Port 12 DTMF Active #
  - 312 Tried to hang up patch when was already hung up.
- 313 Before turn HF mode on
- 314 After turn HF mode off
- 315 HF Band 160m
- 316 HF Band 80m
- 317 HF Band 40m
- 318 HF Band 30m
- 319 HF Band 20m
- 320 HF Band 17m
- 321 HF Band 15m
- 322 HF Band 12m
- 323 HF Band 10m below 29MHz
- 324 HF Band 10m above 29MHz
- 325 HF Band 6m
- 326 HF Band 2m
- 327 HF Band 125cm
- 328 HF Band 70cm
- 329 HF Band 33cm
- 330 HF Band 23cm
- 331 HF Band Other
- 332 Pre Patch Off Hook
- 333 Pre Patch On Hook.
- -334 Hang Up Command 115 Blocked
- 333 TX 1 Tail Message 1
- 334 TX 1 Tail Message 2
- 335 TX 1 Tail Message 3
- 336 TX 2 Tail Message 1
- 337 TX 2 Tail Message 2
- 338 TX 2 Tail Message 3
- 339 TX 3 Tail Message 1
- 340 TX 3 Tail Message 2
- 341 TX 3 Tail Message 3
- 342 TX 4 Tail Message 1
- 343 TX 4 Tail Message 2
- 344 TX 4 Tail Message 3
- 345 TX 5 Tail Message 1

```
<u>346 - TX 5 Tail Message</u> 2
```

- 347 TX 5 Tail Message 3
- 348 TX 6 Tail Message 1
- <u> 349 TX 6 Tail Message 2</u>
- 350 TX 6 Tail Message 3
- 351 TX 7 Tail Message 1
- 352 TX 7 Tail Message 2
- 353 TX 7 Tail Message 3
- 354 TX 8 Tail Message 1
- 355 TX 8 Tail Message 2
- 356 TX 8 Tail Message 3
- 357 TX 9 Tail Message 1
- 358 TX 9 Tail Message 2
- 359 TX 9 Tail Message 3
- 360 TX 10 Tail Message 1
- 361 TX 10 Tail Message 2
- 362 TX 10 Tail Message 3
- 363 TX 11 Tail Message 1
- 364 TX 11 Tail Message 2
- 365 TX 11 Tail Message 3
- 366 TX 12 Tail Message 1
- 367 TX 12 Tail Message 2
- 368 TX 12 Tail Message 3
- 369 Autopatch Line Sense Hangup. Enter 157
  - 369 114 to make the patch automatically
- hang up when the phone hangs up. Audio is routed to nowhere by default. If call the
- hangup command, it automatically routes
- to the correct ports.
- 370 Reverse Patch Answered default audio routing is to the autopatch port.
- 3<del>35</del>71 Reverse Patch Password OK makes command 158 speak "Control"
- 3<del>36</del>72 Command Entered from Reverse Patch -Makes command 158 reset patch time-out timer.
- 337373 30 seconds until patch time-out doesn't make command 158 do anything.
- 3<del>3874</del> 20 seconds until patch time-out doesn't make command 158 do anything.
- 3<del>39</del>75 10 seconds until patch time-out doesn't make command 158 do anything.
- 34076 Patch Dialing Cover Tone makes command 158 send a cover tone while dialing a number.

34177 - Mode 1 Connect - Someone answered reverse patch while ringing in mode 1.
34278 - Mode 2 Connect - Someone answered directed reverse patch.

379 - Directed Reverse Patch No Pager - makes command 132 speak "No P A G E R" to the person on the phone if they try to do a directed page to someone that has reverse patch paging disabled with command 192. 380 - Directed Reverse Patch No Answer happens whenever command 132 is used, no one enters the reverse patch answer command, and the controller gives up. It makes command 132 speak "No Answer" to the person on the phone. 381 - Directed Reverse Patch Cancelled - happens when someone enters the hangup code while command 132 is being used. 382 - Directed Reverse Patch Clear 383 - Semi-Private Patch Cover Tone - makes command 158 send a cover tone during semi-private patch operation. 343384 - Repeat Dial Message - happens when command 129 is used. Speaks "Repeat Dial". 34485 - Nothing to Re-Dial Message - happens when command 129 is used. 34586 - Call Aborted Message - Hang up patch before dial forward completed. Speaks "Cancel call." Must be programmed to execute command 158. 34687 - Dial Timer Expired, Port 1 34788 - Dial Timer Expired, Port 2 348389 - Dial Timer Expired, Port 3 349390 - Dial Timer Expired, Port 4 3<del>50</del>91 - Dial Timer Expired, Port 5 3<del>51</del>92 - Dial Timer Expired, Port 6 3<del>52</del>93 - Dial Timer Expired, Port 7 3<del>53</del>94 - Dial Timer Expired, Port 8 354395 - Dial Timer Expired, Port 9 3<del>55</del>96 - Dial Timer Expired, Port 10 3<del>56</del>97 - Dial Timer Expired, Port 11 3<del>57</del>98 - Dial Timer Expired, Port 12

3<del>58</del>99 - PTT Active, Port 1

```
359400 - PTT Active, Port 2
```

- 360401 PTT Active, Port 3
- 361402 PTT Active, Port 4
- 362403 PTT Active, Port 5
- 363<u>404</u> PTT Active, Port 6
- 364<u>405</u> PTT Active, Port 7
- 365406 PTT Active, Port 8
- 366<u>407</u> PTT Active, Port 9
- 367408 PTT Active, Port 10
- 368409 PTT Active, Port 11
- 369410 PTT Active, Port 12
- 370411 PTT Inactive, Port 1
- 371412 PTT Inactive, Port 2
- 372413 PTT Inactive, Port 3
- 373414 PTT Inactive, Port 4
- 5/5<del>414</del> F11 Illactive, F0114
- 374<u>415</u> PTT Inactive, Port 5
- 375<u>416</u> PTT Inactive, Port 6
- 376<u>417</u> PTT Inactive, Port 7
- 377<u>418</u> PTT Inactive, Port 8
- 378<u>419</u> PTT Inactive, Port 9
- 379<u>420</u> PTT Inactive, Port 10
- 380421 PTT Inactive, Port 11
- 381422 PTT Inactive, Port 12

#### Notes about the Event Triggers:

Tail Messages: There are three tail messages assigned to each transmitter. They can be used to indicate

that you are on battery power, that a link is up, to announce club meetings, etc. If you transmit PL from

your repeater, you may want to consider turning the PL encoder off and sending a CW pause from a tail

message to make your PL go away before the repeater actually drops (you could turn the PL encoder

back on from the "any connected receiver active" event trigger). You can enable any one, two, or all

three tail messages at the same time. The controller will send them in order after the courtesy beep (if on

a repeater) and hang time are over. They will normally be the last thing sent before the transmitter drops

(the mini-hang time is all that happens afterward). To keep them from getting too annoying, they will be

sent no more often than the duration of the tail message timers (see Chapter 4), which defaults to 5

minutes. If you set the tail message timers to 0, they will be sent every time the transmitter drops. If you

key up while a tail message is being sent, it will start the cycle over again; that is the tail message will-

be

sent again after you unkey, and the courtesy beep and hang timer are done.—

# Chapter 21: Remote Base Control

#### 224: Set Port Destination Info

<224> pp Recall Settings for port 'pp'.

<224> pp ['c'['x..x']] Apply sub-command 'c' with parameters 'x..x' to port 'pp'.

#### Parameters:

 $-\dot{\mathbf{u}}$  'pp' is the port to set/recall.

 $-\frac{1}{2}$  'c' is the sub-command to perform. (see chart below)

 $-\frac{1}{2}$  'x..x' is additional data required by the sub-command.

#### **Sub-command Chart**

Command Description Function

# Examples:

 $\rightarrow$  224 01 - recall settings for port 01.

 $-\dot{\mathbf{u}}$  224 01 0 1 - enable channel selection for port 01.

 $-\frac{1}{2}$  224 01 1 24 - select channel 24 on port 01.

#### 225: Set Destination Info

<225> 'ddd'

recall settings for destination 'ddd'.

<225> 'ddd' ['c' [x..x]] apply command 'c' to destination 'ddd'.

#### Parameters:

- 'ddd' is the destination to set/recall.
- 'c' is the sub-command to execute. (see chart below)
- 'x..x' is any additional information required by the sub-command.

#### **Sub-command Chart**

Command Description Function

Set destination type to type 'x'.

0 = empty

1 = channel

2 = direct-freq-control

Set destination description to 'x..x'.

```
<2> 'set_of_ports'
Set of ports for which destination 'ddd' is enabled.
Formatting for 'set_of_ports' is as follows: "a,b,c,d,e" (include quotations)

<3> 'DDD' 'set_of_ports'
Set of ports for which destinations 'ddd' through 'DDD' are enabled.
Formatting for 'set_of_ports' is as follows: "a,b,c,d,e" (include quotations)

Examples:
-\(\frac{1}{2}\) 225 005 - recall settings for destination 005.
-\(\frac{1}{2}\) 225 005 0 1 - set destination 005 type to channel.
-\(\frac{1}{2}\) 225 005 1 NOAA Weather - set destination 005 description to "NOAAWEATHER"
```

8.

 $-\underline{\underline{\dot{u}}}$  225 005 3 009 "1,2,3,5" - set the ports for which destinations 005 through 009 are enabled

- set the ports for which destination 005 is enabled to 1,2,3,4,5,

to 1,2,3, and 5.

226: Set Destination Radio Channel T Info

<226> 'ddd' 0 'x..x' set the radio channel number 'x..x' for the destination 'ddd'.

-<u>u</u> 225 005 2 "1-5,8"

and

#### Parameters:

 $-\dot{\mathbf{u}}$  'ddd' is the destination to set.

 $-\dot{\mathbf{u}}$  0 is sub-command that sets radio channel number 'x..x' for destination 'ddd'.

'<u>u</u>' 'x..x' is the radio channel number for destination 'ddd'. (defaults to 1)

#### 227: Set Destination Radio Freq T Info

<227> 'ddd' ['c' [x..x]] set destination frequency option 'c' for destination 'ddd'.

#### Parameters:

- $-\dot{\mathbf{u}}$  'ddd' is the destination to set.
- $-\overline{\underline{\underline{u}}}$  'c' is sub-command. (see chart below)
- $-\frac{1}{2}$  'x..x' is additional info required by the sub-command.

**Sub-command Chart** 

# Command Description

Function

<0>'xxx.yyyzzz'

Set RX frequency to MHz.KhzHzz

Use '.' or '\*' for decimal point. If no point entered, number is considered MHz.

<1>'xxx.yyyzzz'

Set RX frequency to MHz.KhzHzz

Use '.' or '\*' for decimal point. If no point entered, number is considered MHz.

Set bandwidth 'x'.

- 0 = 12.5Khz (narrow, use with FRS)
- 1 = 20Khz (medium)
- 2 = 25Khz (wide default)

Set power level 'x'.

- 0 = very low power
- 1 = low power
- 2 = medium power
- 3 = high power

Sub-audible signal settings.

- 0 = sub-audible signaling disabled. (no CTCSS, DCS, etc)
- 1 = enable CTCSS

#### 2 = enable DCS

<6>'x'

Sub-audible tx/rx settings to 'x'.

0 = use sub-audible signaling (if enabled) for RX only.

1 = use sub-audible signaling (if enabled) for TX only.

2 = use sub-audible signaling (if enabled) for RX and TX.

<7>'x..x'

Set CTCSS frequency to 'x..x'

Currently lets you set to any 1/10Hz frequency.

Example Freq: "103.5"

<8>'ccc'

Set DCS code 'ccc'. If code is less than 3 digits, leading zeros will be added.

229: Set Destination Info by Persist Format

<229>

set the radio channel number

'x..x' for the destination 'ddd'.

#### Parameters:

 $-\dot{\mathbf{u}}$  'ddd' is the destination to set.

<u>→</u> 0 is sub-command that sets radio channel number 'x..x' for destination 'ddd'.

 $\underline{\dot{}}$  'x..x' is the radio channel number for destination 'ddd'. (defaults to 1)

235: Set Destination With Send Page Macro T Info

<235> 'ddd'

[c'[x..x]]

sets up page macro info for

destination 'ddd'.

#### Parameters:

- $-\dot{\mathbf{u}}$  'ddd' is the destination to modify.
- $\underline{\dot{}}$  'c' is the sub-command to execute. (see table below)
- $-\frac{1}{2}$  'x..x' is additional data required by the sub-command.

#### **Sub-command Chart**

#### Command Description Function

< 0 >

Erases the page macro.

<1>'ccc' 'd..d'

Append command 'ccc' with arguments 'd..d' to the page macro.

## <2> 'ffff' 'dddd' [pppp]

Append macro to send tone with frequency 'ffff', duration 'dddd' milliseconds, and then pause for 'pppp' milliseconds. Pause defaults to zero if not specified.

# <7> [hhhh]

After sending each page, add a hangtime for 'hhhh' milliseconds to every place the page was send except the console.

<8>'set of ports' send the page hang to 'set of ports'. the destination number is ignored. see \_example-

of sub-command 9 for format.

<9>'set of ports' send the page to 'set of ports'. see example for format.

#### Examples:

- $-\underline{\underline{\dot{u}}}$  235 003 recall settings for destination 003.  $-\underline{\underline{\dot{u}}}$  235 003 0 erase the page macro for destination - erase the page macro for destination 003.

- <u>•ù</u> 235 003 1 030 00 01 02 append command 030 with args '00 01 02' to page macro.
- -<u>u</u> 235 003 2 0850 0500 0000 append the paging macro tone of 850Hz for 500ms followed by a

0ms pause.

 $-\dot{\mathbf{u}}$  235 003 9 1-3,5 - send the page to transmitters 1,2,3,5.

# Chapter 22: Windows(TM) Remote Control Interface GUI Commands

# Chapter 22: Commands Used By RCI (Windows Software)

The commands in this chapter would normally be used only by RCI, the Windows software used to manage the RLC-DSP404.

201: Set Up Network

This command sets the IP Address, netmask and gateway.

<201> w

Enable/Disable Network, Select Action

<201> w aaa.aaa.aaa.aaa Set IP/Netmask/Gateway

#### Parameters:

- 'w' is the action to perform.

'0' to disable network

'1' to enable network

- '2' to set IP address (requires address)
- '3' to set Netmask (requires address)
- '4' to set Gateway (requires address)
- '5' to disable DHCP
- '6' to enable DHCP
- 'aaa.aaa.aaa' is the IP Address if required.

#### Examples:

- -<u>u</u> 201 0 Disable Network
- -<u>u</u> 201 1 Enable Network
- 201 2 192.168.0.182 Set IP Address to "192.168.0.182"
- -<u>u</u> 201 3 255.255.255.0 Set Netmask to "255.255.255.0
- -<u>u</u> 201 4 192.168.0.1 Set Gateway to "192.168.0.1"
- <u>·</u><u>u</u> 201 5 Disable DHCP
- <u>u</u> 201 6 Enable DHCP

204: Set Radio Name

<204> recall the name of all ports.

<204> pp
"..."
set name of port
'pp' to "..."

#### Parameters:

- pp is the port number to recall or set
- "..." is the name to tie to the port number.

#### Examples:

- $-\dot{\mathbf{u}}$  204 Recall the name of all ports.
- <u>1</u> 204 02 HT/MTXc Set name for port 02 to "HT/MTXc"

208: Set Console PTT

Set PTT for port number 'pp' e

<208> pp 'e'
'tttt'
Set PTT for port
number 'pp' e and
start timer
'tttt'.

#### Parameters:

- pp is the port number to recall or set
- 'e' enables or disables ptt for port pp (0 = disable, 1 = enable)
- 'tttt' is the start time of the PTT timer.

#### Examples:

 $-\dot{\mathbf{u}}$  208 - Recall the name of all ports.

208 02 HT/MTXc - Set name for port 02 to "HT/MTXc"

214: Set Remote Logging

<214> 'r'

enable/disable remote logging.

#### Parameters:

- 'r' enables/disables remote logging for the connection this command was received from.
  - 0 Disable Remote Logging
  - 1 Enable Remote Logging

#### Example:

<u>·</u><u>u</u> 214 0 - Disable Remote Logging.

214 1 - Enable Remote Logging.

215: Update Remote Data

<215>

update remote data

#### Example:

<u>·</u><u>u</u> 215 - updates remote data.

#### 222: Streaming Audio Configuration

<222> pp [c [aaa] Applies sub-command 'c' and address 'aaa' to port 'pp'.

#### Parameters:

- 'pp' is the group to setup.
- 'c' is the sub-command to use.
  - 0 =disable streaming.
  - 1 = enable streaming.
  - 2 = set voip streaming address (requires variable 'aaa'; see below).
- 'aaa' is additional data needed for the sub-command, in this case, an address in format "aaa . aaa
  - . aaa . aaa"

#### Example:

222 02 0 - Disable streaming for port 'pp'.

222 02 1 - Enable streaming for port 'pp'.

222 02 2 192.168.0.33 - Set streaming address for port 'pp' to 192.168.0.33.

#### 223: Request Remote CRC

<223>

request remote crc.

#### Example:

 $-\dot{\mathbf{u}}$  223 - request remote crc.

#### 237: Set Radio Description

"d..d"
Sets description of port 'pp' to
"d..d"

#### Parameters:

- 'pp' is the port to accept description.
- $-\frac{1}{u}$  'd..d' is the port description to be applied to port 'pp'.

#### Example:

237 01 FIRSTPORT - set description of port 01 to "FIRSTPORT".

#### 238: Set Password Settings

<238>

Recall user permissions and passwords.

<238>1

<new user password>

<238> 2

<new admin password>

<238>3

<new user permission set>

<238>4

<new admin permission set>

#### Examples:

-<u>u</u> 238 - recall all permissions.

-<u>u</u> 238 1 "user password" - set user password to "user password".

-<u>u</u> 238 2 "admin password" - set admin password to "admin password"...

 $-\underline{\underline{\dot{u}}}$  238 3 0x001E - new user permission set 0x001E.

 $\frac{1}{2}$  238 4 0x7FE0 - new admin permission set 0x7FE0.

# 219: Set Group Name

<222>

recall the names of all groups.

```
<222> 'ggg'
_"..."
set name of group 'ggg' to "..."
```

# Parameters:

- 'ggg' is the group to setup.
- "..." is the group name to use.

# Example:

219 002 HT/MTXc - set the name of user group 2 to "HT/MTXc"

#### Appendix A: The Audio Routing Variable System

#### Explanation of the System

The key to controlling messages on the RLC-DSP404 is understanding what the audio routing variable

needs to be in each different situation. Fortunately, the RLC-DSP404 does most of the work for you.

When any command is executed by the user (either by DTMF or the serial port) or by the controller itself

(to send an ID, courtesy beep, etc.), the audio routing variable is automatically set to send the audio to

the logical place. You only need to concern yourself with this information if you wish to change the way

the audio is routed. The value of the audio routing variable in several situations is listed below:

-When a command is executed by DTMF, the audio routing variable is set to send all of the responses to the port that the DTMF input came from.

-Before a time out, time out clear, or any ID macro is executed, the audio routing variable is set to

send the message to the relevant port.

-Before a courtesy beep is sent, the audio routing variable is set to send the beeps to the right ports

(repeater ports connected to the receiver that just unkeyed).

You probably noticed in the list above that the audio routing variable automatically sends the audio-

where

\_you would normally want it to go. The only reason you need to know about it is because there a-few

situations where the controller can not know correct audio routing.

Suppose, for example, that you want the scheduler to cause the time to be read at the top of every hour.

How could the controller know that you want only ports 1 and 2 to hear the message? It can't. There

\_are-

two ways for you to specify where messages from the scheduler go. First, choose where you want

\_most-

of the messages caused by the scheduler to go. Tell the controller what ports those are with Command-

050. Now all of the messages caused by the scheduler will go out those ports. What if you

want one of-

the messages caused by the scheduler to go somewhere else? Simply make the scheduler call \_a user-

macro and program the first command in the macro to be Command 037 D or unkey and list the ports-

where you want the message to go to. This will change the audio routing variable for the rest of \_the-

commands in the macro. Command 037 can be used to change where the messages generated by any

macro will go. All commands executed after Command 037 in a macro until the end of that macro will

go to the ports specified with Command 037.

A similar situation exists for commands entered from the serial port. Since the controller sends serial

responses to the commands that you execute, you don't have to worry about voice responses if you don't

want to. There are times, however, when you want to hear the voice messages that are generated. You

can use Command 050 to specify which ports get the audio that is caused by the serial port. The RLC-DSP404 defaults to sending these messages out of port one, but you can send them to any ports

\_you-

want to, or to no ports at all.

Suppressing Command Responses in Macros:

There is one other time when you will often want to change the audio routing variable. Suppose that you

have programmed macro 600 to connect the main repeater on port 1 to port 2 (a link in this example).

Your macro would probably contain command "000 12". The voice response from that command would

be "1 connect 2 on". To replace that voice response with "link on" (word numbers 292 and 358), do the

following:

Insert Command 038 (suppress audio) as the first command in the macro:

Command 059 600 00 038 D or unkey or <Enter>

If you executed the macro at this point, it would be silent.

Insert the new voice message even before that:

#### Command 059 600 00 036 292 358 D or unkey or <Enter>

Now the macro will do the following:

- -Speak the voice message "link on" (command number 036)
- -Suppress the audio (set the audio routing variable to no ports, command number 038)
- -Connect ports 1 and 2 (throws the voice responses away)
- -Connect ports 1 and 4 (throws the voice responses away)

So a template for making macros that have a customized voice response could be:

make sure macro is empty

056 600 036 <word numbers>; send voice response

056 600 038; be quiet for rest of this macro

056 600 <do other stuff here>

The same process can be used to suppress or change the voice response from any macro. Any-commands

\_that are executed after Command 038 in a macro will be silent.

Appendix B: Voice Word Table

Romeo's words (words 000..543):

These words make up the main vocabulary of the controller. They are arranged with the numbers first.

then the alphabet, then alphabetically.

Prefixes and Suffixes (words 544..552):

These are really parts of words. They can be used in combination with other words to make some new

words. For example, you can use words 311 and 549 together to form the word "meetings".

Juliet's words (words 553..586):

These are used primarily for time and date. They are not intended to allow you to run the whole controller with the female voice.

Pause (word 587):

Word 587 is listed as "pause". It causes the voice to pause for a moment, such as between sentences. It

does not speak the word "pause". It can be used in combination with any of the other words.

Sound Effects (words 588..598):

Try them!!!

Junior's words (599..685):

Romeo quit the recording business, so we had to get Junior to record some other words for us. Some

words were recorded by both Romeo and Junior, so you might want to check both places in the word list.

It usually sounds best if you don't mix words from the two lists in one message, but sometimes that is the

only way to get the words you want.

Variable words (810..919):

Most of these words allow you to insert a message that is not always the same into a voice message, such

as the current time. If you want to include the time in one of your IDs, for example, you could just

include word 810 in the ID message. "At <the time>, this-is the XXXXX repeater" would be word

numbers 086, 810, 480, 475, 054, 054, 054, 054, 054, 411. These words make it easy to write custom

messages that read the time, date, I/O lines, etc.

#### Word List:

#### Romeo's Words

- 000 ZERO
- 001 ONE
- 002 TWO
- 003 THREE
- 004 FOUR
- 005 FIVE
- 006 SIX
- 007 SEVEN
- 008 EIGHT
- 009 NINE
- 010 TEN
- 011 ELEVEN
- 012 TWELVE
- 013 THIRTEEN
- 014 FOURTEEN
- 015 FIFTEEN
- 016 SIXTEEN
- 017 SEVENTEEN
- 018 EIGHTEEN
- 019 NINETEEN
- 020 TWENTY
- 021 THIRTY
- 022 FORTY
- 023 FIFTY
- 024 SIXTY
- 025 SEVENTY
- 026 EIGHTY
- 027 NINETY
- 028 HUNDRED
- 029 THOUSAND
- 030 MILLION
- 031 A
- 032 B
- 033 C

- 034 D
- 035 E
- 036 F
- 037 G
- 038 H
- 039 I
- 040 J
- 041 K
- 042 L
- 043 M
- 044 N
- 045 O
- 046 P
- 047 Q
- 048 R
- 049 S
- 050 T
- 051 U
- 052 V
- 053 W
- 054 X
- 055 Y
- 056 Z
- 057 ABORT
- 058 ABOUT
- 059 ABOVE
- 060 ACKNOWLEDGE
- 061 ACTION
- 062 ADJUST
- 063 ADVANCED
- 064 ADVISE
- 065 AERIAL
- 066 AFFIRMATIVE
- 067 AIR
- 068 AIRPORT
- 069 AKRON
- 070 ALERT
- 071 ALL
- 072 ALOFT
- 073 ALPHA
- 074 ALTERNATE
- 075 ALTITUDE
- 076 AMATEUR
- 077 AMPS
- 078 AND

- 079 ANSWER
- 080 APPROACH
- 081 APRIL
- 082 AREA
- 083 ARRIVAL
- 084 AS
- 085 ASSOCIATION
- 086 AT
- 087 AUGUST
- 088 AUTO
- 089 AUTOMATIC
- 090 AUTOPILOT
- 091 AUXILIARY
- 092 AVON
- 093 AVON MOUNTAIN
- 094 A.M.
- 095 BAND
- 096 BANK
- **097 BASE**
- 098 BATTERY
- 099 BELOW
- 100 BETWEEN
- 101 BLOWING
- 102 BLUE KNOB
- 103 BOARD
- 104 BOOST
- 105 BOZO
- 106 BRAKE
- 107 BRAVO
- 108 BREAK
- 109 BROKEN
- 110 BUSY
- 111 BUTTON
- 112 BY
- 113 CABIN
- 114 CALIBRATE
- 115 CALL
- 116 CALLING
- 117 CALM
- 118 CANCEL
- 119 CAUTION
- 120 CEILING
- 121 CELSIUS
- 122 CENTER
- 123 CHANGE

- 124 CHARLIE
- 125 CHECK
- 126 CIRCUIT
- 127 CLEAR
- 128 CLIMB
- 129 CLOCK
- 130 CLOSED
- 131 CLUB
- 132 CODE
- 133 COLUMBUS
- 134 COME
- 135 COMPLETE
- 136 COMPUTER
- 137 CONDITION
- 138 CONGRATULATIONS
- 139 CONNECT
- 140 CONNECTICUT
- 141 CONTACT
- 142 CONTROL
- 143 CONVERGING
- 144 COSHOCTON
- 145 COUNT
- 146 COURSE
- 147 CRANE
- 148 CROSSWIND
- 149 CURRENT
- 150 CUYAHOGA FALLS
- 151 CYCLE
- 152 DALLAS
- 153 DANGER
- **154 DATE**
- 155 DAY
- 156 DAYS
- 157 DAYTON
- 158 DECEMBER
- 159 DECREASE
- 160 DECREASING
- 161 DEGREES
- 162 DELTA
- 163 DEPARTURE
- 164 DEVICE
- 165 DIAL
- 166 DINNER
- 167 DIRECTION
- 168 DISPLAY

- 169 DIVIDED
- 170 DOOR
- 171 DOWN
- 172 DOWNWIND
- 173 DRIVE
- 174 DRIZZLE
- 175 DUST
- 176 EAST
- 177 ECHO
- 178 ELECTRICIAN
- 179 ELEVATION
- 180 EMERGENCY
- 181 ENGINE
- 182 ENTER
- 183 EQUAL
- 184 EQUALS
- 185 ERROR
- 186 ESTIMATED
- 187 EVACUATE
- 188 EVACUATION
- 189 EXIT
- 190 EXPECT
- 191 FAIL
- 192 FAILURE
- 193 FARAD
- 194 FAHRENHEIT
- 195 FARMINGTON
- 196 FAST
- 197 FEBRUARY
- 198 FEET
- 199 FILED
- 200 FINAL
- 201 FINDLAY
- 202 FIRE
- 203 FIRST
- 204 FLAPS
- 205 FLIGHT
- 206 FLOW
- 207 FOG
- 208 FOR
- 209 FOURTH
- 210 FOXTROT
- 211 FREEDOM
- 212 FREEZING
- 213 FREQUENCY

- 214 FRIDAY
- 215 FROM
- 216 FRONT
- 217 FULL
- 218 GALLONS
- 219 GATE
- 220 GAUGE
- 221 GEAR
- 222 GET
- 223 GLIDE
- 224 GO
- 225 GOLF
- 226 GOODBYE
- 227 GREEN
- 228 GREENWICH
- 229 GROUND
- 230 GURNEE
- 231 GUSTINGTO
- 232 HAIL
- 233 HALF
- 234 HAM
- 235 HAMFEST
- 236 HAMVENTION
- 237 HAVE
- 238 HAZARDOUS
- **239 HAZE**
- 240 HEAVY
- 241 HELLO
- 242 HELP
- 243 HENRY
- 244 HERTZ
- 245 HIGH
- 246 HOLD
- **247 HOME**
- 248 HOTEL
- 249 HOUR
- 250 HOURS
- 251 ICE
- 251 ICE
- 252 ICING
- 253 IDENTIFY
- 254 IGNITE
- 255 IGNITION
- 256 IMMEDIATELY
- 257 IN
- 258 INBOUND

- 259 INCH
- 260 INCREASE
- 261 INCREASING
- 262 INCREASINGTO
- 263 INDIA
- 264 INDICATED
- 265 INFLIGHT
- **266 INFORMATION**
- 267 INNER
- 268 INSPECTOR
- 269 INTRUDER
- 270 IS
- 271 IT
- 272 JANUARY
- 273 JULIET
- 274 JULY
- **275 JUNE**
- 276 KENTUCKY
- 277 KEY
- 278 KILO
- 279 KNOTS
- 280 LAND
- 281 LANDING
- 282 LATE
- 283 LAUNCH
- 284 LEAN
- **285 LEFT**
- 286 LEG
- 287 LESS THAN
- 288 LEVEL
- 289 LIGHT
- 290 LIMA
- 291 LINE
- 292 LINK
- 293 LIST
- 294 LITTON
- 295 LOCK
- 296 LONG
- 297 LOOK
- 298 LOW
- 299 LOWER
- 300 LUNCH
- 301 MACHINE
- 302 MAINTAIN
- 303 MANUAL

- 304 MARCH
- 305 MARKER
- 306 MAY
- 307 MAYDAY
- 308 ME
- **309 MEAN**
- 310 MEASURE
- 311 MEETING
- 312 MEGA
- 313 MESSAGES
- 314 METER
- 315 MICRO
- **316 MIKE**
- 317 MILES
- 318 MILL
- 319 MILLI
- 320 MINUS
- 321 MINUTES
- 322 MIST
- 323 MOBILE
- 324 MODERATE
- 325 MONDAY
- 326 MONTH
- 327 MORETHAN
- 328 MOTOR
- 329 MOUNT HAMILTON
- 330 MOUNT TAMALPAIS
- 331 MOVE
- 332 MOVING
- 333 MUCH
- 334 NEAR
- 335 NEGATIVE
- 336 NET
- 337 NEW
- 338 NEWINGTON
- 339 NEW HAVEN
- **340 NEXT**
- 341 NIGHT
- 342 NO
- 343 NORTH
- 344 NORTHEAST
- 345 NORTHWEST
- 346 NOT
- 347 NOVEMBER
- 348 NUMBER

- 349 OAKS
- 350 OBSCURED
- 351 O'CLOCK
- 352 OCTOBER
- 353 OF
- 354 OFF
- 355 OHIO
- 356 OHMS
- 357 OIL
- 358 ON
- 359 OPEN
- 360 OPERATION
- 361 OPERATOR
- 362 OSCAR
- 363 OTHER
- 364 OUT
- 365 OUTER
- 366 OVER
- 367 OVERCAST
- 368 PAPA
- 369 PARTIALLY
- **370 PASS**
- 371 PASSED
- 372 PATCH
- **373 PATH**
- 374 PELLETS
- 375 PER
- 376 PERCENT
- 377 PHONE
- 378 PICO
- 379 PLEASE
- 380 PLUS
- 381 POINT
- 382 POLICE
- 383 POSITION
- 384 POWER
- 385 PRACTICE
- 386 PRESS
- 387 PRESSURE
- 388 PRIVATE
- 389 PROBE
- 390 PROGRAMMING
- 391 PULL
- 392 PUSH
- 393 P.M.

- 394 QUEBEC
- 395 RADAR
- 396 RADIO
- **397 RAIN**
- 398 RAISE
- 399 RANGE
- 400 RATE
- 401 RATTLESNAKE

**MOUNTAIN** 

- 402 READY
- 403 REAR
- 404 RECEIVE
- 405 RED
- 406 RELEASE
- 407 REMARK
- 408 REMOTE
- 409 REPAIR
- 410 REPEAT
- 411 REPEATER
- 412 RICH
- 413 RICHMOND
- 414 RIG
- 415 RIGHT
- 416 ROAD
- 417 ROGER
- 418 ROMEO
- 419 ROUTE
- 420 RUNWAY
- 421 SAFE
- **422 SAINT PETERSBURG**
- **423 SAND**
- 424 SANTA CLARA
- 425 SAN LEANDRO
- 426 SATURDAY
- 427 SCATTERED
- 428 SECOND
- 429 SECONDS
- 430 SECURITY
- 431 SELECT
- 432 SEPTEMBER
- 433 SEQUENCE
- 434 SERVICE
- 435 SET
- 436 SEVERE
- **437 SEXY**

- 438 SHORT
- 439 SHOWERS
- **440 SHUT**
- 441 SIDE
- 442 SIERRA
- 443 SIGHT
- 444 SLEET
- 445 SLOPE
- **446 SLOW**
- 447 SMOKE
- **448 SNOW**
- 449 SOUTH
- 450 SOUTHEAST
- 451 SOUTHWEST
- 452 SPEED
- 453 SPRAY
- 454 SQUAWK
- 455 STALL
- 456 START
- 457 STOP
- 458 STORM
- 459 SUNDAY
- 460 SWITCH
- 461 SYSTEM
- 462 TANGO
- **463 TANK**
- 464 TARGET
- **465 TARPON SPRINGS**
- 466 TAXI
- **467 TEEN**
- 468 TELEPHONE
- **469 TEMPERATURE**
- 470 TERMINAL
- 471 TEST
- 472 THANK YOU
- **473 THAT**
- 474 THE (LONG E)
- 475 THE (SHORT E)
- 476 THE
- 477 THIN
- 478 THINLY
- 479 THIRD
- 480 THIS IS
- **481 THIS**
- 482 THUNDERSTORMS

- 483 THURSDAY
- 484 TIME
- 485 TIMER
- 486 TIMES
- 487 TO
- 488 TODAY
- 489 TOMORROW
- 490 TONIGHT
- 491 TOOL
- 492 TORNADO
- 493 TORONTO
- 494 TOUCHDOWN
- 495 TOWER
- 496 TRAFFIC
- 497 TRANSMIT
- 498 TRIM
- 499 TUESDAY
- 500 TURBULANCE
- 501 TURN
- 502 UNDER
- 503 UNIFORM
- **504 UNIT**
- 505 UNLIMITED
- 506 UNTIL
- 507 UP
- 508 USE (NOUN)
- 509 USE (VERB)
- 510 VALLEY
- 511 VALVE
- 512 VARIABLE
- 513 VERIFY
- 514 VICTOR
- 515 VISIBILITY
- 516 VOLTS
- 517 WAIT
- **518 WAKE**
- 519 WAKEUP
- 520 WARNING
- 521 WATCH
- 522 WATTS
- 523 WAY
- 524 WEATHER
- 525 WEDNESDAY
- 526 WELCOME
- 527 WEST

- 528 WEST HARTFORD
- 529 WHISKEY
- 530 WILL
- 531 WIND
- 532 WISKEY
- 533 WITH
- 534 WRONG
- 535 X-RAY
- 536 YANKEE
- 537 YELLOW
- 538 YESTERDAY
- 539 YOU
- 540 YOUR
- 541 ZED
- 542 ZONE
- 543 ZULU

## Prefixes and Suffixes

- 544 FIF-
- 545 THIR-
- 546 -ED
- 547 -ER
- 548 -ING
- 549 -S
- 550 -TEEN
- 551 -TH
- 552 -TY

### Juliet's Words

- 553 OH
- 554 ONE
- 555 TWO
- 556 THREE
- 557 FOUR
- 558 FIVE
- 559 SIX
- 560 SEVEN
- 561 EIGHT
- 562 NINE
- 563 TEN
- 564 ELEVEN
- 565 TWELVE
- 566 THIRTEEN

- 567 FOURTEEN
- 568 FIFTEEN
- 569 SIXTEEN
- 570 SEVENTEEN
- 571 EIGHTEEN
- 572 NINETEEN
- 573 TWENTY
- 574 THIRTY
- 575 FORTY
- 576 FIFTY
- 577 GOOD
- 578 MORNING
- 579 AFTERNOON
- 580 EVENING
- 581 THE
- 582 TIME
- 583 IS
- 584 A.M.
- 585 P.M.
- 586 O'CLOCK

#### Pause

## 587 PAUSE

### Sound Effects

- 588 LASER
- 589 WHISTLE
- 590 PHASER
- 591 TRAIN
- 592 EXP
- 593 CROWD
- 594 TIC
- 595 TOC
- 596 HIGH-LOW TONE
- 597 LOW-HIGH TONE
- 598 HIGH TONE

### Junior's Words

- 599 ALARM
- 600 AMATEUR
- 601 ANALOG
- 602 ARIZONA

- 603 AUTOPATCH
- 604 BACHELOR
- 605 BAD
- 606 BASE
- 607 BATTERY
- 608 BAY
- 609 BILLINGS
- 610 BOZEMAN
- 611 CANOE
- 612 CAPROCK
- 613 CENTRAL
- 614 CHARGING
- 615 CLOUDS
- 616 CLUB
- 617 COMMUNICATIONS
- 618 CONTROLLER
- 619 DIGITAL
- 620 EMPIRE
- 621 EVENT
- 622 FIELD
- 623 FLASH
- 624 FLOOD
- 625 FRIENDLY
- 626 GOLDEN
- 627 GREYCLIFF
- 628 HAM
- 629 HAMFEST
- 630 HARRISON
- 631 HOLLEY
- 632 HOME
- 633 INFORMATION
- 634 INLAND
- 635 INPUT
- 636 INSIDE
- 637 KOOTENAI
- 638 LINK
- 639 LITTLEROCK
- 640 MEDIUM
- 641 MEETING
- 642 MICA
- 643 MONITOR
- 644 MOUNTAIN
- 645 NET
- 646 OBED
- 647 OREGON

- 648 OUTSIDE
- 649 PEAK
- 650 POUND
- 651 PUMP
- 652 PYRAMID
- 653 RACES
- 654 RADIO
- 655 RATTLESNAKE
- 656 REMOTE
- 657 REPEATER
- 658 RIDGE
- 659 SANDRA
- 660 SCAN
- 661 SIDNEY
- 662 SKYWARN
- 663 SOCIETY
- 664 SPOKANE
- 665 STAR
- 666 STATE
- 667 SUNDANCE
- 668 SYSTEM
- 669 TACOMA
- **670 THIS**
- 671 TIGER
- 672 TODAY
- 673 TOMORROW
- 674 TONIGHT
- 675 VALUE
- 676 VOLTAGE
- 677 WASHINGTON
- 678 WATCH
- 679 WATER
- 680 WELCOME
- 681 WITH
- 682 YAKIMA
- 683 YELLOWHEAD
- 684 YELLOWKNIFE
- 685 ZED

### Internal Variable Words

(don't use these)

- 800 UNUSED
- **801 START POLITE**
- 802 END POLITE
- 803 END POLITE DO

## CMD 804 DO DELAYED DIAL 805 START DVR TIMER

User Variable Words

- 810 TIME
- 811 HOUR (12 hr)
- 812 HOUR (24 hr)
- 813 MINUTE OF HOUR
- 814 AM/PM
- 815 DATE
- 816 MONTH OF YEAR
- 817 DAY OF MONTH
- 818 YEAR
- 819 DAY OF WEEK
- 830 TIME (FEMALE)
- 831 HOUR,F (12 hr)
- 832 HOUR,F (24 hr)
- 833 MINUTE,F
- 834 AM/PM (FEMALE)
- 835 MRN/AFT/EVE, F

## Special Word Pairs:

Most of the following words need to be followed by another word number that specifies which one to do: which analog line to read, which command to execute, which time zone to use, etc. For example, to read analog 5 as an S-meter, you would want to speak word 861 followed by word 005.

840 xxx - read analog 001..016 841 xxx - analog 001..016 high value 842 xxx - analog 001..016 high time 843 xxx - analog 001..016 low value

```
844 xxx - analog 001..016
   low time
  848 xxx - read analog 1..16
   as S-Meter. To
— obtain
  a current
  reading,
__ must use an event
   event trigger to clear the
   the high value each time
   time the COR goes
— active.
_ For example
<del>--- "157 000"</del>
   500"
 followed by
  "053 500
= 038" and
  "056 500
= 160 15" will
 _ reset the
— high value
  for analog
\frac{1}{2} line 1
whenever the <u>COR</u>
  <del>COR</del> for port 1 goes
— active.
  849 xxx - read analog line as
   a Direction: N, NE,
   E, SE, S, etc.
  850 xxx - execute command
   xxx (up to command
   900 or so, may not go
   all the way to 999).
   Will not happen until
   this word is actually
   spoken.
  851 xxx - speak 24 hour time
   in male voice adding
   xxx hours. Can use to
   speak the time for any
   time zone.
  852 xxx - same as above in
   female voice
  853 xxx - callsign of user xxx
```

(as set with cmd 191) 854 xxx - callsign of user logged onto port xxx 855 xxx - callsign of user being paged with command 132

# Appendix C: CW Code Table

CW

XX

CW

XX

CW

XX

CW

XX

CW

XX

0

00

A

10

K

20

U

30

SPACE

40

1

01

В

11

L

21

V 31

. PAUSE

41

2 02

. C 12

. M 22

. W 32

3 03

. D 13

. N 23

. X 33 .

43

4 04

. E 14

O 24

. Y 34

5 05

. F 15 . P 25

. Z 35

6 06

. G 16 . Q 26

. / 36

7 07

H 17

. R 27

. 0 37

8 08

. I 18

. S 28

. ? 38

9 09

. J 19

. T 29

. AR 39

Note: Sending the "CW" character 42, 43 or 44 actually plays one of the internal DVR messages.

## Appendix D: Reset and Initialization

The terms "reset" and "initialization" refer to totally different things on the RLC-DSP404. The-controller

- \_is "reset" when any of the following things happen:
- -the power is turned off and back on
- -the reset button on the motherboard is pressed and released
- -Command 035 is executed

Resetting the controller does not cause you to lose any of your programming. It does restart all of the

timers and a lot of other internal variables. If the controller is not doing what you think it should, try

resetting it and see if things straighten out.

"Initialization" (sometimes called "re-initialization") resets all of the controller's internal settings back to

the factory defaults. It does cause you to lose all of your programming. You will almost always have to

initialize the controller when you install a new version of software, but rarely otherwise. If you are-

trying

\_to learn to program the RLC-DSP404 and you mess things up, you can use this to put everything

#### back

the way it is supposed to be. Initialization does not hurt the RLC-DSP404 in any way - there is

EEPROM or anything to wear out. To reinitialize the RLC-DSP404, follow one of the two methods

below:

Method #1: Press and hold the INIT button on the motherboard. Turn on the power. Wait for about 3 seconds (or longer). Release the INIT button.

Method #2: Turn the power on. Press and hold the INIT button. Press and release the RESET button. Wait at least 3 seconds. Release the INIT button.

If you are successful you will hear the message "I-N-I-T" out of the transmitter that is hooked to port 1

and see the message "All settings have been reset to factory defaults" on the serial terminal.

—<u>Appendix</u> E: Hardware Documentation

## Appendix F: Programming with the Serial PortSetting Up the Controller with a Computer

<u>Traditionally, repeater controllers have been set up by entering commands using the DTMF pad on a</u>

<u>radio</u>. Most of the commands in this manual can be entered with only the 12 standard DTMF digits (0-9,

\* and #). If the radio being used has a 16-digit DTMF pad (with digits A-D), a few extra features are

<u>available (such as using D like an ENTER key, to force a command to execute without unkeying).</u>

While the ability to enter commands using a DTMF pad is convenient when you aren't at the same

<u>location</u> as the controller, it can be cumbersome to enter a lot of codes.

The RLC-DSP404 also makes it possible to enter commands using a computer by connecting it to the

<u>controller using a serial cable or Ethernet network (crossover cable, LAN or over the Internet).</u>

<u>You will</u>

need to run some terminal software on the PC to make it communicate over the serial cable or network.

<u>See the web site http://link-comm.com/wiki/index.php?title=Programming\_Using\_a\_Computer</u> for more

<u>information about the options (HyperTerminal, which is included with Windows 95 through XP but not</u>

<u>in Vista is commonly used). That website also has information about software that available for some</u>

<u>controllers to provide a point-and-click rather than command line interface.</u> For most people, it <u>is easiest</u>

to set up the RLC-DSP404 using the RCI software described in Chapter 1. Some advanced features are

<u>not yet supported in that software, entering commands as described in this chapter is a good way to fix in</u>

those gaps. Note that the terminal window in RCI (open it from the Communications window) can be

<u>used both to enter individual commands and to upload text files containing list of commands as described below.</u> Alternately, standard serial communications or telnet client software can be <u>used to</u>

access the command line interface. When you get a "root:~>" prompt, type "client" (without the quotes)

and press enter to get a "DSP4>" prompt before trying to enter the commands from this manual. If you

wish to return to the root:~> prompt (where you can enter Linux shell commands, press CTRL-X (hold

the CTRL key down while and pressing the X key).

Entering commands from the serial portcomputer using terminal software works almost exactly the same way as-

with DTMF tones from a

radio. The characters you enter on the keyboard are treated the same way asthe digits on your radio

\_keypad. Of course you can enter digits on the keyboard that you can not enterfrom a keypad, which

gives you a little additional flexibility. Some of the things you can do from the-keyboard that you can not

\_do from a DTMF pad are:

-Back up. If you type a digit you did not mean to type, simply press the backspace key and erase it.

-Press the Enter key. This tells the controller to try to execute whatever you have typed so far. This is exactly the same as unkeying your radio to force a command to execute. When you have

entered a command you can either enter an '!' or press <Enter> to make it execute.

-Store a bunch of commands in a file on your computer that you can upload without typing them again. See the section on using a serial upload file later in this appendix.

Example: I want to execute Command 009 to see which ports are connected together:

Over the air:

<Key radio> 009 <Unkey or press "D">

From the serial port:

<ENTER>

You will see the serial port prompt "DTMF>". This indicates that the characters you enter are being treated just as if they were entered by DTMF from a radio port

009 <Enter or press "D">

Voice responses to commands entered serially:

Normally, when you enter commands from the serial port, the voice responses go out port one. Since

you also get responses on your computer screen, they really aren't needed in most cases, and can get

annoying if you are doing a lot of programming. You can control whether or not you get voice responses

to the commands you enter serially with Command 050. Using that command you can tell the RLC-DSP404 to send the voice responses out any port (or more than one), or nowhere at all.

## **To**The

command needed to keep it

<u>from sending voice responses depends on which "client" connection the command was entered from. In most cases it will be client connection #1, but you can check the message you get when you first start the client to make sure. Assuming connection #1, enter "050 134 0"-</u>

and press enter (you can also make that the first line of \_your upload files). To turn them back on, enter"050 134 1" and press enter ENTER (see command 050 for more \_information).

If you are uploading a large file and you have the voice enabled, the voice might not be able to keep up

with the commands that are being uploaded. If this happens and the voice gets 300 words or so behind,-

it

will just skip those words so it is caught up and again try to keep up (which is harmless but prevents

<u>you from hearing all of the responses</u>). You either have to upload very slowly or turn the voice off-

during uploads to avoid this. <u>In most cases, there is no reason to leave the voice on, as the commands</u>

print responses to the terminal program so you can tell how it is progressing and see any error messages.

## Using a serial upload file:

A very convenient way to set up your controller if you have a computer is to type all of the commands

that you use to set up your controller in a file using a word processor. Save the file in ASCII (plain text)

format. Load your communications program and make sure you are talking to the RLC-DSP404 by

hitting return and checking for the "DTMF>" prompt. Now do an ASCII upload of the file that you

saved all of your commands in (the controller won't know that you are doing an automatic upload, it will

just think you are typing fast). Test the stuff you uploaded and if you want to make a change, go back to

your editor and change it in the file. Now upload it again. By setting up your controller this way, you

have a permanent record of everything you have done. If something ever gets messed up on the controller, all you have to do is initialize it (see Appendix D) and re-upload your file. Also, when you get

a new version of software (which will almost always require you to reinitialize), you will

probably only

have to make minor changes to your file to make it work with the new software version. This will

definitely save you time in the long run. There is no quick and easy way to download all of the information in the controller to a file, so it is best to create the file as you go. (QuickStart, available

free from our web site, can download most of the settings, but it takes several hours. It works much

better if you use it from the very beginning and keep a file of your settings on your computer so you don't

need to download them from the controller later.) An example willilustrate the idea:

Using your favorite editor, enter the following (including the comments):

```
; this line is a comment - put a description of the file here

050 13 0; —; Turn off the voice responses to serial commands

007 01 1; —; Turn DTMF muting on for port +01

050 01 313 1; — Turn on voice responses to port 1

036 01 35 135; —; Speak the word "Complete"
```

Save the file as "RLC-DSP404.txt" (without the quotes) or some other name of your choice. Load your communications program.

Hit <Enter> and watch for the "DTMF>" prompt from the RLC-DSP404. If you do not get it, check your cable and setup in your communications software.

You may want to tell your communications program to open a log file at this point.

It will come in handy for checking if any of the commands caused errors.

Start an ASCII upload of your file.

Wait until it finishes.

Close the log file if you opened one.

Try out your new settings. 009 will check the crosspoint and 007 will check the DTMF muting.

Go back to your editor, make the required changes, and repeat the cycle. You can find more information

about using upload files and programming examples on the support web site, <a href="http://link-comm.com/wiki/index.php?title=Programming\_Using\_a\_Computer">http://link-comm.com/wiki/index.php?title=Programming\_Using\_a\_Computer</a>

Note about spaces in serial commands:

The controller totally ignores spaces in commands you enter from the serial port. Spaces are shown in

the manual to make it easier to see the separate groups of characters; you may want to do this in your

upload files as well. Spaces are never required, but you can put them wherever you want in your serial

commands to make them easier to read.

Note about comments in serial upload files:

You can put as many comments in your upload files as you want. Anything following a ';' will be considered a comment and will be totally ignored by the controller. If you want a whole line to be a

comment, just start it with a semicolon like this:

; this line is a comment.

If you want to put a comment after a command (on the same line), do it like this:

N026<u>007 01 1</u>; <u>Turn DTMF muting on this is a comment - this command recalls the time.for port 01</u>

It is highly recommended that you comment your upload files throughly. You will thank yourself when

you go back months later and try to figure out what you were trying to do.

Note about capital letters:

By default the RLC-DSP404 converts everything you type to a capital letter. This is because DTMF

characters are always treated as capital letters and it avoids confusion. However, there may be a time

when you would like to enter lower case letters, such as when you send serial messages with Command

032. At those times you can turn off the conversion to all capital letters with Command 060.

Note about upload speeds:

If you upload a file with more than a dozen commands or so in it, you may find that the responses from

the RLC-DSP404 get way behind, or even get lost with the message "Serial Output Queue just overflowed - it now looks empty". This is caused by the RLC-DSP404 trying to send back all of the

descriptive responses to the commands and not being able to send the responses as fast as it gets new

commands. Eventually it runs out of buffer space and is forced to throw some of the responses away (it

does not support software flow control yet). This does not affect the commands that are being sent to

the-

RLC-DSP404 in any way - just the responses that you see on the screen. If you do not care about the

responses, just let them get thrown away and forget it. There is no file size limit, just a limit on how fast

you can send it to the controller. If you need to know what the responses are, you need to insert pauses

while your communications program sends the commands to the RLC-DSP404. Slowing the baud rate

down will not help significantly, as that will slow down the responses just as much as the commands you

are sending. There are several ways to do this:

Tell the comm program to wait until it sees a new "DTMF>" prompt before sending the next line.

To do this with the Windows 3.1 terminal program, go to the "Settings" menu, select "Text Transfers", then select flow control of "Line at a Time" and set a "Wait for Prompt String" of "DTMF>". Other comm programs will only let you set a single pacing character. You can try >'

(the last character in the "DTMF>" prompt). Waiting for a new prompt, or at least the last character of it, is the best method because it makes the comm program wait exactly as long as needed for the controller to finish the previous command.

Thange the ASCII transfer settings on your communications software to insert a 1.5 second delay

after each line (longer for slow baud rates, shorter for fast baud rates). This will give the RLC-DSP404 time to send the responses back without overflowing the queue. You may have

experiment to get enough delay to avoid overflowing without having to wait all day for the upload

– to finish.

ightharmore If you can't figure out how to do either of the above methods, you can try putting tilde characters

at the end of each line in you upload file, like this:

The tilde tells most comm programs to pause for a bit, usually « to 1 second.

Serial responses to commands entered from a radio:

Normally the commands that are entered from a radio do not cause anything to be sent out of the serial

port; that is they are "suppressed". This lets you program the controller from the serial port while

people

are entering DTMF commands without them causing confusing messages to show up on the serial-

screen.

If you want to see the commands that are being entered from the radios, you can turn-

"suppressed" serial

off with command 060.

Very Long Serial Commands:

This section only applies to very long serial commands. If a line fits on the screen (80 characters wide),-

it

\_isn't long enough to worry about. But there may be times when you make a very long command,

maybe

\_programming a voice message:

```
; make macro 600 speak one two three four five six seven eight 600 036 001 002 003 004 005 006 007 008; comment
```

There is an internal line length limit; you will get an error message if you exceed it. If you do exceed it,

check the following things: make sure there is a ';' right after the command, even if the comment is way

off to the right. It is ok if the comment exceeds the line length limit - that won't cause an error, it iust

won't let you backspace once you have exceeded the limit.

If you have checked to make sure the ';' comes right after the end of the command and you still get a

message that the command is too long and overflows the buffer, remove some of the spaces in that

command. If even that isn't enough to get it under the length limit, you will probably have to break it up

into separate commands, possibly speaking the first half and last half of the message separately.

## QuickStart Software For WindowsTM

The RLC-DSP404 can be configured with a program called RLC-QuickStart that runs under Microsoft

WindowsTM. RLC-QuickStart allows a user to program some of the basic functionality of the controller

through a graphical "point and click" interface. The software is meant to help with getting a new

controller set up and running quickly as well as making some of the basic everyday changes a little easier

to handle. Some of the more common uses of RLC-QuickStart include programming IDs, timers, macros, and port connections. Even if you don't use QuickStart, you can (and should if possible) use a

computer to set up the controller. See Appendix F for more information.

#### **Installation:**

Installation of the RLC-QuickStart software requires a CD-ROM drive and a hard drive on your computer. RLC-QuickStart is available for download from

http://www.link-comm.com/quickstart.html

or on the CD included with your controller.

If you have downloaded RLC-QuickStart from the web site, skip steps 1 through 3.

- 1) Insert the CD into the CD-ROM drive.
- 2) Click <Start><Run>.
- 3) Click <Browse> and then navigate to the CD-ROM drive.
- 4) Double-click on "install\_rlcqs.exe" and follow the rest of the instructions provided by the installer

<del>program.</del>

### Operation:

Click on the 'RLC-QuickStart' icon and the software will begin to run. Once the software is running you

can select an existing file to work on, or click cancel to continue to the main program. If you have gotten

to the main program screen by clicking cancel instead of selecting a file to edit, you must now select an

option from the File menu. You may choose to create a New Blank file, open an Existing File, or Import

your controller's current settings into a new file.

Once you have made your desired changes, save the file. You can either quit now or use the terminal

window to upload the software to a controller via. modem software or a direct connection (with a serial

cable connected between your computer and the controller).

#### **Limitations:**

Not all functions of the controller can be edited graphically with this software. If there are functions you

wish to program that cannot be edited graphically, you may use the text editor in the Terminal window of

RLC-QuickStart to enter the commands using a text file. For more help on this topic, refer to Appendix

<del>F.</del>

WindowsTM is a registered trademark of Microsoft Corporation.

# Appendix G: ASCII Chart

This chart may be helpful when programming serial messages with Command 034. Not all of the codes

are included because not all of them are universally used and some don't print well.

032

033!

034 "

035#

036\$

037 %

038 &

039 '

040 (

041)

041 )

043 +

044,

045 -

0.16

046 . 047 /

048 0

049 1

050 2

0513

052 4

053 5

054 6

055 7

0568

0579

058:

059;

060 <

061 =

062 >

063 ?

064 @

065 A

066 B

067 C

068 D

069 E

070 F

071 G

072 H

073 I

074 J

075 K

076 L

077 M

078 N

079 O

080 P

081 Q

082 R

083 S

084 T

085 U

086 V

087 W

088 X 089 Y

090 Z

091 [ 092 \

093]

094 ^

095 -

097 a

098 b 099 c

100 d

101 e

102 f

103 g

104 h

105 I

106 j

107 k

1081

109 m

110 n

111 o

112 p

113 q

114 r

115 s

116 t

117 u

118 v

119 w

120 x

121 y

122 z

123 {

124 |

125 }

126 ~

128€

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131 f

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133 ...

134 †

135 ‡ 136 ^

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137 700 138 Š

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142 Ž

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144 • 145 '

146,

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165¥

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168 ..

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171 «

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173 -

174®

175 -

176°

 $177 \pm$ 

178 <sup>2</sup>

179 <sup>3</sup>

180′

181 μ

182 ¶

183 ·

184,

185 <sup>1</sup>

186°

187 »

188 1/4

189 ½

190 3/4

191 ¿ 192 À

193 Á

194 Â

195 Ã

196 Ä

197 Å

198Æ

199 Ç

200 È

201 É

 $202\; \hat{E}$ 

203 Ë

204 Ì

205 Í

 $206\ \hat{I}$ 

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208 Đ

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216 Ø

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222 Þ

223 В

224 à

225 á

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228 ä

229 å

230 æ

231 ç

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235 ë

236 ì

237 í

238 î

239 ï

240 ð

241 ñ

242 ò

243 ó

244 ô

245 õ

246 ö

247 ÷

248 💆

249 <del>ù</del>

250 <del>ú</del>

251 û

252 ü

253 ý 254 þ 255

#### Appendix H: Using the LM335 Temperature Sensor

The RLC-DSP404 supports the National Semiconductor LM335Z temperature sensor. The sensor

converts temperature into voltage. This voltage is read by the controllers ADC (Analog-Digital Convertor) which allows the controller to read a voltage. When using the LM335Z sensor, the sensor

needs to be powered in order for the temperature to be read. The sensors will be powered when the

powering dip switch for the appropriate input is switched to ON. Locate To power the sensor, turn on the pullup

resistor by turning on the corresponding DIP switch (switch 1 for analog input 1, switch 7 for analog

<u>input 7, etc.</u>). For analog inputs 1-7, the <u>DIP switch can be found</u> on the DSP404's main board (;\_for analog inputs 1-8) or on the daughter board (for

analog inputs 9-16) an 8 position DIP switch. This

switch is the largest DIP switch on the board. Switch the switch position to ON to power the external

LM335 temperature sensor.

on the expansion board (if installed). See Command 102 in Chapter 9 for information about how to tell the controller to interpret the voltage as a temperature and to calibrate the

reading. An example can be found online at

http://link-comm.com/wiki/index.php?title=RLC-DSP404\_FAQs#Q: How\_do\_I\_read\_temperature\_us

ing a LM335 sensor.3F

## LM335Z Temperature Probe Connections Diagram

### Troubleshooting:

- -The voltage across the sensor should be between 2.7 and 3.0 V in most cases (Temperature Celsius = (voltage\*100)-273).
- -If the voltage across the sensor measures about 0.6V, the temperature sensor may be hooked up backwards (OUT switched with GND).
- -If the voltage across the sensor is near 0V, make sure that the sensor is powered (as described at

the top of this page) and that the wires aren't shorted out.

-If the voltage across the sensor is near 5V, there is either a bad connection to the sensor, the wrong pins are being used, or the sensor is blown out (possibly by nearby lightning).

# Appendix I: Software Problem and Request Form

Link Communications Inc. Num email: feedback@link-com		406 - 245 - 5002 (Voice)
Name		
Serial		
#		
Phone ##_	Fax	
Request:		

Attention Allan or Steve	Number of Pages:

# Software Problem and Request Form

Link Communications Inc. Num email: feedback@link-com		406 - 245 - 5002 (Voice)
Name		
Serial		
#		
Phone ##_	Fax	
Request:		

Attention Allan or Steve	Number of Pages:

## Appendix K: Internet Linking (VoIP)

The RLC-DSP404 can be easily interfaced with any of several Internet linking (VoIP) systems (IRLP,

EchoLink, iLink, etc.). Linking through the Internet is very similar to using RF links, with the Internet

link interfacing in the same way and serving the same purpose as RF link radios.

VoIP interfaces (often a computer with a sound card and possibly some specialized hardware) are

#### usually

\_connected in one of two ways:

- -Method A: Connected to the link port of a repeater controller.
- -Method B: Connected to a radio tuned to the frequency of a repeater (like a remote base).

#### Method A:

If using method A, the controller's link port should be configured as follows:

- -Zero hang time (see the hang timers and mini-hang timers in Chapter 4)
- -No courtesy beeps on link transmitter (that is the default, see command 041)
- -No ID messages on link transmitter (that is the default, see command 085)

To get the controller to communicate with the VoIP interface, the controller needs to be configured so

the port that the users are talking on and listening to (usually a repeater port) is "connected" (see eChapter

2) to the link port that is wired to the VoIP interface. The controller will then pass audio back and forth

from the Internet link to the repeater. The only audio passed from the controller to the Internet link will

be the audio received on the repeater (no courtesy beeps or IDs), even when the controller sends a CW

ID out the repeater while someone is talking.

Note that when wiring the controller's link port to the VoIP interface, the labels for the connections may

be confusing. VoIP interfaces are generally designed for interfacing to a radio rather than to a controller.

Because of that, its connections may be labeled to match the point in the radio to which they would

normally be connected rather than according to their function on the VoIP interface. In other words,

"audio in" may refer to the VoIP interface's audio output, which would normally be connected to the

radio's audio input. Such an audio output from the VoIP interface would need to be connected to

the

controller's audio input (pin 5 on the DB-9). The COR (sometimes called CAS) and PTT connections

may be similarly confusing. Just make sure that outputs from the controller are connected to inputs on

the VoIP interface and vice versa, and you should be OK.

#### Method B:

If using method B, care should be taken to keep the repeater's courtesy beeps and ID from being sent

down the Internet link, and to keep the repeater's hang time from holding up the Internet link. One way

to accomplish this is to encode PL (CTCSS) on the repeater transmitter only when someone is actually

talking (not during the courtesy beep, hang time and IDs), then to set the radio connected to the Internet

linking interface so it requires PL (tone squelch mode). That could be done for a simple repeater by

switching the encoded PL based with the repeater receiver's COR signal. In a more complex system,

where the audio going out the repeater transmitter could come from other sources (other repeater receivers running on the same controller, other links, remote bases, or an autopatch), one of the controller's open collector output lines should be used to switch the encoded PL. The controller can then

be configured to turn that output line on and off at the appropriate times as follows:

```
; program macro 600 to turn output line on (encoded PL on) 055 600; ;make sure macro is empty 056 600 038; ; ;be quiet for rest of this macro 056 600 093 1; ;; turn on output line 1

; program macro 601 to turn output line off (encoded PL off) 055 601; ;make sure macro is empty 056 601 038; ;; be quiet for rest of this macro 056 601 094 1; ; ;turn off output line 1

; set event trigger to automatically execute macro 600 (so it will; send PL) when a connected receiver is active 157 1873 600; ; set event trigger to automatically execute macro 601 (so it will; stop sending PL) when all connected receivers are inactive 157 2185 601;
```

### Controlling:

To control a Internet linking interface using DTMF digits (to connect it to other nodes, etc.), you will

need to provide a way to either pass user-entered DTMF digits through the controller to the interface or

to make the controller generate DTMF digits on command. There are a variety of ways to do this.

-Option #1: Pass all user-entered DTMF digits through to the Internet linking interface. If interface method B (described above) is used, this means turning off the DTMF mute feature (see

command 007) for the repeater transmitter, which will allow anyone listening to the repeater to hear the digits entered. If using interface method A (also described above), the DTMF mute needs to be turned off only for the link transmitter; DTMF can still be muted on the repeater transmitter. In either case, the Internet linking interface will "hear" all digits entered by users.

With this method, the controller may send error messages in response to the DTMF strings that are entered, or worse yet, execute a command you did not intend for it to. To get rid of error messages, you can just delete the macro that generates them. For example, "Error 301553" is generated by macro 301553; you can delete it by entering "055 301553". The following methods don't

have this problem.

-Option #2: Pass user-entered DTMF digits only if they bypass the DTMF mute. To do this, use

command 007 to turn on the DTMF mute bypass for the port that is connected to the Internet linking interface. To send DTMF digits to that interface, key up, press 'D' (the force execution digit, can be changed with command 078), then the digits you want to send. The controller will ignore those digits and will not send error messages in response to them.

If you do not have an audio delay module on the receiver that the DTMF digits are entered from,

the first 40mS or so of the 'D' will be passed out the transmitter before the mute kicks in. If the DTMF decoder on the Internet linking interface is fast enough, it may decode that 'D' and get confused (that isn't a problem with IRLP, as it always ignores the DTMF digit 'D').

-Option #3: Use controller macros to generate DTMF digits. If the number of DTMF commands

you want to send to the Internet linking interface is reasonably small, you can make a controller macro for each one. The macro can be renamed (see command 010), send a voice message to confirm what it is doing, and send DTMF. For example:

```
010 600 ABC : name macro ABC make sure macro is empty
```

```
056 600 036 139 003 ; ; speak "Connect three" ; send DTMF "0003" to TX 3
```

Alternately, the last two line of the above macro could be replaced with the following lines. This

method allows DTMF pauses and the force-execution digit (normally 'D') to be sent (see command 069 for its limitations).

```
056 600 037 3 ; ;route following DTMF to TX 3 056 600 031 00 00 00 03 ;send DTMF "0003"
```

-Option #4: Make a command to regenerate whatever DTMF digits the users enter.

```
010 600 ABC ; ;name macro "ABC"

067 600 01 1 ; ;allow macro to take data (see command 067)

055 600 ; ;make sure macro is empty

056 600 069 3 ; ;user-entered data will be appended here
```

Now entering "ABC 026" will cause DTMF "026" to be generated out transmitter 3. In other words, "ABC" means "send the following DTMF digits to transmitter 3".

## Appendix L: Use '0\*' For the Current Port

Commands 003, 004, 008, 037, 061, 068, 130 and 131 allow '0\*' to be entered as a port number when

the command is entered from one of the radio ports. The '0\*' gets replaced with a number that corresponds with the port number that entered the DTMF digits. For example, if "008 0\*2" is entered

from port 01, the controller will execute it as if "008 012" had been entered. Entering "003 0\*" from

port 02 will query which transmitters are connected to receiver 02, just as "003 02" would. If a '0\*' is-

used as a port

\_number from the serial port or a macro that is executed by anything but a DTMF-command (as part of an

ID, event trigger, scheduler, etc), it will not be replaced with a port number and-will usually cause an error.